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Filtering of Cardiac and Power Line in Surface Respiratory EMG Signal

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Biomedical EMG signal is contaminated by many noise sources as the electrocardiogram ECG artefact and the power line interference PLI artefact. It's difficult to filter these noises from EMG signal, and errors resulting from filtering can atlter the signal. In order to solve this problem, we present in this paper an adaptative interference filter with a variable step size parameter for the removal of the two principal noises (ECGand PLI) which disturb the surface electromyography signal (Diaphragm), the "Adaptive Interference Canceller" (AIC) for the PLI and the "Cascade Adaptive Canceller" (CAC) for the ECG. The algorithms proposed require a reference signal that is correlated with the noise contaminating the signal. The noise references are then extracted : first with a noise reference mathematically constructed using two different cosine functions; 50Hz (the fundamental) function and 150Hz (the first harmonic) function for the power line interference and second with a matching pursuit technique combined to an LMS structure for the ECG artefact estimation. The proposed procedures require only one channel to both estimating the adaptive filter input reference and the EMG signal. The proposed techniques of filtering are evaluated using both computer simulations and real EMG records, and its efficiency in interference cancellation is compared to already conducted research.

Keywords: Surface EMG, adaptive noise canceller, matching pursuit, ECG, power line interference, diaphragm EMG.

1 Introduction

The Diaphragm electromyographic signal conveys important information about the respiratory control mechanism [16] especially in the case of long-time monitoring. The ma-

jor problem with EMG signal recorded by surface electrode is its bad signal to noise ratio. However the principal artifacts which often disturb EMG signal are the electrode noise [12], the electrode motion artefact, the ECG artifact [4, 8, 26], and the electromagnetic interference 50Hz and its harmonic 150Hz [6].

The spectra of ECG artifact and EMG signal overlap in some frequency range moreover the variable amplitude ratio between them caused by the non-stationary EMG signal nature made the ECG, very difficult to eliminate [9]. The second important artifact that contaminates the EMG signal concerned the power line interference which can be much larger than the EMG its self. This noise arises from the power lines and the electric equipment. The frequency of these fields is at the frequency of the alternative current power supply (50Hz) and its harmonics. In order to reduce the magnitude of this artefact, first of all, we tried to realize a good preparation of the body skin indeed the skin is abraded and cleaned with abrasive cream and alcohol. Second to reduce the effect of the cable length the signals are differentially amplified [14, 23] twice. However, these changes may not always be sufficient in case of a deep contaminated surrounding and weak muscular activities and it will be necessary to reduce the interference using other means. The use of analogical or digital filters of fixed band centered on [20 - 40Hz] for the ECG signal (maximum energy of ECG) and on 50Hz and on 150Hz for the power line interference PLI fails. Indeed these filters allowed the reduction of the noises they also eliminate some useful signal components. A solution to this problem is proposed by applying, the LMS adaptive algorithm [27, 28] but without introducing supplementary electrodes to the noise reference in order to minimize the presence of electronics.

2 Experimental Configuration

We apply in our analysis bipolar technique. The pair of electrodes is situated on 7th and 8 th intercostals spaces and at two centimetres of junction chondrocostal on the left of the sternum. This exactly specific location has been chosen in order to particularly pay attention to diaphragmatic EMG in his costal part. We first note that we must use the reference electrode, which is situated on the wrist of the patient. In fact, the two electrodes are connected to a differential amplifier of instrumentation. We use three millimetre diameter metallic electrodes. The distance between the electrodes of one pair is fixed at 36 millimetres and it is imposed by the distance between two intercostals spaces. The electrodes are carefully positioned and situated on clean skin, which is beforehand abraded and cleaned with abrasive cream and alcohol. The signals are differentially amplified at twice. The first level amplifies (LF442), it filters frequency band [10 - 230Hz] [11]. Then, it digitizes at 1024Hz sampling frequency (one channel 12 bits ADC and are processed by digital signal processor Analog device ADC 2105). The recordings are obtained from subjects, who are

stretched out. The obtained recordings have a cardiac rhythm turning around to 60 at 90 and having a quiet respiratory cadence breaths. The analysis selected window is chosen equal to 8192 samples (8 seconds).

3 Alternating Current Power Line Interference Filtering

The electromagnetic components 50Hz and harmonics 150Hz overlap the respiratory surface EMG signal, as well as frequency and time. The classical filtering methods using a moving average window [15,17] or a narrow band rejector filter centered at the fundamental frequency [10] filtered simultaneously both the electromagnetic noise and the useful EMGcomponents. These approach may be an acceptable compromise if only a rough EMG amplitude estimate is of interest. So, they are not really adaptable to our case study. However Barata [2], estimates the amplitude and phase of the power line interference signal from a clean EMG recording segment, then a signal with the same amplitude and phase was generated and subtacted from the whole length of the noisy signal. This method will fail if the amplitude and phase change during the EMG recording session. Other techniques use the adaptable filters type LMS (Least Mean Square) which were suggested in [1,3,27]. These techniques might give interesting results especially according to ECG recording signal case. These methods can be applied for interference rejection if a reference noise can be obtained simultaneously with the corrupted signal. Then the reference input is adaptively filtered and subtracted from the original noisy signal. Widrow suggests a reference input constructed with a fixed delay Δ inserted in the reference input drawn directly from the primary input. The delay chosen must have a sufficient length to cause the respiratory EMG signal components in the reference input decorrelated from those in the primary input. The interference components willremain correlated with each other because of their periodic nature. The evaluation of the autocorrelation function of a respiratory EMG signal shows that the delay must have a sufficient length 150 milliseconds [29]. To enhance the signal to noise ratio (SNR) Bahoura proposes in [1] the same LMS structure but estimates the reference noise signal with a band-pass filter centered on the electromagnetic interference. However, it is not really sufficient because of the presence of useful signal EMG in electromagnetic components.

3.1 The algorithm

In this section, we have compared the performances by applying two combined adaptive techniques The two methods for respiratory EMG estimation require an estimation of power line interference PLI as a reference signal \widehat{PLI}_{ref} so that an LMS adaptive filter can be used to cancel PLI in the contaminated EMG signal.

The first combined adaptive technique (AIC) follows two steps. The first step consists

in generating an input reference $\widehat{PLI}_{ref} = \cos(\omega_{50}t) + \cos(\omega_{150}t)$ made of a pure cosine functions mathematically constructed; 50Hz (the fundamental) function and 150Hz (the first harmonic) function. However, in the second step the the output of the filter \widehat{PLI} is estimated to match the noise PLI in the primary input (adaptive filter type LMS) and subtracted from it to obtain the EMG estimated signal (see Fig.3. 1). The filter is optimal by minimizing the least mean square error ε_i (equation 3.1) [27,28].

The second combined adaptive technique (B_F) follows also two steps: the first step applies pass-band filter centered at the fundamental frequency 50Hz([49.5 - 50.5Hz]) and its harmonics 150Hz ([149.5 - 150.5Hz]) in order to extract the *PLI* noise reference signal. The second step applies again the same processing shown in the first adaptive technique (*AIC*).

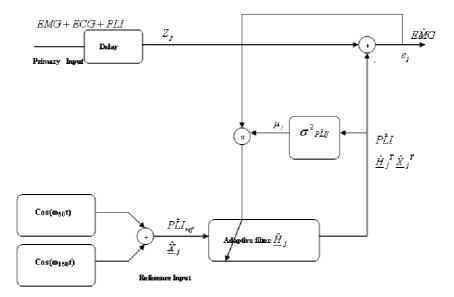


Figure 3.1: The (AIC) structure of adaptive power line interference filtering : $z_j = EMG + ECG + PLI$, raw signal; EMG, signal of interest ; PLI, noise; \widehat{PLI}_{ref} , reference noise ; \widehat{PLI} , estimate of the noise with the adaptive filter ; \hat{H}_j , adaptive filter coefficient ; \widehat{EMG} , filtered signal.

The coefficients $\underline{\widehat{H}}_{j+1}$ of the adaptive filter are computed according to equation (3.2). The error ε_j represents the difference between the original signal Z_j and the adaptive filter output $\underline{\widehat{H}}_j^T \underline{X}_j^T \left(\widehat{PLI} \right)$.

The reference input \widehat{PLI}_{ref} is the sum of two cosinusoidal signals with respectively 50Hz and 150Hz frequencies and zero phases.

The fundamental equations of this algorithm are:

$$\varepsilon_j = Z_j - \underline{\widehat{H}}_j^T \underline{X}_j^T, \qquad (3.1)$$

where $\underline{\hat{H}}_{j}$ is the reference input \widehat{PLI}_{ref} , and $\underline{\hat{H}}_{j}$ is the adaptive filter coefficients.

$$\underline{\widehat{H}}_{j+1} = \underline{\widehat{H}}_j + 2\mu\varepsilon_j\underline{\widehat{X}}_j,\tag{3.2}$$

$$j: 1 \longrightarrow M,$$
 (3.3)

$$\mu_{j+1} = \mu_j + \sigma_{\widehat{PLI}_j}^2 + \frac{1}{1 + \sigma_{\widehat{PLI}_j}^2},$$
(3.4)

 Z_j is the original signal (EMG + ECG + PLI), ε_j is the estimated EMG signal with LMS algorithm and μ is the Rate of convergence and accuracy of the adaptation process.

The noise PLI of the primary input and the reference signal \hat{PLI}_{ref} are assumed to be correlated.

The finite impulse response of the adaptive filter $\underline{\widehat{H}}_j$ is carried out with M coefficients. $\sigma^2_{\widehat{PLI}_i}$ is the power of the noise estimation \widehat{PLI} .

M should be sufficiently long in order to compensate the phase shift that may exists between the synthesized \widehat{PLI}_{ref} signal and the PLI of the raw respiratory EMG signal.

A sufficient length of an LMS filter using the adaptive filter structure can be formulated in the following expression

$$M > \frac{fs}{fpli},\tag{3.5}$$

where fs is the sampling frequency and fpli is the lowest interference frequency

3.2 Results

3.2.1 Performance indicators

To compare different methods of power line interference filtering, the Total Power in percent (TP%) is calculated according to

$$TP_i\% = 100 \frac{\sum_{i=f_1}^{f_2} (P_S(i))^2}{\sum_{i=f_1}^{f_2} (P_r(i))^2},$$
(3.6)

where Ps(i) and Pr(i) are respectively the spectral densities amplitudes of the processed signal and the raw EMG signal contaminated with obvious ECG artefacts and power line interference artefacts PLI per frequency bins. fi are frequency bins.

To evaluate the effect of the processed methods on the *PLI* and respiratory *EMG* signal separately we use the *EMG* specific segments (TP_{EMG} %) free of *PLI* and *PLI* specific segments (TP_{PLI} %) free of *EMG*.

3.2.2 Performance evaluation

We present in Figure 3.2 computer simulations demonstrating the performance of our adaptive algorithm (AIC). So we construct EMG respiratory signal contaminated by pure power line interference PLI following two-step procedures. First, cosine functions with 50Hz and 150Hz frequency are generated and then modulated by a 1 Hz cosine function frequency to produce the simulated *SPLI* signal, as shown in Fig. 3.2(a). Second, a real respiratory EMG signal measured between the 7th and the 8th intercostals space in one subject (Fig. 3.2(b)) is added to the simulated pure SPLI as shown in Fig. 3.2(c) to produce the contaminated respiratory EMG signal. The filtered respiratory *EMG* signal, recovered from the proposed algorithm, is shown in Fig. 3.2(d). This figure suggests that the original respiratory EMG features are mostly preserved while suppressing the power line interference Fig. 3.2(e) present the reference noise signal \widehat{PLI}_{ref} .

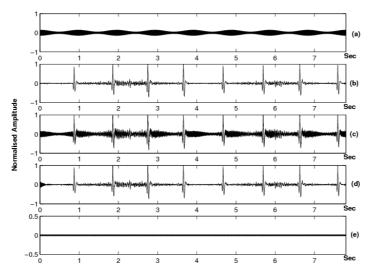


Figure 3.2: Simulation example of power line interference filtering: (a) the simulated SPLI signal; (b) real respiratory EMG signal measured between the 7th and the 8th intercostals space in one subject; (c) the constructed respiratory EMG signal. using (a) and (b) ; (d) the filtered respiratory EMG signal; (e) the reference noise signal \widehat{PLI}_{ref} .

The effects of the (AIC) cleaning technique are evaluated through different levels of signal-to-noise ratio between respiratory EMG signal and simulated SPLI signal (13 4 0 -3 -6 -9 -12db). Table 3.1 demonstrates that this method removes more than 90% of PLI across all the SNR level

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Total Power in Percent (TP%)		
SNR Level(db) (EMG/PLI)	PLI evaluation	
13	96	
4	94	
0	94	
-3	92	
-6	92	
-9	91	
-12	90	

Table 3.1: The Total Power (TP%) of a 50 and 150 Hz power line interference extracted from a contaminated respiratory EMG signal relative to a Pure simulated 50 and 150 Hz interference (PLI) in percent, TP mean is evaluated with two segments 49 to 51 Hz range for the 50 Hz and over the 149 and 151 Hz range for the 150Hz for PLI.

3.2.3 Application to real respiratory EMG signal

In this section we will compare the methods which are used to estimate the respiratory EMG signal, described in section 3.1 : two combined tecchniques: our method (AIC) and behoura adaptive filter (B_F) applied to the EMG case. The difference between them involved the reference estimation procedure. Specially, the first method (AIC) estimates the reference by using synthesized cosine functions while the second method (B_F) uses for the extraction of the reference a band pass filter varying from 49.5 to 50.5Hz and from 149.5 to 150.5Hz.

In order to prove the efficiency of the suggested method compared to the one designed in [1]. We present in Fig. 3.3a the power spectral density of the raw respiratory EMGsignal contaminated with ECG and power line interference signal. Fig 3.3b shows the spectral densities of the adaptive filter output. when the reference is carried out by generating cosines function (Fig.3.3c) (AIC) method. On the contrary Fig 3.3d displays the spectral density of the filtered signal when we apply a band-pass filters ([49.5 - 50.5Hz]and [149.5 - 150.5Hz]) ($B_{-}F$) method as a reference noise (Fig 3.3e) It's clear from this Figure that the (AIC) method (Fig.3.3b) reduces considerably the undesirable EMGspectral components around 50Hz and 150 Hz frequency compared to the case of ($B_{-}F$) method as shown in Fig.3.3d.

Respiratory signal contaminated by ECG signal and power line interference signal is shown in Fig. 3.4a. Fig.3.4b and Fig. 3.4c represent respectively the estimation of power line Interference signal \widehat{PLI} and respiratory EMG signal \widehat{EMG} applying the already designed method AIC. Using this proposed method we can note substantial cancellation of the PLI artefact as shown in Figure 3.4.

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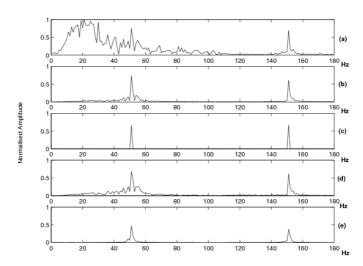


Figure 3.3: Power spectral densities of: (a) raw respiratory EMG signal contaminated with ECG and Power line interference signal; (b) filtered signal using (AIC) method; (c) reference noise signal using (AIC) method; (d) filtered signal using (B_F) method.; (e) reference noise signal using (B_F) method.

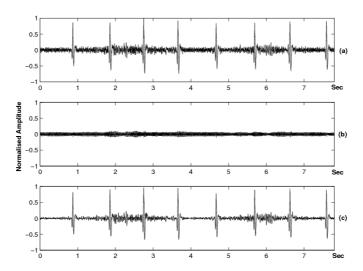


Figure 3.4: Power line interference artifact removal with AIC method: (a) Raw surface respiratory EMG signal contaminated with ECG and power line interference signals; (b) Power line interference estimation; (c) Respiratory EMG signal after power line interference subtracting.

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Total Power in Percent (TP%)				
	SNR Level(db) (EMG/PLI)	B_F method	AIC method	
PLI evaluation	5	90	93.5	
$EMG_{distortion}$	5	24	4.9	

Table 3.2: The Total Power (TP%) of a 50 and 150 Hz power line interference extracted from a contaminated respiratory EMG signal relative to a Pure simulated 50 and 150 Hz interference (PLI) in percent, TP mean is evaluated with three segments: 1-45Hz, 55-145Hz and 155 -250Hz, for EMG and with two segments 49 to 51 Hz range for the 50 Hz and over the 149 and 151 Hz range for the 150Hz for PLI ($B_{-}F$: Bahoura adaptive filter; AIC : the new proposed method).

To quantify the effects of the proposed methods on the PLI and the EMG spectral content separately, we evaluate the TP of the 50Hz and 150Hz (PLI), over the 49 to 51Hz range for the 50Hz and over the 149 and 151Hz range for the 150Hz. Table 3.2 depicts the Total power mean (TP%) of PLI cleaned signal relative to the PLI contained in the raw signal in percentage, evaluated with the two segments described above. However, The Total Power mean (TP%) of the cleaned respiratory EMG signal, relative to the raw respiratory EMG signal in percentage, is calculated to avoid PLI over the 1 to 45Hz range, the 55 to 145Hz range and the 155 to 250Hz range. We present as well in Table2. the Total power (TP%) mean of respiratory EMG cleaned signal relative to the raw respiratory EMG signal in percentage, evaluated in frequency domain mentioned above. It's clear that the (AIC) method preserves more than 95% of spectral power of EMG features while this method suppresses more than 93.5% electromagnetic interference PLI spectral power. However, we note for (B_{-F}) methods more than 24% of power alteration in EMG.

4 Electrocardiogram Artifact Filtering

The major problem with EMG respiratory surface signal is the ECG Electrocardiogram artefact. Various techniques have been proposed to reduce ECG artefact from the EMG. In fact, some of them suggested a non-linear filtering [18] based on a statistical technique. This method requires intensive matrix computation making it inappropriate for real time application. Other method developed a high-pass cut off frequency to estimate the spectral component of the EMG [25], because ECG signal overlaps in frequency domain [13] with the surface respiratory EMG. This method will result in a signal information loss. The adaptive algorithm based on that of Widrow [22, 27, 28] is an effective method to separate an interfering signal from a signal of interest. In this noise canceller the ECG signal is recorded separately and used as the reference input to the LMS filter. In order to avoid these supplementary electrodes a Widrow adaptable structure, was suggested by [24] where the input reference is carried out using band pass filter centered. at the max-

imum energy of ECG signal. This method was not really efficient because the existence of EMG residual in the reference signal, causing the distortion of the original EMG signal. To improve the adaptive filter reference input of [24] we have already suggested an adaptive technique in the precedent studies in which the noise-reference is estimated by a pass-band filter fixed rather on the QRS complex [29]. The obtained results showed a logic amelioration of the EMG/ECG signal to noise ratio.

4.1 The adaptive filtering method

In this section, we have compared the performances by applying two combined adaptive techniques The two methods for respiratory EMG estimation require an estimation of electrocardiogram interference ECG as a reference signal so that an LMS adaptive filter can be used to cancel ECG in the contaminated EMG signal.

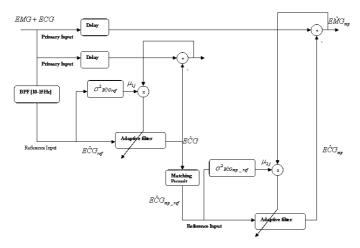


Figure 4.1: The ECG noise canceller algorithm (CAC): $z_j = EMG + ECG$, raw signal; EMG, signal of interest; ECG, noise; \widehat{ECG}_{ref} , reference noise; \widehat{ECG} , estimate of the noise with the adaptive filter; \widehat{H}_j , adaptive filter coefficient; $\widehat{ECG}_{mp,ref}$, estimate of the reference noise with the matching pursuit; \widehat{ECG}_{mp} , estimate of the noise with the adaptive filter; \widehat{EMG}_{mp} , filtered signal at the second step.

The first cascade combined adaptive approach (CAC) proposed for de-noising the respiratory EMG signal (Fig. 4.1) may be divided into two main steps: The first step uses a widrow adaptive filter type LMS and a noise reference extracted by pass-band filtering [10-15Hz], this step aims to filter the signal. Whereas to filter the ECG signals again, in order to get a highly qualified input noise reference, the second step applies the matching pursuit algorithm [7,20,21]. Then we apply once again the LMS adaptive structure to filter the signal.

The second combined adaptive technique($(BPF_{10-15hz})$) follows also two steps: the first step applies pass-band filter centered at the QRS complex ([10 - 15Hz]), in order to extract the ECG noise reference signal. The second step applies again the same processing shown in the first adaptive technique (CAC).

In this section we use the same LMS algorithm described at section 3.1 except that for the stability of the algorithm, the step-size parameter μ will be restrict according to the following equation

$$\mu_{j+1} = \mu_j + \frac{1}{1 + \sigma_{ECG_{ref_j}}^2},\tag{4.1}$$

where $\sigma_{ECG_r}^2$ is the power of the reference input.

We choose the Matching Pursuit algorithm for his high resolution and local ability to adapt to transients structures. It is an iterative, non-linear procedure. The MP decomposes signal into the summation of a series of linear expansion function. The waveforms ("atoms") are selected from a redundant dictionary of vectors of a unit module.

The algorithm of vector pursuit begins by choosing the waveform that matches the signal f, as described in equation (4.3), and at each consecutive steps, the whole dictionary is searched and an atom that is adapted (is largest) to the particular segment of the signal (residuum, left after subtracting results of previous iterations) is picked up.

$$f = \langle f, g_{\lambda 0} \rangle g_{\lambda 0} + R^1 f, \qquad (4.2)$$

$$f = \sum_{n=0}^{M-1} \langle R^n f, g_{\lambda n} \rangle g_{\lambda n} + R^M f.$$
(4.3)

The number of iteration depends on the decomposed signal length; it is fixed after test applied on real situation. The first term $\left(\sum_{n=0}^{M-1} \langle R^n f, g_{\lambda n} \rangle g_{\lambda n}\right)$ of equation (9) represent the second step electrocardiogram ECG reference signal estimation $\widehat{ECG}_{mp,ref}$

The algorithm is performed on MatLab using Wave Lab toolbox. For a decomposed signal of N = 16384 samples. The number of iteration of the matching pursuit procedure is fixed to 70, to ovoid EMG signal estimation. The FIR filter coefficients are fixed to 32 > 1024/50.

We select Symmlet wavelet family for their similarity to the ECG signal [5], especially eight order (Symmlet 8) as mother wavelet.

4.2 Results

4.2.1 Performance indicators

However, to quantitatively assess the validity and efficiency of the proposed ECG removal technique we use in this study the most common estimator of amplitude features:

the Average Rectified Value (ARV). The average rectified value of signals is defined in percent as

$$ARVs\% = 100 \; \frac{\sum_{k=1}^{N} |s(k)|}{\sum_{k=1}^{N} |r(k)|},\tag{4.4}$$

where N represents the number of samples, s(k) the processed signal samples and r(k) the raw respiratory EMG signal contaminated with obvious ECG artefacts.

To evaluate the effect of the processed methods on the ECG and EMG signals separately, we use the segments of the EMG signal between two consecutive ECG spikes $(ARV_{EMG}\%)$ free of ECG and the segments of consecutive ECG spikes $(ARV_{ECG}\%)$ free of EMG signal [30].

4.2.2 Application to real respiratory EMG signal

The adaptive process needs initially an input reference. We present in Figure 4.2 references noise signal estimation of the ECG and the processed respiratory EMG signal. Raw surface respiratory EMG signal contaminated by ECG signal is showed in Fig. 4.2a. Fig. 4.2b presents the case of an ECG noise reference obtained by the decomposition of the signal with the matching pursuit algorithm (CAC method); Fig. 4.2c depicts the case of an ECG reference estimated with a pass band filter ($BPF_{10-15hz}$) fixed on the ECG-QRS component [10-15Hz]. The Figs. 4.2d and 4.2e show the EMG processed signals. When the adaptive filter reference is respectively carried out by the CAC method and by applying band-pass filters ([10-15Hz]) ($BPF_{10-15hz}$). It is important to notice the undesirable residual ECG signal contained in the EMG signal estimation with $BPF_{10-15hz}$ method as shown in Fig. 4.2e.

According to Table 4.1 it's clear that the best performing reference signal ECG extraction is the CAC method. However we have a good ECG estimation more than 85% without EMG residual 0%.

We notice too that the frequency components of the EMG signal (less than 20Hz) are better preserved as shown on the Figure 4.3 with CAC method. This may be explained by the fact that the LMS filter adapt to EMG component that could exist in the reference signal when the BPF10 - 15hz method is applied.

In order to better confront the two methods we evaluate separately for each method, the effect of filtering on both EMG respiratory signal and ECG signal estimation (Table 4.1). The results evaluated show that the ARV% of EMG is more than 99% when we have applied CAC method. On the contrary, we loose accounting for the ARV%, more than 10% of signal EMG amplitude by applying (BPF_{10-15hz}) method. The two methods applied estimate more than 90% of ECG signal amplitude (ARV%), but in reality, CAC method has got the highest value which is equal to 98%.

To conclude, it is showed in Figure 4.4 the two phases of surface EMG signal filtering.

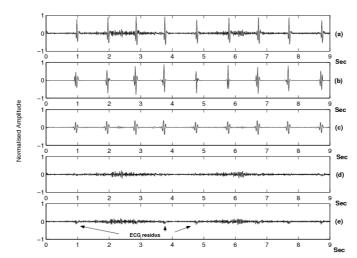


Figure 4.2: Reduction of the ECG artifacts:(a) Raw respiratory EMG signal contaminated with ECG signal.(b): ECG noise references signals extracted using matching pursuit (CAC) method.(c): ECG noise references signals extracted using Band Pass Filter $(BPF_{10-15hz})$ method. (d) Cleaned EMG signal with (CAC) method. (e) Cleaned EMG signal with $(BPF_{10-15hz})$ method.

The first phase consists in filtering (AIC) the electromagnetic components 50 Hz and 150 Hz (Fig. 4.4b) then, in the second phase we filter the ECG signal by applying the CAC

ARV Amplitude in Percent (%)			
Reference signals			
Raw EMG	$EMG_{removal}$ with BPF $_{10-15hz}$	$\mathrm{EMG}_{removal}$ with CAC	
100	96	100	
Raw ECG	ECG $_{10-15hz}$ method	ECG CAC method	
100	60	85	
Filtered Signals			
Raw EMG	$EMG_{Distortion}$ with BPF $_{10-15hz}$	$EMG_{Distortion}$ with CAC	
100	10	0.92	
Raw ECG	ECG $_{10-15hz}$	ECG CAC	
100	91	98	

Table 4.1: Average rectified value (ARV) mean of ECG and EMG components in reference noise signal.and in Filtered Signal using CAC and $B_{-}F$ methods.

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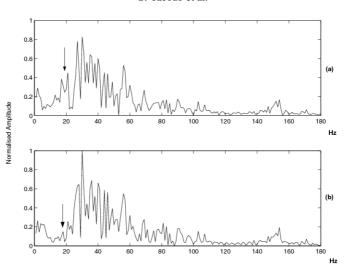


Figure 4.3: Power spectral density estimation of cleaned respiratory EMG signal with:(a) $BPF_{10-15hz}$ method (b) New CAC method.

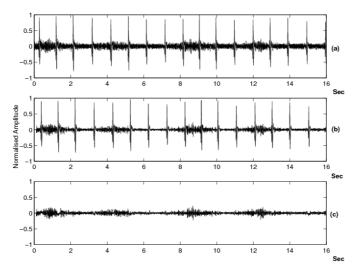


Figure 4.4: Raw surface respiratory EMG signal contaminated with ECG and power line interference signals; (b) Power line interference removal after applying (AIC) algorithm; (c) ECG signal removal after applying (CAC) algorithm.

method (Fig. 4.4c). The obtained results showed clearly the improvement of the signal to noise EMG/PLI and EMG/ECG in both cases.

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5 Conclusion

In this work we have developed new techniques of noise filtering. In case of electromagnetic interference it is shown that the use of synthesized reference noise with the help of cosines function allows us to get a clean reference noise signal, well corrolated with te noise of the primary input. These conditions play an important role in the rate of convergence and rejection bandwith of the filter. Concerning the cascade adaptive filter of electrocardiogram ECG component, it's carried out in two steps. The first one aims at getting the finest ECG noise reference signal estimation by combining two structures: an LMS structure in which the reference is performed with a band pass filter [10 - 15Hz] followed by a matching pursuit algorithm. In order to cancel the ECG signal the second step applies the LMS structure again with the reference obtained at the first step. This method preserves a large component of EMG while effectively eliminating ECG artefact. In addition the automatic adjustment of the filter adaptation parameter μ avoids the cumbersome trial and error process needed to chose an adequate value for the step-size parameter. It will increase the speed of convergence of the new structures (AIC and CAC). and it will also minimize the rejection bandwidth even when the primary input noise increases. Furthermore the proposed procedures may also be applied without the use of supplementary electrode pairs, which will have interesting implications on future usage with fewer cables.

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