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Some Fixed Point Theorems Satisfying Contractive Conditions of Integral Type in Dislocated Quasi-Metric Space

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Abstract: The aim of this note is to study some fixed point theorems of integral type in dislocated quasi-metric space. We have establish some fixed point theorems satisfying integral type contractive conditions which generalizes fixed point theorems proved by Aage and Salunke [1], Muraliraj and Hussain [6], kohli et al. [7] and Zeyada et al. [11].

Keywords: Complete dislocated quasi-metric space, self-mapping, Cauchy sequence, fixed point.

1 Introduction

The concept of dislocated metric space was introduced by Hitzler and Seda [5]. In such a space the self-distance of points need not to be zero necessarily. They also generalized famous Banach contraction principle in dislocated metric space. Dislocated metric space play a vital role in Topology, Logical programming and Electronic engineering etc. Zeyada et al. [11] developed the notion of complete dislocated quasi-metric space and generalized the result of Hitzler and Seda [5] in dislocated quasi-metric space. With the passage of time many papers have been published by various authors containing fixed point results in dislocated quasi-metric spaces for different type of contractive conditions (see [1], [2], [6], [7], [9], [10]).

In 2002, Branciari [3] obtained a fixed point theorem for a single self-mapping satisfying an analogous of Banach's contraction principle for integral type inequality in metric space. Recently, in 2014 Patel et al. [8] studied some fixed point theorems of integral type in dislocated quasi-metric space.

In this article, we have establish some fixed point results for integral type contractive conditions in dislocated quasi-metric space. Our obtain results generalizes some well-known results in the literature. Examples are constructed in the support of our establish theorems and corollaries.

2 Preliminaries

Througisout the paper \mathbb{R}^+ represent the set of non-negative real numbers.

Definition 2.1.[8]. Let *X* be a non-empty set. Let $d: X \times X \to \mathbb{R}^+$ be a function satisfying the conditions for all $x, y, z \in X$,

$$d_{1} \int_{0}^{d(x,x)} \rho(t)dt = 0;$$

$$d_{2} \int_{0}^{d(x,y)} \rho(t)dt = \int_{0}^{d(y,x)} \rho(t)dt = 0 \implies x = y;$$

$$d_{3} \int_{0}^{d(x,y)} \rho(t)dt = \int_{0}^{d(y,x)} \rho(t)dt;$$

$$d_{4} \int_{0}^{d(x,y)} \rho(t)dt \le \int_{0}^{d(x,z)} \rho(t)dt + \int_{0}^{d(z,y)} \rho(t)dt.$$

If *d* satisfies all of the above conditions then *d* is called a metric on *X*. If *d* satisfies the conditions from $d_2 - d_4$ then *d* is said to be dislocated metric (OR) shortly (*d*-metric) on *X* and if *d* satisfies only d_2 and d_4 then *d* is called dislocated quasi-metric (OR) shortly (*dq*-metric) on *X* and the pair (*X*, *d*) is called dislocated quasi-metric space. Where $\rho : \mathbb{R}^+ \to \mathbb{R}^+$ is a Lebesque integrable mapping which is summable on each compact subset of \mathbb{R}^+ ,

non-negative and such that for any $s > 0 \int_{0}^{s} \rho(t) dt > 0$.

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Note. The above definition change to usual definition of metric space if $\rho(t) = I$.

It is clear that every metric space is dislocated metric and dislocated quasi metric space but the converse is not true. Also every dislocated metric space is dislocated quasi-metric space but the converse is not necessarily true.

The following definitions can be found in [8].

Definition 2.2. A sequence $\{x_n\}$ in *dq*-metric space is said to be *dq*-convergent to a point $x \in X$ if

$$\lim_{n\to\infty}\int\limits_0^{d(x_n,x)}\rho(t)dt=\lim_{n\to\infty}\int\limits_0^{d(x,x_n)}\rho(t)dt=0.$$

In such a case *x* is called *dq*-limit of the sequence $\{x_n\}$. **Definition 2.3.** A sequence $\{x_n\}$ in *dq*-metric space (X,d)is said to be Cauchy sequence if for $\varepsilon > 0$ there exist $n_0 \in N$ such that $m, n \ge n_0$ implies

$$\int_{0}^{d(x_n,x_m)} \rho(t)dt = \int_{0}^{d(x_m,x_n)} \rho(t)dt < \varepsilon$$

(OR)

$$\lim_{n\to\infty}\int_{0}^{d(x_n,x_m)}\rho(t)dt=\lim_{n\to\infty}\int_{0}^{d(x_m,x_n)}\rho(t)dt=0$$

Definition 2.4. A dq-metric space (X,d) is said to be complete if every Cauchy sequence in X converge to a point in X.

The following simple but important results can be seen in [11].

Lemma 2.5. Limit of a convergent sequence in *dq*-metric space is unique.

Theorem 2.6. Let (X,d) be a complete dq-metric space $T: X \to X$ be a contraction. Then T has a unique fixed point.

Branciari [3] proved the following theorem in metric spaces.

Theorem 2.7. Let (X,d) be a complete metric space for $\alpha \in (0,1)$. Let $T: X \to X$ be a mapping such that for all $x, y \in X$ satisfying

$$\int_{0}^{d(Tx,Ty)} \rho(t)dt \leq \alpha \cdot \int_{0}^{d(x,y)} \rho(t)dt.$$

Where $\rho : \mathbb{R}^+ \to \mathbb{R}^+$ is a Lebesque integrable mapping which is summable on each compact subset of \mathbb{R}^+ , non-negative and such that for any $s > 0 \int_{0}^{s} \rho(t) dt > 0$. Then *T* has a unique fixed point in *X*.

3 Main Results

Theorem 3.1. Let (X,d) be a complete dislocated quasimetric space, for $a, b, c, e, f \ge 0$ with a + b + c + e + f < 1

and let $T: X \to X$ be a continuous self-mapping such that for all $x, y \in X$, satisfying the condition

$$\int_{0}^{d(Tx,Ty)} \rho(t)dt \leq a \cdot \int_{0}^{d(x,y)} \rho(t)dt + b \cdot \int_{0}^{d(x,Tx)} \rho(t)dt + d(x,Tx)$$

$$\int_{0}^{d(y,Ty)} \rho(t)dt + e \cdot \int_{0}^{\frac{d(y,Ty)[1+d(x,Tx)]}{1+d(x,y)}} \rho(t)dt + f \cdot \int_{0}^{\frac{d(x,Ty)d(y,Ty)}{d(x,y)+d(y,Ty)}} \rho(t)dt$$

where $\rho : \mathbb{R}^+ \to \mathbb{R}^+$ is a Lebesque integrable mapping which is summable on each compact subset of \mathbb{R}^+ , non-negative and such that for any $s > 0 \int_{0}^{s} \rho(t) dt > 0$.

Then T has a unique fixed point.

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Proof. Let x_0 be arbitrary in *X* we define a sequence $\{x_n\}$ in *X* defined as follows

$$x_0, x_1 = Tx_0, \dots, x_{n+1} = Tx_n.$$

To show that $\{x_n\}$ is a Cauchy sequence in X consider

$$\int_{0}^{d(x_{n},x_{n+1})} \rho(t)dt = \int_{0}^{d(Tx_{n-1},Tx_{n})} \rho(t)dt$$

By given condition in the theorem we have

$$\leq a \cdot \int_{0}^{d(x_{n-1},x_n)} \rho(t)dt + b \cdot \int_{0}^{d(x_{n-1},Tx_{n-1})} \rho(t)dt + c \cdot \int_{0}^{d(x_n,Tx_n)} \rho(t)dt + c \cdot \int_{0}^{d(x_n,Tx_n)} \rho(t)dt + e \cdot \int_{0}^{\frac{d(x_n,Tx_n)[1+d(x_{n-1},Tx_{n-1})]}{1+d(x_{n-1},x_n)}} \rho(t)dt + c \cdot \int_{0}^{\frac{d(x_{n-1},Tx_n)d(x_n,Tx_n)}{d(x_{n-1},x_n)+d(x_n,Tx_n)}} \rho(t)dt + c \cdot \int_{0}^{\frac{d(x_n,Tx_n)d(x_n,Tx_n)}{d(x_{n-1},x_n)+d(x_n,Tx_n)}} \rho(t)dt + c \cdot \int_{0}^{\frac{d(x_n,Tx_n)d(x_n,Tx_n)}{d(x_{n-1},x_n)+d(x_n,Tx_n)}}} \rho(t)dt + c \cdot \int_{0}^{\frac{d(x_n,Tx_n)d(x_n,Tx_n)}{d(x_n,Tx_n)+d(x_n,Tx_n)}}} \rho(t)dt + c \cdot \int_{0}^{\frac{d(x_n,Tx_n)d(x_n,Tx_n)}{d(x_n,Tx_n)+d(x_n,Tx_n)}} \rho(t)dt + c \cdot \int_{0}^{\frac{d(x_n,Tx_n)d(x_n,Tx_n)}{d(x_n,Tx_n)+d(x_n,Tx_n)}} \rho(t)dt + c \cdot \int_{0}^{\frac{d(x_n,Tx_n)d(x_n,Tx_n)}{d(x_n,Tx_n)+d(x_n,Tx_n)}}}$$

Using the definition of the defined sequence we have

$$\leq a \cdot \int_{0}^{d(x_{n-1},x_n)} \rho(t)dt + b \cdot \int_{0}^{d(x_{n-1},x_n)} \rho(t)dt + c \cdot \int_{0}^{d(x_n,x_{n+1})} \rho(t)dt + c \cdot \int_{0}^{\frac{d(x_n,x_{n+1})[1+d(x_{n-1},x_n)]}{1+d(x_{n-1},x_n)}} \rho(t)dt + c \cdot \int_{0}^{\frac{d(x_n-1,x_{n+1})d(x_n,x_{n+1})}{1+d(x_n,x_{n+1})}} f \cdot \int_{0}^{\frac{d(x_n-1,x_n+1)d(x_n,x_{n+1})}{1+d(x_n,x_{n+1})}} \rho(t).$$

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Simplification yields

$$\leq a \cdot \int_{0}^{d(x_{n-1},x_n)} \rho(t)dt + b \cdot \int_{0}^{d(x_{n-1},x_n)} \rho(t)dt +$$

$$c \cdot \int_{0}^{d(x_{n},x_{n+1})} \rho(t)dt + e \cdot \int_{0}^{d(x_{n},x_{n+1})} \rho(t)dt + f \cdot \int_{0}^{d(x_{n},x_{n+1})} \rho(t)dt$$
$$\int_{0}^{d(x_{n},x_{n+1})} \rho(t)dt \le \left(\frac{a+b}{1-(c+e+f)}\right) \cdot \int_{0}^{d(x_{n-1},x_{n})} \rho(t)dt.$$

Let $h = \frac{a+b}{1-(c+e+f)}$, so the above inequality become

$$\int_{0}^{d(x_n,x_{n+1})} \rho(t)dt \leq h \cdot \int_{0}^{d(x_{n-1},x_n)} \rho(t)dt.$$

Also

$$\int_{0}^{d(x_{n-1},x_n)} \rho(t)dt \leq h \cdot \int_{0}^{d(x_{n-2},x_{n-1})} \rho(t)dt.$$

So

$$\int_{0}^{d(x_n,x_{n+1})} \rho(t)dt \leq h^2 \cdot \int_{0}^{d(x_{n-2},x_{n-1})} \rho(t)dt.$$

Similarly proceeding we get

$$\int_{0}^{d(x_n,x_{n+1})} \rho(t)dt \leq h^n \cdot \int_{0}^{d(x_0,x_1)} \rho(t)dt.$$

Since h < 1 and taking limit $n \to \infty$, we have $h^n \to 0$. Hence

$$\int_{0}^{d(x_n,x_{n+1})} \rho(t)dt \to 0.$$

Which implies that $d(x_n, x_{n+1}) \to 0$ as $n \to \infty$. Hence $\{x_n\}$ is a Cauchy sequence in complete dq-metric space. So there must exists $u \in X$ such that

$$\lim_{n\to\infty}x_n=u.$$

Since T is continuous so

$$Tu = \lim_{n \to \infty} Tx_n = \lim_{n \to \infty} x_{n+1} = u.$$

Thus u is the fixed point of T.

Uniqueness. If $u \in X$ is a fixed point of *T*. Then by given condition in the theorem we have

$$\int_{0}^{d(u,u)} \rho(t)dt = \int_{0}^{d(Tu,Tu)} \rho(t)dt$$

$$\int_{0}^{d(u,u)} \rho(t)dt \leq (a+b+c+e+f) \int_{0}^{d(u,u)} \rho(t)dt.$$

Since a + b + c + e + f < 1, so the above inequality is possible if d(u,u) = 0 similarly if $v \in X$ is the fixed point of *T*. Then we can show that d(v,v) = 0. Now consider that u, v are two distinct fixed points of *T* then again by given condition in the theorem We have

$$\int_{0}^{d(u,v)} \rho(t)dt = \int_{0}^{d(Tu,Tv)} \rho(t)dt$$

$$\leq a \cdot \int_{0}^{d(u,v)} \rho(t)dt + b \cdot \int_{0}^{d(u,Tu)} \rho(t)dt + c \cdot \int_{0}^{d(v,Tv)} \rho(t)dt + c \cdot \int_{0}^{d(v,Tv)} \rho(t)dt + c \cdot \int_{0}^{d(v,Tv)[1+d(u,Tu)]} \rho(t)dt + f \cdot \int_{0}^{\frac{d(u,Tv)d(v,Tv)}{d(u,v)+d(v,Tv)}} \rho(t)dt.$$

Now using the fact that u, v are fixed points of T and then simplifying We get the following inequality

$$\int_{0}^{d(u,v)} \rho(t)dt \le a. \int_{0}^{d(u,v)} \rho(t)dt.$$

Since a < 1 so the a above inequality is possible if d(u,v) = 0 similarly we can show that d(v,u) = 0 which implies that u = v. Hence fixed point of *T* is unique.

Theorem 3.1 yields the following corollaries. **Corollary 3.2.** Let (X,d) be a complete dislocated quasi-metric space, for $a \ge 0$, with $a \in (0,1)$ and let $T: X \to X$ be a continuous self-mapping such that for all $x, y \in X$ satisfying the condition

$$\int_{0}^{d(Tx,Ty)} \rho(t)dt \le a \cdot \int_{0}^{d(x,y)} \rho(t)dt.$$

Where $\rho : \mathbb{R}^+ \to \mathbb{R}^+$ is a Lebesque integrable mapping which is summable on each compact subset of \mathbb{R}^+ , non-negative and such that for any $s > 0 \int_{0}^{s} \rho(t) dt > 0$. Then *T*

has a unique fixed point.

Corollary 3.3. Let (X,d) be a complete dislocated quasimetric space, for $a,b,c \ge 0$, with a+b+c < 1 and let $T: X \to X$ be a continuous self-mapping such that for all $x, y \in X$ satisfying the condition

$$\int_{0}^{d(Tx,Ty)} \rho(t)dt \leq a \cdot \int_{0}^{d(x,y)} \rho(t)dt + b \cdot \int_{0}^{d(x,Tx)} \rho(t)dt + c \cdot \int_{0}^{d(y,Ty)} \rho(t)dt + c \cdot \int_{0}^{d(y,Ty)} \rho(t)dt.$$

Where $\rho : \mathbb{R}^+ \to \mathbb{R}^+$ is a Lebesque integrable mapping which is summable on each compact subset of \mathbb{R}^+ , nonnegative and such that for any $s > 0 \int_{0}^{s} \rho(t) dt > 0$. Then T has a unique fixed point.

Corollary 3.4. Let (X,d) be a complete dislocated quasi metric space, for $a, b, c \ge 0$, with a + b + c < 1 and let $T: X \to X$ be a continuous self-mapping such that for all $x, y \in X$ satisfying the condition

$$\int_{0}^{d(Tx,Ty)} \rho(t)dt \leq a \cdot \int_{0}^{d(x,y)} \rho(t)dt + b \cdot \int_{0}^{d(y,Ty)} \rho(t)dt + \frac{\frac{d(y,Ty)[1+d(x,Tx)]}{1+d(x,y)}}{c \cdot \int_{0}^{\frac{d(y,Ty)[1+d(x,Tx)]}{1+d(x,y)}} \rho(t)dt$$

Where $\rho : \mathbb{R}^+ \to \mathbb{R}^+$ is a Lebesque integrable mapping which is summable on each compact subset of \mathbb{R}^+ , nonnegative and such that for any $s > 0 \int_{0}^{s} \rho(t) dt > 0$. Then T

has a unique fixed point.

Corollary 3.5. Let (X,d) be a complete dislocated quasimetric space, for $a, b \ge 0$, with a + b < 1 and let $T : X \rightarrow$ X be a continuous self-mapping such that for all $x, y \in X$ satisfying the condition

$$\int_{0}^{d(Tx,Ty)} \rho(t)dt \leq a \cdot \int_{0}^{d(x,y)} \rho(t)dt + b \cdot \int_{0}^{\frac{d(x,Ty)d(y,Ty)}{d(x,y)+d(y,Ty)}} \rho(t)dt.$$

Where $ho:\mathbb{R}^+ o\mathbb{R}^+$ is a Lebesque integrable mapping which is summable on each compact subset of \mathbb{R}^+ , nonnegative and such that for any $s > 0 \int_{0}^{s} \rho(t) dt > 0$. Then T

has a unique fixed point.

We have the following remarks from the above corollaries. Remarks.

- -In Corollary 3.2 if $\rho(t) = I$. Then we get the result of Zeyada et al. [11].
- -In Corollary 3.3 if $\rho(t) = I$. Then we get the result of Aage and Salunke [1].
- -In Corollary 3.4 if $\rho(t) = I$. Then we get the result of Kohli et al. [7].
- -In Corollary 3.5 if $\rho(t) = I$. Then we get the result of Muraliraj and Hussain [6].

Example 3.6. Let X = [0,1] and the complete dq-metric defined on X is given by d(x,y) = |x| with self-mapping defined on X is $Tx = \frac{x}{2}$ and $\rho(t) = \frac{t}{2}$. Then

$$\int_{0}^{d(Tx,Ty)} \rho(t)dt = \int_{0}^{|\frac{x}{2}|} \frac{t}{2}dt = \frac{1}{16}x^{2} \le \frac{1}{4}\left(\frac{1}{4}x^{2}\right) \le a. \int_{0}^{d(x,y)} \rho(t)dt.$$

Satisfy all the conditions of the Corollary 3 for $a \in [\frac{1}{4}, 1)$ having x = 0 is its unique fixed point.

Example 3.7. Let X = [0,1] and the complete dq-metric defined on X is given by d(x,y) = |x| with self-mapping defined on X is $Tx = \frac{x}{2}$ and $\rho(t) = \frac{t}{2}$ for $a = \frac{1}{3}, b = \frac{1}{4}, c =$ $\frac{1}{6}, e = \frac{1}{8}, f = \frac{1}{12}$. Satisfy all the conditions of Theorem ?? having x = 0 is the unique fixed point of *T*.

Theorem 3.8. Let (X,d) be a complete dislocated quasimetric space, for $\alpha \ge 0$, with $\alpha \in [0,1)$ and let $S, T : X \rightarrow$ X are continuous self-mappings such that for all $x, y \in X$ satisfying the condition

$$\int_{0}^{d(Sx,Ty)} \rho(t)dt \leq \alpha. \int_{0}^{M(x,y)} \rho(t)dt$$

with $M(x,y) = \alpha \cdot \max\{d(x,y), d(x,Sx), d(y,Ty)\}$ where $\rho: \mathbb{R}^+ \to \mathbb{R}^+$ is a Lebesque integrable mapping which is summable on each compact subset of \mathbb{R}^+ , non-negative and such that for any $s > 0 \int_{0}^{s} \rho(t) dt > 0$. Then S and T have a unique common fixed point.

Proof. Let x_0 be arbitrary in X we define a sequence $\{x_n\}$ for n = 0, 1, 2, ... by the rule

$$x_0, x_1 = Sx_0, x_3 = Sx_2, \dots, x_{2n+1} = Sx_{2n}$$

and

$$x_2 = Tx_1, x_4 = Tx_3, \dots, x_{2n} = Tx_{2n-1}$$

Now we have to show that $\{x_n\}$ is a Cauchy sequence in *X* for this consider

$$\int_{0}^{d(x_{2n+1},x_{2n+2})} \rho(t)dt = \int_{0}^{d(Sx_{2n},Tx_{2n+1})} \rho(t)dt$$

By given condition in the theorem and using the construction of the sequence defined above we have

$$\max\{d(x_{2n}, x_{2n+1}), d(x_{2n}, Sx_{2n}), d(x_{2n+1}, Tx_{2n+1})\} \leq \alpha \cdot \int_{0}^{\infty} \rho(t) dt$$

$$\max\{d(x_{2n}, x_{2n+1}), d(x_{2n}, x_{2n+1}), d(x_{2n+1}, x_{2n+2})\}$$

 $\leq \alpha \cdot \int_{0}^{d(x_{2n}, x_{2n+1})} \rho(t) dt.$

 $\rho(t)dt$.

Similarly

$$\int_{0}^{d(x_{2n},x_{2n+1})} \rho(t)dt \leq \alpha \cdot \int_{0}^{d(x_{2n-1},x_{2n})} \rho(t)dt.$$

So

$$\int_{0}^{d(x_{2n+1},x_{2n+2})} \rho(t)dt \leq \alpha^2 \cdot \int_{0}^{d(x_{2n},x_{2n+1})} \rho(t)dt.$$

Proceeding in such a way we have

$$\int_{0}^{d(x_{2n+1},x_{2n+2})} \rho(t)dt \leq \alpha^{2n} \cdot \int_{0}^{d(x_0,x_1)} \rho(t)dt.$$

Since h < 1 and taking limit $n \to \infty$, We have $h^{2n} \to 0$. Hence $d(x_{2n+1}, x_{2n+2})$

$$\int_{0}^{x_{2n+1},x_{2n+2})} \rho(t)dt \to 0.$$

Which implies that $d(x_{2n+1}, x_{2n+2}) \to 0$ as $n \to \infty$. Hence $\{x_n\}$ is a Cauchy sequence in complete *dq*-metric space. So there must exists $u \in X$ such that

$$\lim_{n\to\infty}x_n=u.$$

Also the sub-sequences $\{x_{2n}\}$ and $\{x_{2n+1}\}$ converges to *u*. Since *S* and *T* are continuous so

$$T \lim_{n \to \infty} x_{2n+1} = Tu \Rightarrow Tu = u$$

Similarly we can show that Su = u. Therefore *u* is the common fixed point of *S* and *T*.

Uniqueness. Let u, v be two distinct common fixed points of *S* and *T*. Then by using the given condition in the theorem we can easily show that

$$d(u,u) = d(v,v) = 0.$$

Now consider

$$\int_{0}^{d(u,v)} \rho(t)dt = \int_{0}^{d(Su,Tv)} \rho(t)dt$$

$$\max_{\substack{\{d(u,v),d(u,u),d(v,v)\}\\ 0}} \alpha \cdot \int_{0}^{d(u,v)} \rho(t)dt$$
$$\leq \alpha \cdot \int_{0}^{d(u,v)} \rho(t)dt.$$

Since $\alpha < 1$ so the above inequality is possible if d(u, v) = 0. Similarly we can show that d(v, u) = 0 implies that u = v. Hence *S* and *T* have a unique common fixed point. **Remark.**

-In Theorem 3.8 if S = T and $\rho(t) = I$. Then we get the result established by Aage and Salunke [2].

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