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On a Differential Equation with Caputo-Fabrizio Fractional Derivative of Order $1 < \beta \le 2$ and Application to Mass-Spring-Damper System

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Abstract: In this work, we investigate a linear differential equation involving Caputo-Fabrizio fractional derivative of order $1 < \beta \le 2$. Under some assumptions the considered equation is reduced to an integer order differential equation and solutions for different cases are obtained in explicit forms. We also prove a uniqueness of a solution of an initial value problem with a nonlinear differential equation containing the Caputo-Fabrizio derivative. Application of our result to the mass-spring-damper motion is also presented.

Keywords: Caputo-Fabrizio derivative, mass-spring-damper system, nonlinear differential equation, integral equation.

1 Introduction

It is well-known that the concept of derivative in applied mathematics, which describes the rate of change of a given function, is one of the most important concepts and it is used to develop mathematical models of many real life problems. Concept of fractional derivative, in particular, became popular, because it is more suitable for modeling certain real world problem than the regular derivative. Various type of fractional derivatives and their applications can be found in one of the most cited monographs, related to the fractional calculus [1].

Without neglecting the huge amount of work, devoted to theoretical development and applications of fractional derivatives to various branches of sciences, we directly pass to the recently introduced fractional derivative without singular kernel [2]. This new derivative has supplementary motivating properties, precisely, it can portray substance heterogeneities and configurations with different scales, which noticeably cannot be managed with the renowned local theories [3].

Properties of this new operator studied in [4] and various boundary problems for fractional heat equation involving this operator have been investigated in [5]. We would like to note several studies, where applications of the Caputo-Fabrizio operator were under discussion. Namely, in [6], application to nonlinear Fisher's reaction-diffusion equation, in [7], application to steady heat flow, in [8], application to Korteweg-de Vries-Bergers equation, in [9], [10], application to groundwater flow and in [11], application to the studying chaos on the Vallis model for El Nino were investigated. In [12], Caputo-Fabrizio fractional Nagumo equation with nonlinear diffusion and convection was also studied.

We would like to note that in [13], authors discussed coupled systems of time-fractional differential problems, by using Caputo-Fabrizio derivative.

We would like also to note work of Gomez-Aquilar et al [14], where modeling of mass-spring-damper system by fractional derivatives with and without a singular kernel is studied. Authors considered fractional differential equation with the Caputo-Fabrizio operator of order $1 < \beta \le 2$. In order to solve the problem, authors used Laplace transform and then solutions were obtained using numerical inverse Laplace transform. The same approach was used in [15], where the main object of investigation was diffusive transport with a fractional derivative without singular kernel. We have to note that in [14], authors considered only two particular cases, mass-spring and spring-damper motions.

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Another motivation for consideration of this type equations is connected with fractional wave and fractional diffusionwave equations, involving Caputo-Fabrizio derivative. Application of the Fourier method for studying direct and inverse problems for afore-mentioned equations depends on explicit form of solution to the equation, discussed in this work. Results of this work will be base for further investigations on this direction.

In [16], more general fractional derivative without singular kernel is introduced. Various applications of this derivative were discussed in [17]. Investigations differential equations with this new fractional derivative will give new impulse for further researches on direct and inverse problems for fractional order partial differential equations.

In the present work, we investigate differential equation with Caputo-Fabrizio fractional derivative of order $1 < \beta \le 2$. Reducing considered equation to the integer order differential equation, depending on various values of parameter, we have obtained explicit form of general solution for fixed β . Based on this result, we also proved a uniqueness of the solution to an initial value problem for nonlinear differential equation with Caputo-Fabrizio fractional derivative $1 < \beta \le 2$. At the end we investigated application of our result to the mass-spring-damper motion in general case, which is not considered in [14].

2 Investigation of linear differential equation

Consider the following linear fractional differential equation

$$_{CF}D_{at}^{\beta}u(t) - \lambda u(t) = f(t), \ t \ge a,$$
(1)

where $\beta = \alpha + 1$ such that $0 < \alpha \le 1$, $a \in (-\infty, t)$ and $_{CF}D_{at}^{\beta}u(t)$ is the Caputo-Fabrizio derivative defined as [2]

$$_{CF}D_{at}^{\beta}u(t) = \frac{1}{1-\alpha}\int_{a}^{t}u''(s)e^{-\frac{\alpha}{1-\alpha}(t-s)}ds.$$
(2)

We remind that in order to get equality $_{CF}D_{at}^{\alpha+1}u(t) = {}_{CF}D_{at}^{1+\alpha}u(t)$, we have to suppose that u'(0) = 0 (see [2]). Using definition (2), we rewrite equation (1) as follows

$$\frac{1}{1-\alpha}\int_{a}^{t}u''(s)e^{-\frac{\alpha}{1-\alpha}(t-s)}ds - \lambda u(t) = f(t)$$

or

$$\int_{a}^{b} u''(s)e^{\frac{\alpha}{1-\alpha}s}ds - \lambda(1-\alpha)u(t)e^{\frac{\alpha}{1-\alpha}t} = (1-\alpha)f(t)e^{\frac{\alpha}{1-\alpha}t}$$

Two times integration by parts yields

$$\frac{d}{dt} \left[u(t)e^{\frac{\alpha}{1-\alpha}t} \right] - \left(\frac{2\alpha}{1-\alpha} + \lambda(1-\alpha)\right) u(t)e^{\frac{\alpha}{1-\alpha}t} + \left(\frac{\alpha}{1-\alpha}\right)^2 \int_a^t u(s)e^{\frac{\alpha}{1-\alpha}s} ds = (1-\alpha)f(t)e^{\frac{\alpha}{1-\alpha}t} + u'(a) - u(a).$$
(3)

Introducing new function as

$$v(t) = u(t)e^{\frac{\alpha}{1-\alpha}t} \tag{4}$$

and differentiating (3) once, we get

$$''(t) - \mu_1 v'(t) + \mu_2 v(t) = g(t),$$
(5)

where

$$\mu_1 = \frac{2\alpha}{1-\alpha} + \lambda(1-\alpha), \ \mu_2 = \left(\frac{\alpha}{1-\alpha}\right)^2, \ g(t) = \left[(1-\alpha)f'(t) + \alpha f(t)\right]e^{\frac{\alpha}{1-\alpha}t}.$$
(6)

Depending on the sign of $A(\lambda) = 4\lambda\alpha + \lambda^2(1-\alpha)^2$ (discriminant of the corresponding auxiliary equation), we get different solutions to (5).

First, consider the case $A(\lambda) = 0$, which correspond to $\lambda = 0$ or $\lambda = -\frac{4\alpha}{(1-\alpha)^2}$.

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It is obvious that in this case, general solution can be written as

$$v(t) = e^{\mu_1 t} \left[c_1 - \int g(t) t e^{-(\mu_1/2)t} dt + t \left(c_2 + \int g(t) e^{-(\mu_1/2)t} dt \right) \right].$$

Considering designation (4), we get

$$u(t) = e^{(\lambda(1-\alpha)/2)t} \left[c_1 - \int g(t)t e^{-(\mu_1/2)t} dt + t \left(c_2 + \int g(t) e^{-(\mu_1/2)t} dt \right) \right].$$

or precisely,

$$u(t) = c_1 - \int g(t)t e^{-\frac{\alpha}{1-\alpha}t} dt + t \left(c_2 + \int g(t)e^{-\frac{\alpha}{1-\alpha}t} dt\right).$$

$$\tag{7}$$

for $\lambda = 0$ and

$$u(t) = e^{\frac{-2\alpha}{1-\alpha}t} \left[c_1 - \int g(t)t e^{\frac{\alpha}{1-\alpha}t} dt + t \left(c_2 + \int g(t)e^{\frac{\alpha}{1-\alpha}t} dt \right) \right]$$
(8)

for $\lambda = -\frac{4\alpha}{(1-\alpha)^2}$. Here c_1 and c_2 are arbitrary constants.

Now, consider the case $A(\lambda) > 0$, which can be achieved if we suppose that $\lambda \in \left(-\infty; -\frac{4\alpha}{(1-\alpha)^2}\right) \cup (0, +\infty)$. In this case, general solution to (5) will have the form

$$\begin{aligned} v(t) &= e^{\frac{\mu_1}{2}t} \left[c_3 e^{\frac{\sqrt{A(\lambda)}}{2}t} + c_4 e^{-\frac{\sqrt{A(\lambda)}}{2}t} + \frac{e^{\frac{\sqrt{A(\lambda)}}{2}t}}{\sqrt{A(\lambda)}} \int g(t) e^{-\frac{\mu_1 + \sqrt{A(\lambda)}}{2}t} dt - \frac{e^{-\frac{\sqrt{A(\lambda)}}{2}t}}{\sqrt{A(\lambda)}} \int g(t) e^{-\frac{\mu_1 - \sqrt{A(\lambda)}}{2}t} dt \right]. \end{aligned}$$

Solving for u(t) using (4), we obtain

$$u(t) = e^{\frac{\lambda(1-\alpha)}{2}t} \left[c_3 e^{\frac{\sqrt{A(\lambda)}}{2}t} + c_4 e^{-\frac{\sqrt{A(\lambda)}}{2}t} + \frac{e^{\frac{\sqrt{A(\lambda)}}{2}t}}{\sqrt{A(\lambda)}} \int g(t) e^{-\frac{\mu_1 + \sqrt{A(\lambda)}}{2}t} dt - \frac{e^{-\frac{\sqrt{A(\lambda)}}{2}t}}{\sqrt{A(\lambda)}} \int g(t) e^{-\frac{\mu_1 - \sqrt{A(\lambda)}}{2}t} dt \right].$$
(9)

Here c_3 and c_4 are arbitrary constants.

Finally, consider the case $A(\lambda) < 0$, which requires that $\lambda \in \left(-\frac{4\alpha}{(1-\alpha)^2}, 0\right)$. Using the expression of general solution, based on designation (4), we get

$$u(t) = e^{\frac{\lambda(1-\alpha)}{2}t} \left[\cos\left(\sqrt{-A(\lambda)t}\right) \left(c_5 - \sqrt{-A(\lambda)} \int g(t) \sin\left(\sqrt{-A(\lambda)t}\right) dt\right) + \\ + \sin\left(\sqrt{-A(\lambda)t}\right) \left(c_6 + \sqrt{-A(\lambda)} \int g(t) \cos\left(\sqrt{-A(\lambda)t}\right) dt\right) \right],$$
(10)

where c_5 and c_6 are arbitrary constants.

We formulate the obtained results as the following theorem:

Theorem 1. If $f(t) \in C[0, +\infty) \cap C^1(0, +\infty)$, $f''(t) \in L_1(a, +\infty)$ and f(a) = 0, then the general solution to equation (1) for fixed α can be represented

[*i*] by (7) for
$$\lambda = 0$$
 and by (8) for $\lambda = -\frac{4\alpha}{(1-\alpha)^2}$;
[*ii*] by (9) for $\lambda \in \left(-\infty; -\frac{4\alpha}{(1-\alpha)^2}\right) \cup (0, +\infty)$;
[*iii*] by (10) for $\lambda \in \left(-\frac{4\alpha}{(1-\alpha)^2}, 0\right)$.

Let us verify that, for instance, function, defined by (7) satisfies equation (1). For this aim from (7) we calculate u''(t):

$$u''(t) = g(t)e^{-\frac{\alpha}{1-\alpha}t}.$$

Considering representation of g(t) given by (6), we get

$$u''(t) = (1 - \alpha)f'(t) + \alpha f(t).$$

Therefore

$${}_{CF}D^{\beta}_{at}u(t) = \frac{1}{1-\alpha}\int_{a}^{b} \left[(1-\alpha)f'(s) + \alpha f(s) \right] e^{-\frac{\alpha}{1-\alpha}(t-s)} ds =$$
$$= e^{-\frac{\alpha}{1-\alpha}t}\int_{a}^{b} f'(s)e^{\frac{\alpha}{1-\alpha}s} ds + \frac{\alpha}{1-\alpha}e^{-\frac{\alpha}{1-\alpha}t}\int_{a}^{b} f(s)e^{\frac{\alpha}{1-\alpha}s} ds = f(t) - f(a)e^{-\frac{\alpha}{1-\alpha}t}.$$

Since, we imposed condition f(a) = 0, the latter equality proves our statement.

Remark. The following more general equation

$$a_{CF}D_{at}^{\alpha+1}u(t) + b_{CF}D_{at}^{\alpha}u(t) + cu(t) = h(t).$$
(11)

can be studied similarly as (1).

In fact, using the definition (2), after integration by parts, we get

$$\left(\frac{a}{\alpha}u'(t)+cu(t)\right)e^{\frac{\alpha}{1-\alpha}t}+\left(\frac{b}{1-\alpha}-\frac{1-\alpha}{\alpha}\right)\int_{0}^{t}u'(s)e^{\frac{\alpha}{1-\alpha}s}ds=h(t)e^{\frac{\alpha}{1-\alpha}t}+\frac{a}{\alpha}u'(0).$$

Using integration by parts again, the above equation can be rewritten in the following form

$$\frac{a}{\alpha}\frac{d}{dt}\left[u(t)e^{\frac{\alpha}{1-\alpha}t}\right] + \left[c - \frac{a}{1-\alpha} + \frac{b}{\alpha} - \left(\frac{1-\alpha}{\alpha}\right)^2\right]u(t)e^{\frac{\alpha}{1-\alpha}t} - \frac{1-\alpha}{\alpha}\int_0^t u(s)e^{\frac{\alpha}{1-\alpha}s}ds = h(t)e^{\frac{\alpha}{1-\alpha}t} + \frac{a}{\alpha}u'(0) + \left[\frac{b}{\alpha} - \left(\frac{1-\alpha}{\alpha}\right)^2\right]u(0)ds$$

Introducing a new function as $v(t) = u(t)e^{\frac{\alpha}{1-\alpha}t}$ and differentiating the above equation, we get

$$v''(t) + \left[\frac{b}{a} - \frac{\alpha}{1 - \alpha} + \frac{c\alpha}{a} - \frac{(1 - \alpha)^2}{a\alpha}\right]v'(t) + \frac{1 - \alpha}{a}v(t) = \left[h'(t) + \frac{\alpha}{1 - \alpha}h(t)\right]\frac{\alpha}{a}e^{\frac{\alpha}{1 - \alpha}t}.$$

This second order constant coefficient ordinary differential equation can be studied similarly as (5).

3 Nonlinear differential equation

In this section, we present a uniqueness result of an initial value problem containing the following nonlinear fractional order differential equation with the Caputo-Fabrizio derivative

$${}_{CF}D^{\beta}_{0t}u(t) = \varphi(t, u(t))$$

This uniqueness result is formulated in the following theorem.

Theorem 2.Let T > 0, $\beta = 1 + \alpha$ such that $0 < \alpha \le 1$ and $\varphi : [0,T] \times \mathbb{R} \to \mathbb{R}$ be a continuous function satisfying

$$|\varphi(t,s_1) - \varphi(t,s_2)| \le L_1 |s_1 - s_2|, \left| \frac{d\varphi(t,s_1)}{dt} - \frac{d\varphi(t,s_2)}{dt} \right| \le L_2 |s_1 - s_2|$$

for all $s_1, s_2 \in \mathbb{R}$ and some positive constants L_1, L_2 .

If $2T((1-\alpha)L_2+\alpha L_1) < 1$, then the initial value problem given by

$$_{CF}D_{0t}^{\alpha}u(t) = \varphi(t,u(t)), \ t \in [0,T],$$

$$\tag{12}$$

$$u(0) = U_0, \, u'(0) = U_1 \in \mathbb{R}; \tag{13}$$

has a unique solution on C[0,T].

*Proof.*Consider the operator $\mathcal{N} : C[0,T] \rightarrow C[0,T]$ defined by

$$\mathcal{N}u(t) = C_1 - I\overline{g(t)} + t\left(C_2 + I\frac{\overline{g(t)}}{t}\right) \quad \text{for all} \quad u \in C[0,T],$$

where $C_1 = U_0 + I\overline{g(t)}\Big|_{t=0}$, $C_1 = U_1 + I\frac{\overline{g(t)}}{t}\Big|_{t=0}$ and $I\overline{g(t)}$ is an anti-derivative of

$$\overline{g(t)} = \left[(1-\alpha) \frac{d\varphi(t, u(t))}{dt} + \alpha \varphi(t, u(t)) \right] t e^{-\frac{\alpha}{1-\alpha}t}$$

Finding a solution of (12)-(13) in C[0,T] in the form (7) is equivalent to finding a fixed point of the operator \mathcal{N} . Since $u_1, u_2 \in C[0,T]$, using the imposed hypothesis on $\varphi(\cdot)$ and $\frac{d\varphi(\cdot)}{dt}$ we then have

$$\begin{aligned} &|\mathcal{N}u_{1}(t) - \mathcal{N}u_{2}(t)| \leq \\ &2T \int \left[(1-\alpha) \left| \frac{d\varphi(t,u_{1}(t))}{dt} - \frac{d\varphi(t,u_{2}(t))}{dt} \right| + \alpha \left| \varphi(t,u_{1}(t)) - \varphi(t,u_{2}(t)) \right| \right] e^{-\frac{\alpha}{1-\alpha}t} dt \leq \\ &\leq 2T \left[(1-\alpha)L_{2} + \alpha L_{1} \right] \left| \left| u_{1} - u_{2} \right| \right| \end{aligned}$$

for all $t \in [0, T]$.

The above inequality shows that operator \mathcal{N} is a contraction, since $2T[(1-\alpha)L_2 + \alpha L_1] < 1$. The statement follows from Banach's fixed point theorem.

4 Application to mass-spring-damper motion

According to [14], [18], to be consistent with the dimensionality of the physical equation, an auxiliary parameter σ is introduced into the fractional temporal operator:

$$\frac{d}{dt} \to \frac{1}{\sigma^{1-\gamma}} \cdot \frac{d^{\gamma}}{dt^{\gamma}}, \ \frac{d^2}{dt^2} \to \frac{1}{\sigma^{2(1-\gamma)}} \cdot \frac{d^{2\gamma}}{dt^{2\gamma}}, \ m-1 < \gamma \le m, \ m=1,2,3,\dots$$

where γ represents the order of the fractional temporal operator and σ has the dimension of seconds. The auxiliary parameter σ is associated with the temporal components in the system (these components change the time constant of the system). Following this idea, authors of [14], introduced the equation of the mass-spring-damper system represented in Figure 1 as follows:

$$\frac{m}{\sigma^{2(1-\gamma)}} {}_{CF} D_{0t}^{2\gamma} x(t) + \frac{\delta}{\sigma^{1-\gamma}} {}_{CF} D_{0t}^{\gamma} x(t) + kx(t) = F(t), \ 0 < \gamma \le 1,$$
(14)

where m is the mass, δ is the damping coefficient, k is the spring constant and F(t) represents the forcing function.



Fig. 1: Mass-spring-damper system

Since, equation (14) cannot be written in the form (11), we investigate it separately.



Using definition [2]

$${}_{CF}D_{0t}^{\gamma}x(t) = \frac{1}{1-\gamma} \int_{0}^{t} x'(s) e^{-\frac{\gamma}{1-\gamma}(t-s)} ds,$$

we get

$${}_{CF}D_{0t}^{2\gamma}x(t) = {}_{CF}D_{0t}^{\gamma+\gamma}x(t) = {}_{CF}D_{0t}^{\gamma}\left(\frac{1}{1-\gamma}\int_{0}^{t}x'(s)e^{-\frac{\gamma}{1-\gamma}(t-s)}ds\right) =$$
$$= \frac{1}{(1-\gamma)^2}\int_{0}^{t}x'(s)\left[1-\frac{\gamma}{1-\gamma}(t-s)\right]e^{-\frac{\gamma}{1-\gamma}(t-s)}ds.$$

Substituting this expression for $_{CF}D_{0t}^{2\gamma}x(t)$ into equation (14), we get

$$\frac{1}{1-\gamma} \int_{0}^{t} x'(s) \left[\frac{m}{\sigma^{2(1-\gamma)}(1-\gamma)} - \frac{m\gamma}{\sigma^{2(1-\gamma)}(1-\gamma)^{2}}(t-s) + \frac{\delta}{\sigma^{1-\gamma}} \right] \times e^{-\frac{\gamma}{1-\gamma}(t-s)} ds + kx(t) = F(t).$$

Using integration by parts, after some evaluations, we get

 \times

$$\begin{aligned} x(t)e^{\frac{\gamma}{1-\gamma}t}\left[\frac{m}{\sigma^{2(1-\gamma)}(1-\gamma)} + \frac{\delta}{\sigma^{1-\gamma}} + k(1-\gamma)\right] - \\ -\frac{\gamma}{1-\gamma}\int_{0}^{t} x(s)\left[\frac{2m}{\sigma^{2(1-\gamma)}(1-\gamma)} - \frac{m\gamma}{\sigma^{2(1-\gamma)}(1-\gamma)^{2}}(t-s) + \frac{\delta}{\sigma^{1-\gamma}}\right]e^{\frac{\gamma}{1-\gamma}s}ds = \\ = (1-\gamma)F(t)e^{\frac{\gamma}{1-\gamma}t} + x(0)\left[\frac{m}{\sigma^{2(1-\gamma)}(1-\gamma)} - \frac{m\gamma}{\sigma^{2(1-\gamma)}(1-\gamma)^{2}}t + \frac{\delta}{\sigma^{1-\gamma}}\right]. \end{aligned}$$

Introducing new function as $y(t) = x(t)e^{\frac{\gamma}{1-\gamma}t}$, we obtain second kind Volterra integral equation

$$y(t) + \int_{0}^{t} y(s) [A + B(t - s)] ds = F_1(t),$$

if $\frac{m}{\sigma^{2(1-\gamma)}(1-\gamma)} + \frac{\delta}{\sigma^{1-\gamma}} + k(1-\gamma) \neq 0$, which is uniquely solvable ([19], page 110). Here

$$A = \frac{\gamma \left(2m + \delta(1-\gamma)\sigma^{1-\gamma}\right)}{(1-\gamma)^2 \left(m + \delta\sigma^{1-\gamma} + k(1-\gamma)\sigma^{2(1-\gamma)}\right)},$$

$$B = -\frac{m\gamma^2}{(1-\gamma)^3 \left(m + \delta\sigma^{1-\gamma} + k(1-\gamma)\sigma^{2(1-\gamma)}\right)},$$

$$F_1(t) = \frac{\sigma^{2(1-\gamma)}}{m + \delta\sigma^{1-\gamma} + k(1-\gamma)^2\sigma^{2(1-\gamma)}} \times \left[(1-\gamma)F(t)e^{\frac{\gamma}{1-\gamma}t} + \frac{F(0)}{k}\left(\frac{m + \delta(1-\gamma)\sigma^{1-\gamma}}{\sigma^{2(1-\gamma)}} - \frac{m\gamma}{\sigma^{2(1-\gamma)}}t\right)\right]$$

5 Conclusion

In the present work, we investigate a linear differential equation involving Caputo-Fabrizio fractional derivative of order $1 < \beta \le 2$. We have found explicit form of solutions in various cases reducing it to the integer order differential equation. Statement on a uniqueness of a solution of an initial value problem with a nonlinear differential equation containing the Caputo-Fabrizio derivative is proved. Application of our result to the mass-spring-damper motion is also presented.

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