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A Hybrid CS-ABC Optimization Technique for Solving Unit Commitment Problem with Wind Power Uncertainty

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Abstract: The strength of the power system is completely based in the power flow analysis, examination and design. It is mandatory to perform planning, operating, economic scheduling and power exchange in the available utilities. The voltage and magnitude phase angle at the bus and real/reactive power flow in the transmission lines are the primary function of the power flow examination. This investigation anticipates a solution to power system's optimal power flow (OPF) integrating wind power. The wind related costs estimation parameters are (i) estimation of wind generator output based on reserve cost arising (ii) cost for not utilizing completely offered wind power which incorporated in conventional OPF. A hybrid cuckoo search optimization technique and artificial bee colony optimization technique is employed for resolving wind power OPF model. Modified IEEE bus systems are used as test systems and it is show that the cuckoo searches and artificial bee colony executes better than conventional swarm optimization. The cost estimation is performed in MATLAB environment. The minimum operating cost is \$156000000 at load demand 78MW and wind probability is 0.8269. Similarly, the maximum operating cost is \$416000000 for 20th hour at load demand 102MW and the wind probability is 1.

Keywords: Cuckoo search optimization, Artificial Bee Colony optimization, Optimal power flow, Cost estimation, IEEE bus system, wind generator.

1 Introduction

Wind energy shows an abundance growth for the recent years for its clear nature, less expensive and due to its availability. The fast depleting and the environmental concerns of the traditional resources like fossil fuels has provided an alternative energy sources, thus acts as a driving factor for certain areas of research. The main crisis related to it is the stochastic nature and the intermittent nature in addition to the costs as in figure 1. To extract the maximum beneficial outputs, reduction of costs is the primary need currently. Huge amount of conventional work has been carried out in the optimal power flow (OPF) along with the wind farms. Wind generation in association with OPF model [1] was investigated in the deeper manner.

Optimal power flow (OPF) issues are the essential central issues in control framework task. Generally, they are the streamlining issues and their fundamental target is to decrease the aggregate cost of units while fulfilling different requirements in the framework. The OPF issue has been generally utilized as a part of energy framework task and arranging. Numerous methods, for example, straight programming (LP), nonlinear programming (NLP) [5]-[8], and quadratic programming (QP) have been connected for tackling the OPF issue. For usage of these techniques, the issue should be convexity and subsequently there is a fore to rearrange the issue to guarantee the convexity. Be that as it may, the OPF is when all is said in done a non-convex issue with numerous nearby minima. Moreover, the traditional streamlining techniques are profoundly delicate to the beginning stages and every now and again meet to neighborhood ideal arrangement or veer by and large.

Fixed speed of the wind generator at P-Q bus has been considered for this model. It is reported that the up/down spinning reserve costs along with wind power generation uncertainty [2] was considered as the objective function with respect to power generation cost.

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Fig. 1: Cost and power flow in a wind power

This investigation projects the wind generators real power outputs as a quality penalty function and a control variable with the penalty factors to realize the successive discretization of discrete control variables. The solution of this crisis has been obtained using primal-dual interior point. Estimation of the wind power along with the penalty based on the function generation is included in the wind generation.

This investigational effort is organized as the following segments: Segment 2 deliberates the wind power random variable overflow. Segment 3 shows power flow analysis. Segment 4 explains wind cost modeling considering costs related estimation of wind farm output power. Segment 5 explains the multi-objective based UCP of generator. Segment 6, OPF problem formulation incorporating CS is presented. Section 7 depicts the effectiveness of Artificial Bee colony optimization, in Section 8 hybrid ABC algorithm based on CS algorithm is demonstrated. The results obtained by CS-ABC are shown in section 8. Simulation and conclusion of the proposed method is illustrated in section 9 and 10 respectively.

2 Power Flow Overview

The complete objective of this investigation is to generate a program that performs the user to sort out the power flow crisis. Moreover, other functionalities are required as follows:

- -In order to plan the other stages of new networks in addition to the prevailing one, power flow analysis is significant. Adding new generators, increase in load demand requirement and location of the transmission sites.
- -Load flow solution provides the nodal voltages and phase angles as an outcome [3]. Thus, power injection is caused in the power flow and the entire buses through the interconnecting power channels.
- -The bus voltage is verified. The reversing of the voltage level buses is held in closed tolerances. Identification of line flows is also considered.
- -The line associated with the load flow should not be overloaded. That is, it is to be avoided to work to the nearer values of stability and limits.
- -The transmission lines performance are recorded based on the transformer and the generator at the steady state condition.

A program for power flow examination should be given for training principles. To acquire the simulation of

the power flow, an investigation is carried out using MATLAB environment.

3 Analysis of Power Flow

The analysis of power flow (recognized to be load-flow) is a significant tool concerning mathematical examination functional of power scheme [4]. Disparate of conventional circuit examination, power flow typically makes use of simplified notation like per-unit scheme and one-line diagram, and spotlights on diverse AC power forms (i.e., real, apparent and reactive) devoid of current and voltage. The benefits of power flow investigation are to plan the future development of power systems in addition to the finest operation of prevailing schemes.

Load buses: No generators are connected in the load bus, thus real power, PG_i and reactive power QG_i are determined as zero. The load given by buses is provided as real power $-PL_i$ and reactive power $-QL_i$ in the power flowing in negative sign over the bus [5]. Thus these buses are referred as P-Q bus. The load flow purpose is to acquire the voltage magnitude —Vi— and the angle δi .

Voltage controlled buses: The generators are associated with the voltage controlled buses. Hence the power generation [6] certain buses are restricted via prime move as terminal voltage manages the generator excitation. Input power are maintained to be constant through keeping a constant bus voltage and turbine-governor control with an automatic voltage regulator, it is provided that specify constant Vi and PG_i for the buses.

Slack or swing Bus: Typically these buses are numbered 1 for load flow analysis. These buses fix angular reference for subsequent buses. It provides the angle difference between two voltage sources that utters reactive and real power flow [7] between them; the definite slack bus angle is not important. It fixes the reference angles next to the subsequent busses where voltages are deliberated. Due to this, the bus angle is typically selected as 0. In addition it is implicit that the voltage of the bus magnitude is identified.

4 Cost Evaluation of Wind Generation

The wind generator output power is not equivalent to the scheduled output because of the stochastic nature of the wind speed [8]. The power related to it is usually greater than or lesser than what is needed initially. Now, there are two possible conditions: primarily, either any third party should own the wind farm or any system operator should own it. In the first case, the third party should guarantee the amount of power bound based on a contract for day to day practice, if that is not done in a regular basis, a costly penalty is incurred. In the present condition, the second condition will be done by the system operator without any

such penalty. To maintain the power balance during wind power overestimation, load shedding or alternate sources (reserves) are required [9] based on penalty to bring significance and reliability of the economic concerns.

Nonetheless, in the case of underestimation, the output power of the wind farm should be reduced to avoid the wastage of the energy capacity available and to avoid the negative impact on environment [10]. By summarizing the above mentioned situations, (one prefers wind farm dependency for power needs, whereas other needs more reliable conventional generators for regular usage) both are harmful to the environment with regards to operational reliability, economy etc. This leads to the modification of the conventional OPF and its objective function [11] in order to restrict the harmful environment. The cost estimation of available wind power based on overestimation and underestimation of wind generated electricity can be expressed as,

Cost function:

Ci(Pi)= $(a_i.W_{G1} + b_i.W_{G2})$ Fun = min $\sum_{k=0}^{N_{WG}} (C_i(P_i))$ NWG - Number of wind power generation ai,bi wind power cost WG1 Wind power generation 1 WG2 Wind power generation 2

5 Multi-Objective Based Unit Commitment Problem.

The wind uncertainty related unit commitment crisis and the net load relevancy is described in a mathematical formulation. In general, the operating cost should be minimized, in a generators unit commitment is a part of the optimization optimization problem [12]-[13]. The cost estimation is classified as the starting up cost and fuel consumption cost. Thus, the modeling of the starting up cost is employed using the piecewise expression to calculate the total hours relied by the particular generator that has been de-committed, conversely, modeling of the fuel consumption cost relies on the power production related quadratic expression.

AUTHOR	INDICATOR OPTIMIZED	OUTCOME	ALGORITHM USED
Arnau González et al	Minimum life cycle cost	In order to necessitates the load demand	PSO and GA
(2015)		with reduced life cycle cost, a hybrid	
		system is designed on the basics of net	
		cost (at present)	
Akbar Maleki (2014)	Annual cost	PSO tool is used to calculate the	TS, PSO, SA, HS,
		optimal solution to provide an	
		outcome with a minimal cost while	
		comparing with the subsequent	
		artificial intelligence methods	
Ce Shang (2016)	Economic, levelized cost	The sizing optimization is described in	PSO
		a dispatch-coupled manner, to derive an	
		optimal battery size for systems with	
		diverse levels of penetration renewable	
Yang Hongxing (2010)	Economic	An optimal hybrid system is designed	Genetic algorithm
		with the least annualized cost with to	
		satisfy load demand on the basis of	
		power supply loss probability	
Yang (2003)	Reliability, and probability of	hybrid power generation systems based	Matlab
	power supply	on the study of weather data and	
		probability analysis	
Khatod (2010)	production cost and assessment	To design a technique based on high	Monte Carlo simulation
		accuracy and lesser computing time in	
		contrast to Monte Carlo technique	
Tina (2010)	Probability distribution	Algorithm development with the	Matlab
	function	outcome that provides information	
		more reliably and optimal design	
		configuration of hybrid systems	

Table 1: Various optimization techniques for cost estimation

 $C \rightarrow \text{total cost;}$

 $H \rightarrow$ total number of hours;

 $U(i,\,t) \rightarrow$ unit status of i at t^{th} hour, i.e., 1 for ON and 0 for OFF;

 a_i , b_i and $c_i \rightarrow$ fuel cost coefficients of generating unit 'i' at t_{th} hour;

 $PRWT(j, t) \rightarrow probability of the wind generator unit j at th hour, thus calculation based on wind power uncertainty;$

 $PTG(i, t) \rightarrow output \text{ power of generator unit `i' at } t^{th} \text{ hour;}$

 $S_c(i, t) \rightarrow$ starting-up cost of unit 'i' at tth hour;

 $N \rightarrow$ number of generating units;

 $k_0,\,i,\,k_1,\,i$ and $k_2,\,i\rightarrow$ starting-up cost coefficients of generating unit 'i' and

 $T_{\rm off}(i,t) \rightarrow$ duration of generating unit 'i' is off at t^{th} hour.

The stochastic UC crisis functionality depends on finding the optimal combination of generators that must be trusted to minimize the generation costs in relation to the power production over the scheduling horizon, thus, by considering the feasible fluctuations of the dissimilar vagueness sources [14]-[15].

5.1 Equality Constraints

Power balance constraints,

$$P_{G'i} + \sum_{i}^{NG} P_{w'i} = \sum PD + \sum_{i}^{P_l} \sum_{j=1}^{NG} \sum_{i=1}^{NG} p_{ij}$$
(1)

where, $P_{g,i}(t) \rightarrow \text{total demand at period } t$; $P_{g,i}(i,t) \rightarrow \text{power generated from unit } i \text{ with } t \text{ hour.}$

5.2 Inequality Constraints

Spinning reserve constraints,

$$P_{g,i,min} < P_{g,i} < P_{g,i,max} \tag{2}$$

where,

 $P_{g,i,max} \rightarrow maximum$ output power limit of the unit i at 't' hour.

 $\mathbf{R}(t) \rightarrow$ spinning reserve requirement of power system at 't' hour

Load demand=100MW

Figure 2 and 3 represents the power generation of wind 1 and 2 with respect to time (sec)





Fig. 2: Representation of wind 1 power generation



Fig. 3: Representation of wind 2 power generation



Fig. 4: Representation of Load power demand



Fig. 5: Representation of load power differences with respect to time(s)



Fig. 6: Representation of wind and load frequency

Figure 4 and 5 depicts the load power demand and the differences of W1 and W2 load power respectively.

Figure 6 shows the wind and load frequency based on the load demand in the various modes of generator. Frequency is measured using hertz with respect to time in seconds. The wind and load frequency lies between 49 Hz to 50 Hz respectively.



Fig. 7: Representation of mode selection-wind generator 1 frequency



Fig. 8: Representation of mode selection-wind generator 2 frequency

Figure 7 & 8 shows the different mode selection wind generator frequency based on the load demand.

Figure 9 shows the different mode selection based on the load frequency.

6 Cuckoo Search Algorithm

Cuckoo search algorithm is one of machine learning models [20,21,22]. The anticipated cuckoo search algorithm is enhanced when compared to the traditional Teaching-learning optimization. The conventional version provides the discovering of the alien eggs with the new solution by generating the population by subtracting the two hazardous nests. Subsequently, the learner phase optimization provides the generation of new solutions to avoid following the worst ones. In the anticipated method, conventional cuckoo search algorithms' second stage i.e., learner phase is provided to improve the recital of cuckoo eggs. Figure 10 explains the stages of the learner stage optimization as depicted by the proposed method. Thus, a



Fig. 9: Representation different mode selection based on load frequency

new nest is produced hazardously amongst the population with the FF (Fitness value) comparison.

The learner stages are combined with the alien egg discovery thus leading to follow the better eggs. It helps in converging the cuckoo eggs faster. Thus, this enhancement lets cuckoo eggs to lie with a local solution. Therefore, a hybrid probability has been engaged to avoid the cuckoo eggs to fall with the local optimal solution.

Simulating Cuckoo search algorithm for optimal allocation of wind related distributed generators:

Step 1: Generation of n host nests with an initial population.

Step 2: Generation of cuckoo is based on a randomly generated Levy flight. The cuckoo which is generated calculates the objective function and the load flow to determine the quality solution.

Step 3: Compute the fitness function (FF) or objective function.

Step 4: Randomly select a nest.

Step 5: The outcome relates to selection of novel nest is finest than to restore this solution.

Step 6: Yet again compute the objective function or fitness.

Step 7: The probability of these worst nests is discarded and novel nest are constructed.

Step 8: Once reaching the utmost iterations and fulfilling the stopping criterion, the outcomes of the cuckoo search with abridged objective function is



Fig. 10: Flow diagram of Cuckoo search algorithm

acquired.

To generate a new solution for X_i^{t+1} for the cuckoo present in the nest, a mathematical expression has been derived,

$$X_i^{t+1} = X_i + \alpha Levy(\delta)$$

where,

 $\alpha \rightarrow$ step size which is greater than 0.

Levy $\rightarrow t^- \; \delta$

 δ varies among 1 and 3 and this 'Levy' acquire infinite variance, with infinite mean.

6.1 Optimizing through Cuckoo Search

Determining the on and off generators is the issue of entering the circuit, the cost of utilizing the generators becomes minimized. Following constraints are listed below:

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- 1.On/off time minimization: Once the generator is turned on, it cannot be turned off for certain time. These are considered as T_{on} and T_{off} for generators.
- 2. The other constraint is the reserve capacity if one generator exists, other generators will no longer be available in the network load.
- 3. The systems overcapacity should not exceed a certain limit, and if overcapacity exists the possibility of turning off the generator may happen, hence overcapacity should be eliminated.

7 Artificial Bee Colony Optimization

Artificial bee colony (ABC) belongs to the swarm grounded optimization technique with the foraging scout bees and onlooker bee's concepts in hive as demonstrated in figure 11. Primarily, an onlooker bee flies over multi-dimensional regions to produce a random food source in a viable manner (finest solution). Secondly, onlooker bee is liable to fly for global food sources by haphazard manner in a limited region. The food source quality of each onlooker bee, (fitness value) is calculated with respect to onlooker bees.

The onlooker bee food source quality is comparatively lower than the subsequent bee in the hive or there is no significant development regarding its preceding food resource, next the food source was discarded by the onlooker bee or supplies memory and later transformed to scout bee. Scout bee hunts the novel realistic food source in a complete area (re-initialization). The scout bee's hive numbers at times limited to evade unintended re-initialization.

The search procedure is repetitive until the preselected iteration is accomplished. Various sequential stages for resolving OPF wind farm crisis incorporated power system with ABC- algorithm as:

Step (i): Initialization of onlooker bees For iteration count t = 0, an initial cluster of onlooker bees OBt i of size Nbee (total number of bees in the hive) is produced haphazardly inside the possible range with consistently dispersed random numbers.

Step (ii): Fitness evaluation (food source quantity) for every preliminary onlooker bee, load flow is accomplished and its fitness value f (food source quality) is calculated.

The ith particle total fuel cost at tth iteration along with k1, k2, k3, k4 and k5 \rightarrow constraint violations penalty factors, respectively. The penalty factors values are chosen, if there are any constraint violations corresponding to ineffective particle and fitness function value.

Step (iii): Foraging of onlooker bees- For next iteration t + 1, each onlooker bee randomly moves within its locality by adding a uniformly distributed random

number with each element of its present value.

Step (iv): Selection/allocation of scout bees. The onlooker bees fitness function values are compared with the existing one. If the fitness value is higher than the prevailing value (ft+1 i >ft i) and if the fitness value is relatively higher than other onlooker bees in hive (ft+1 i > ft+1 ii for ii = i and ii = 1, 2,..., N_{bee}), then the particular onlooker bee abandons the food source or stores in the memory and converts it to a scout bee. The scout bee SB_{*t*+1} 'i' searches feasible food sources in the complete region.

7.1 Optimizing through Artificial Bee Colony Algorithm

Continuous periods should be partitioned to discrete periods that the number of periods should be equal to all power units. The discrete amounts is chosen based on the power units' possibility to reach a specific amount of MW i.e., 450 MW (load supply constraint). So, the last unit lies between minimum and maximum generation. Hence, the sum of discrete values are considered in opposition to the maximum rate of the last generation unit and the minimum difference, the same discrete samples must be chosen.

8 Hybrid Artificial Bee Colony Algorithm Based On Cuckoo Search Algorithm

Artificial bee colony algorithm and Cuckoo search algorithm are the combination of swarm intelligence heuristics. Artificial bee colony algorithm shows relatively better convergence rate, although falls in local optimum solution. Cuckoo search algorithm, possess the general intelligent characteristics, and has a global convergence rate rapidly compared to particle swarm optimization and genetic algorithm. But at the same time, it does not produce effective local optimum, as well, with the performance crisis limitations like the convergence speed caused due to the deficient information sharing mechanism between populations of the individuals.

This paper shows the artificial bee colony's enhancement in the population update approach. It is sensed that Cuckoo search algorithms' Levy flight search strategy is of global search operator kind and escapes from local optimum. The individual's (based on inferior) elimination method to enhance quality advancements amongst the population as in figure 12. Similarly, the characteristics proposed by artificial bee colony algorithms with regards to the effectual information sharing method, defends Cuckoo search algorithm to a certain extent.

This investigation, introduces Levy flight search strategy to perform update operations source's location





Fig. 11: Flow diagram of Artificial Bee colony optimization algorithm



Fig. 12: Block diagram of the proposed CS-ABC optimization

for food sources along with the artificial bee colony algorithm to improvise random walk Levy flight to have direction changes and characteristic of flight, thus preventing the colony effectively from local attractors bound and enlarge search space as illustrated in figure 13.

Suppose,



Fig. 13: Flow diagram of the proposed HCSA-ABC technique.

j best $x \rightarrow$ location of colonies current best food source;

 $L(\lambda) \to$ random search hop path whose step size abide Levy distribution, length and uncertain direction;

 $\lambda \rightarrow$ scale parameter in which $\lambda = \beta + 1$;

 $\otimes \rightarrow$ vector operator.

The simulation procedure of hybrid artificial bee colony procedure is listed below:

- 1.Set initial factors, comprising of colony's maximum evolution generation, maximum number of iterations, number of colonies N, and colony's cluster data;
- 2. Initialize bee colony moderately (food source) X_0 (N), and analyze individuals fitness values amongst population.
- 3.Rotate (till loop condition is satisfied) or hop to (9);
- 4.To produce novel locations, foragers are employed to execute global search in relevance to formula (9), and choose good candidates relatively for better outcome of next generation with the merit-based selection method.
- 5.Based on selection strategy, Reserve/avoid the colony: Compute the probability for selection;
- 6.Based on i_p , the food sources locations are preferred by the onlookers, based on the greedy principles, update and select the location of the food sources in relevance to the good candidate selection in the next generation;
- 7.In order to generate new solutions, Scouts are re-initialized.
- 8.Record and Calculate the optimum outcome of the proposed optimization, then return to step (3);
- 9.Terminate the process.

Selection of mode 1 using the hybrid CS-ABC provides the best parameter. 234.8082, 237.6218 along with the best cost 156 as shown in figure 14.

Selection of mode 2 using the hybrid CS-ABC provides the best params 343.0486, 237.0144 along with the best cost 260 as shown in figure 13.

Selection of mode 3 using the hybrid CS-ABC provides the best params 237.1248, 280.9561 along with the best cost 416 as shown in figure 15.

 Table 1: CSA & ABC Optimization algorithm for total cost estimation

WG1(MW)	120
WG2(MW)	200
Total Load Power (MW)	102
Total cost(\$)	416000000

The total cost estimation of WG1 and WG2 based on total load power is given as \$416000000, with respect to 120 MW and 200 MW.



Fig. 14: Cost and power estimation of Hybrid optimization



Fig. 15: Cost and power estimation of Hybrid optimization

Case Study 1: IEEE 30-Bus

The components of the standard bus systems are 24 load buses, six generators and 41 branches. In the transmission lines, tap chargers such as (6, 9), (6, 10), (4, 12) and (27, 28) belongs to the four branch transformers. In the unique system, 3th, 10th and 24th buses are installed with three capacitors [16]-[17]. In a real power generation, reactive power generation limitations, transformer lap changers limitations, generator voltage



Fig. 16: Cost and power estimation of Hybrid optimization

and maximum apparent power flow of transmission lines are provided.

1.Case 1- Quadratic fuel cost function: The anticipated improved Cuckoo search algorithm presents better outcome than predictable Cuckoo search algorithm and other techniques as given by the mathematical outcomes based on Table II. The finest solution provided by the conventional methods is alike of the proposed methods. Even though, the proposed methods performance is efficient with respect to the standard deviation and the mean value in contrast to the conventional CSA. As well, the conventional CSA attains the global solution but lacks in the mean solution when the comparison is made on the literature.



Fig. 17: Cost estimation based on number of iterations.

2.Case 2- Multi-fuel cost function: Multi-fuel cost functions replaces the first and second generators' fuel cost in the testing case [19]-[23]. The multi-fuel cost functions co-efficient are given in figure 17. Mathematical results demonstrate that the proposed

system provides an enhanced solution with a better performance.



Fig. 18: Cost estimation based on number of iterations.

3.Case 3- Considering Fuel cost function: Generators fuel cost functions have been altered at the first and second buses [24]-[25] to the considering function of loading effective valve-point as in figure 18.

It is used to analyze the power dispatch of the unit unit system according to their desired constraints [26]. Depending on the wind power generation, the generator cost has been minimized [27]-[28]. The parameters for estimating the cost of the generator scheduling is illustrated as follows: the start up cost, fuel cost and the total cost. The power dispatch of the unit bus system based on the fuel cost and the start up cost for 24 hours is roughly given in the figure 15. The computation of total operating cost incurred, while the testing environment differs. Figure 16 shows the 24 hours load demand. Based on the objective function, the amount of power dispatching with generator allocation is executed [29].However, the combination of generator units is optimized by the proposed technique to minimize the cost for load demand conditions [30].

9 Simulation and Analysis

To verify the performance of the anticipated CS-ABC's, this investigation compares the proposed methodology with the existing classical ABC and other algorithms. The environment to carry out the testing is MATLAB simulation software, Intel CPU, Windows server 2008 OS, 16GB memory, finally with 2.0GHZ CPU frequency. The comparison contents of testing environment includes: convergence performance, iterative evolutionary curve along with the comparison of other existing works.

To carry out the recital of the anticipated CS-ABC in this work, simulation was performed with the Benchmark

 Table 2: Cost estimation based on the condition of wind generator 1 & 2

MODE	CONDITION	LOAD POWEP(MW)	COST(\$)
1	WG1	78	156000000
2	WG1 WG2	102	26000000
3	WG1-WG2	102	416000000
5	W01-W02	102	+10000000

 Table 3: Comparison of cost estimation using various algorithms

 [34]

S.No	Algorithms	Total cost
1	COA	78993.2
2	GA	79807.0/ 78988.8
3	HPSO	81118.3
4	AC-PSO	79010.1
5	Evolutionary method	79043
6	Hopfiels-SA	79114.6
7	LR	80766.0
8	HCSA-ABC	41600.0000

functions to calculate the algorithm's global optimization and to eliminate the prematurity capabilities. The simulation process comprises of subsequent parameter setting:

Size \rightarrow 60;

Maximum number of cycles \rightarrow 200;

Maximum number of iterations \rightarrow 2000;

Algorithm is run for 30 times arbitrarily.

From the illustrations, we can understand that the first hour utilizes the minimum operating cost of \$156000000at the load demand 78MW and the wind probability is 0.8269. The maximum operating cost of \$ 416000000 is attained from the 20th hour at the load demand 102MW and the wind probability is 1. Then the effectiveness of the anticipated system is contrast to the traditional techniques and other methodologies available in the literature. The total cost attained from the different techniques is described in Table II. The cost comparison is graphically illustrated in Figure 19, which clearly shows that the proposed method.

Effectively selects the optimal generating unit combinations [31]-[35] with a reduced cost compared to the other techniques.

The convergence performance is analyzed for 100 numbers of iterations [36]-[37]. Hence, it proven that the proposed method is highly effective over the existing methods in resolving the unit commitment crisis.

Figure 17 demonstrates the flow representation of the mode of operations of the generator in three cases.

Case i: Mode 1 = G1 on and G2 off

Case ii: Mode 2 = G1 off and G2 on

Case iii: Mode 3 = G1 on and G2 on

Based on the fitness value the best cost has been computed repeatedly.

Table III depicts various optimization techniques to estimate the cost of utility of power during wind generation.

10 Perspective

This paper is briefly analyzed about the hybrid technique which was proposed for solving the UCP in the system. The hybrid technique is the combination of the enhanced CS-ABC algorithm. These algorithms were utilized to diminish the operating cost of the unit system totally. Here, the three unit system was considered, which contains the wind power probability, system and generates unit constraints. The proposed method was implemented in Matlab/Simulink platform. Using the proposed algorithm, the optimized cost function of UCP are determined.

The performance of the proposed method is evaluated. The anticipated technique is used to provide the useful outcome, which helps in allocating the generators to meet the large scale constraints to assist for the large scale optimization crisis. The total cost is obtained using various existing algorithms such as COA, GA, HPSO, AC-PSO, Evolutionary methods, Hopfield-SA, LR are 78993.2, 79807.0, 81118.3, 79010.1, 79043, 79043, 79114.6, and 80766.0 respectively.

The projected hybrid CS-ABC algorithm outcomes with the lesser cost when compared to the other prevailing techniques, while performing validation on the three-unit test bus systems. The WG1 load power is 78MW and the total cost is about \$156000000, similarly WG2 load power is 102 MW and the total cost is about \$156000000. Hence the total cost is roughly about \$416000000. The outcome of the validation process shows better tradeoff between the proposed and the existing methods as described in the literature. The total best cost obtained using the HCSO-ABC is \$416000000. The future work of this proposed idea will be extended based on various optimization techniques to enhance the cost estimation strategy.

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