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Exponential Parameterization and ε -Uniformly Sampled Reduced Data

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Abstract: We study the quality of piecewise-quadratic Lagrange interpolation for nonparametric data based on ε -uniform sampling and different forms of exponential parameterization. Surprisingly, it turns out that there is a sharp discontinuity in the quality of interpolation: exponential parameterization performs no better than a blind uniform guess, except for the case of scaled cumulative chord, which matches parametric interpolation.

Keywords: Curve interpolation, numerical analysis, asymptotics, exponential parameterization, different samplings

1 Introduction

A list of m + 1 points $Q_m = (q_0, q_1, \dots, q_m)$ in Euclidean *n*-space E^n is obtained by sampling an unknown but sufficiently smooth and regular curve $\gamma : [0,1] \to E^n$ at $0 = t_0 < t_1 < t_2 < \dots < t_m = 1$, where t_1, t_2, \dots, t_{m-1} are also unknown. Here $q_i = \gamma(t_i)$ for $0 \le i \le m$, and we have a problem of *nonparametric interpolation* (see e.g. [1]). More precisely, the task is to estimate the unknown curve γ by a curve $\hat{\gamma} : [0,1] \to E^m$ such that $\hat{\gamma}(\hat{t}_i) = q_i$ for all $i = 0, 1, \dots, m$, where $\hat{\gamma}$ and the \hat{t}_i are computed from q_0, q_1, \dots, q_m . To emphasize that the $\{t_i\}_{i=0}^m$ are not given, we call $\{q_i\}_{i=0}^m$ the *nonparametric data*. Applications of nonparametric data interpolation in computer vision, computer graphics, engineering or physics can be found in e.g. [2], [3], [4] or [5].

By contrast, when both $\{t_i\}_{i=0}^m$ and $\{q_i\}_{i=0}^m$ are known, the curve γ can be estimated using standard methods for *parametric interpolation*, such as piecewise *r*-degree Lagrange interpolation. So our task can be performed by a parametric interpolant using estimates \hat{t}_i of the t_i . For this to be useful, we also need to prove results about the quality of the corresponding estimate $\hat{\gamma}$ of the unknown curve γ . Such results will depend on the $\{t_i\}_{i=0}^m$. For instance in the trivial case, when the $\{t_i\}_{i=0}^m$ are chosen uniformly along [0, 1] (or otherwise actually known), then $\hat{\gamma}$ is just a parametric interpolant whose properties are known from classical results. Indeed, for $\{t_i\}_{i=0}^m$ satisfying the *admissibility condition*:

$$\lim_{m \to \infty} \delta_m = 0, \quad \text{where} \quad \delta_m = \max_{0 \le i \le m-1} (t_{i+1} - t_i), \quad (1)$$

there is the well-known result [6]:

Theorem 1. Let $\gamma: [0,1] \to E^n$ be C^{r+1} , where $r \ge 0$ and be *regular* in the sense that $\dot{\gamma}$ is nowhere **0**. Then piecewise *r*-degree Lagrange interpolation yields a sharp estimate:

$$\hat{\gamma}(t) = \gamma(t) + O(\delta_m^{r+1}) \tag{2}$$

uniformly in $t \in [0, 1]$. \Box

The asymptotic estimate in (2) is sharp, i.e. there exist $\gamma \in C^{r+1}$ and admissible sampling $\{t_i\}_{i=0}^m$, for which the convergence order established in (2) cannot be improved.

Remark 1. Recall that, for a family $F_{\delta_m} : [0,T] \to E^n$ with $0 < T < \infty$ (e.g. for $F_{\delta_m} = \tilde{\gamma}_r - \gamma$ and T = 1; here $\tilde{\gamma}_r$ depends on δ_m) we write $F_{\delta_m} = O(\delta_m^{\alpha})$ when $\|F_{\delta_m}\|_{\infty} = O(\delta_m^{\alpha})$, where $\|F_{\delta_m}\|_{\infty} = \sup_{t \in [0,T]} \|F_{\delta_m}(t)\|$ and $\|\cdot\|$ denotes the Euclidean norm. The latter holds if there exists constant K > 0 such that for some $\bar{\delta} > 0$ we have $\|F_{\delta_m}\| \le K \delta_m^{\alpha}$, for all $\delta_m \in (0, \bar{\delta})$ and all $t \in [0, T]$. Here Kdepends on γ and on each sampling $\{t_i\}_{i=0}^m$. Evidently as interval [0, T] is compact once F_{δ_m} is continuous we have $\|F_{\delta_m}\|_{\infty} = \max_{t \in [0, T]} \|F_{\delta_m}(t)\|$. \Box

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In our situation, where less information is available about the distribution of the $\{t_i\}_{i=0}^m$, it is natural that $\hat{\gamma}$ should be a lower-quality estimate of γ .

Definition 1. We say that the $\{t_i\}_{i=0}^m$ is sampled more-orless uniformly (see e.g. [3], [7] or [8]) when, for some $\beta \in (0, 1]$, and all sufficiently large m and all i = 1, 2, ..., m, we have:

$$\beta \, \delta_m \le t_i - t_{i-1} \le \delta_m. \tag{3}$$

Equivalently

$$\frac{\beta_0}{m} \le t_i - t_{i-1} \le \frac{\beta_1}{m},\tag{4}$$

for some $0 < \beta_0 \leq \beta_1$, sufficiently large *m* and all i = 1, 2, ..., m. Necessarily $\beta_1 \geq 1$, by summing the inequalities. \Box

Definition 2. Given $\varepsilon > 0$, we say that $\{t_i\}_{i=0}^m$ is sampled ε -uniformly (see e.g. [9]) when, for some C^{∞} diffeomorphism $\phi : [0,1] \rightarrow [0,1]$, sufficiently large m and all $0 \le i \le m$,

$$t_i = \phi(\frac{i}{m}) + O(\frac{1}{m^{1+\varepsilon}}). \tag{5}$$

This is more restrictive than the condition enforcing $\{t_i\}_{i=0}^m$ to be distributed more-or-less uniformly. Since by (1), $m\delta_m \ge 1$ and thus the second term in (5) reads as $O(\delta_m^{1+\varepsilon})$. \Box

Again both ϕ and the $O(\delta_m^{1+\varepsilon})$ term depend on the ε -uniform sampling. The most common method to estimate the unknown knots $\{t_i\}_{i=0}^m$ from the nonparametric data is to use some form of *exponential parametrization* (see e.g. [4]) in the following sense:

Definition 3. Choose $\lambda \in [0,1]$ and set $\hat{t}_0 = 0$. Then, inductively, for $1 \le i \le m$, set

$$\hat{t}_i = \hat{t}_{i-1} + \|q_i - q_{i-1}\|^{\lambda}.$$
(6)

Finally, set normalized $\tilde{t}_i = \hat{t}_i/\hat{t}_m$, for $0 \le t \le m$. In order to ensure $\tilde{t}_i < \tilde{t}_{i+1}$ (and also that $\hat{t}_i < \hat{t}_{i+1}$) we assume that $q_i \ne q_{i+1}$. \Box

The choice $\lambda = 0$ yields $\hat{t}_i = i$, corresponding to a blind uniform guess, taking no account of the spread of interpolation points $\{q_i\}_{i=0}^m$ (see [9]).

Theorem 2. Let γ be C^3 and let the unknown $\{t_i\}_{i=0}^m$ be sampled ε -uniformly, where $\varepsilon > 0$. If $\hat{\gamma}$ is constructed using piecewise-quadratic Lagrange interpolation based on $\lambda = 0$ (blind uniform guess) then, for piecewise- C^{∞} reparameterization $\psi : [0, 1] \rightarrow [0, 1]$ (computed from data Q_m), we have sharp asymptotic estimate over [0, 1]:

$$(\hat{\gamma} \circ \psi)(t) = \gamma(t) + O(\delta_m^{\min\{3,1+2\varepsilon\}}),$$

for the trajectory approximation. \Box

Note that in case of reduced data Q_m for F_{δ_m} (see Remark 1) we substitute $F_{\delta_m} = \hat{\gamma}_2 \circ \psi - \gamma$.

At the other extreme we have a more informative estimate of the $\{t_i\}_{i=0}^{m}$, namely the scaled *cumulative chord parameterization* given by exponential parameterization with $\lambda = 1$. Indeed, we have the following (see [10]):

Theorem 3. Let γ be C^3 and let the unknown t_i be sampled ε -uniformly, where $\varepsilon > 0$. If $\hat{\gamma}$ is constructed using piecewise-quadratic Lagrange interpolation based on $\lambda = 1$ (scaled cumulative chord) then, for piecewise- C^{∞} reparameterization $\psi : [0,1] \rightarrow [0,1]$ (computed from data Q_m), the sharp asymptotic estimate:

$$(\hat{\gamma} \circ \psi)(t) = \gamma(t) + O(\delta_m^3) \tag{7}$$

follows for $t \in [0, 1]$. In fact (7) holds also for arbitrary admissible samplings (1). \Box

So scaled cumulative chord parametrization performs as well as the parametric interpolant obtained by taking r = 2 in Th. 1, at least in terms of asymptotic and modulo the reparameterization ψ . On the other hand, the asymptotics for the blind uniform guess of Th. 2 are not nearly so good for small values of ε . Between these extremes, one might expect a steady increase in the exponent of δ_m (or of 1/m) as λ increases from 0 to 1. Surprisingly this does not happen, as shown in Th. 4 below, which *is the main result of this paper*:

Theorem 4. Let γ be C^4 and let the unknown t_i be sampled ε -uniformly where $\varepsilon > 0$. If $\hat{\gamma}$ is constructed using piecewise-quadratic Lagrange interpolation based on $\lambda \in (0,1)$ then, for some piecewise-quadratic- C^{∞} reparameterization $\psi : [0,1] \rightarrow [0,1]$ (computed from data Q_m):

$$(\hat{\gamma} \circ \psi)(t) = \gamma(t) + O(\delta_m^{\min\{3, 1+2\varepsilon\}}) \tag{8}$$

holds for $t \in [0, 1]$. \Box

A similar phenomenon is discovered in [11] for more-or-less uniform samplings, where $(\hat{\gamma} \circ \psi)(t) = \gamma(t) + O(\delta_m)$, for $\lambda \in [0,1)$ and $(\hat{\gamma} \circ \psi)(t) = \gamma(t) + O(\delta_m^3)$, for either $\lambda = 1$, or a uniform sampling and $\lambda \in [0,1)$.

This paper proves Th. 4 and its sharpness in Ex. 2. The general framework used here, has some similarities to [11] which applies only to such more-or-less uniformly sampled curves for which ψ : $[0,1] \rightarrow [0,1]$ is a reparameterization. Our proof for ε -uniform samplings is different and also ensures that $\dot{\psi} > 0$ holds for curves $\gamma \in C^3$. Also, for the more restrictive case of samplings (5) we achieved a better trajectory approximation than for the general class of more-our-less uniform samplings established in [11]. As well as the analysis of the Ex. 2 the numerical tests confirm the sharpness of the asymptotics from Th. 4.

35

2 Exponential parameterization for ε -uniform samplings

The following example is used later in proving Th. 4.

Example 1. a) An inspection reveals that each ε -uniform sampling is also more-or-less uniform. Indeed by Taylor's Th. and (5) we have:

$$t_{i+1} - t_i = \dot{\phi}(\frac{iT}{m})\frac{T}{m} + O(\frac{1}{m^{1+\varepsilon}}) + O(\frac{1}{m^2}) = \dot{\phi}(\frac{iT}{m})\frac{T}{m} + O(\frac{1}{m^{\min\{2,1+\varepsilon\}}}).$$
(9)

Since $\varepsilon > 0$ we have $m^{-\min\{2,1+\varepsilon\}} < m^{-1}$ and thus by boundedness of continuous $\dot{\phi}$ over compact [0,1], there exist constants $0 < K_l < K_u$ such that:

$$\frac{K_l}{m} \le t_{i+1} - t_i \le \frac{K_u}{m}.$$

So ε -uniformity implies more-or-less uniformity (however not conversely).

b) By (5) and Taylor's expansion (applied to ϕ at t = i/m) we have for each $\varepsilon > 0$ the following (with j = 0, 1):

$$t_{i+j+1} - t_{i+j} = \dot{\phi}\left(\frac{i}{m}\right)\frac{1}{m} + O\left(\frac{1}{m^{\min\{2,1+\varepsilon\}}}\right).$$
(10)

Combining (10) with $0 < 1/m \le \delta_m$ (as $\sum_{i=0}^m (t_{i+1} - t_i) = 1$ and thus $m\delta_m \ge 1$) gives:

$$t_{i+2} - t_{i+1} = t_{i+1} - t_i + O(\delta_m^{\min\{2,1+\varepsilon\}}).$$
(11)

For uniform sampling $\{t_i\}_{i=0}^m$ we have $t_{i+2} - t_{i+1} = t_{i+1} - t_i = \delta = 1/m$. \Box

We pass now to the proof of Th. 4.

Proof. As we see later in Remark 5 it is sufficient to prove the asymptotics (8) for both unnormalized knots $\{\hat{t}_i\}_{i=0}^m$ (see (6)) and shifted according to $\hat{t} - \hat{t}_i$. For simplicity the knots in (6) and (12) use the same notation. Let $\psi_i : I_i = [t_i, t_{i+2}] \rightarrow \hat{I}_i = [\hat{t}_i, \hat{t}_{i+2}]$ be the quadratic polynomial satisfying interpolation conditions $\psi_i(t_{i+j}) = \hat{t}_{i+j}$, with j = 0, 1, 2, where

$$\hat{t}_{i} = 0, \quad \hat{t}_{i+1} = \|q_{i+1} - q_{i}\|^{\lambda},$$
$$\hat{t}_{i+2} = \hat{t}_{i+1} + \|q_{i+2} - q_{i+1}\|^{\lambda}.$$
(12)

The track-sum of $\{\psi_i\}_{i=0}^{m-2}$ (for $i = 0, 2, 4, \dots, m-2$) defines a continuous piecewise- C^{∞} mapping $\psi: [0,1] \to [0,\hat{T}]$, where $\hat{T} = \hat{t}_m$.

The proof of Th. 4 is divided into five steps:

2.1 Step 1: proof that ψ is a reparameterization

We show first that ψ_i is asymptotically a reparameterization of I_i into \hat{I}_i , for arbitrary $\varepsilon > 0$ and $\lambda \in [0,1]$. This is proved here under the weaker assumption that $\gamma \in C^3([0,1])$ - recall that by [11], for either $\lambda = 1$ and $\{t_i\}_{i=0}^m$ merely admissible (1) or $\{t_i\}_{i=0}^m$ uniform and $\lambda \in [0,1)$, the quadratic ψ_i yields also asymptotically a reparameterization. This is not always true for arbitrary more-or-less uniform samplings (3) and $\lambda \in [0,1)$ as both shown also in [11].

Newton's Interpolation Formula for divided differences $\psi_i[\cdot]$, $\psi_i[\cdot, \cdot]$ and $\psi_i[\cdot, \cdot, \cdot]$ (see [6]) gives over each I_i :

$$\psi_{i}(t) = \psi_{i}[t_{i}] + \psi_{i}[t_{i}, t_{i+1}](t - t_{i}) + \psi_{i}[t_{i}, t_{i+1}, t_{i+2}](t - t_{i})(t - t_{i+1}), \psi_{i}^{(1)}(t) = \psi_{i}[t_{i}, t_{i+1}] + (2t - t_{i+1} - t_{i})\psi_{i}[t_{i}, t_{i+1}, t_{i+2}], \psi_{i}^{(2)}(t) = 2\psi_{i}[t_{i}, t_{i+1}, t_{i+2}].$$
(13)

For ψ_i to be a reparameterization it suffices to show that $\psi_i^{(1)} > 0$ over I_i . For the latter, as $\psi_i^{(1)}(t)$ is linear, it is sufficient to demonstrate that both $\psi_i^{(1)}(t_i) > 0$ and $\psi_i^{(1)}(t_{i+2}) > 0$ hold asymptotically. In doing so, by (13) a simple inspection reveals:

$$\begin{split} \psi_i^{(1)}(t_i) &= \psi_i[t_i, t_{i+1}] + (t_i - t_{i+1})\psi_i[t_i, t_{i+1}, t_{i+2}], \\ \psi_i^{(1)}(t_{i+2}) &= \psi_i[t_i, t_{i+1}] \\ &+ ((t_{i+2} - t_{i+1}) + (t_{i+2} - t_i))\psi_i[t_i, t_{i+1}, t_{i+2}]. \end{split}$$
(14)

To show inequality $\psi_i^{(1)}(t_i) > 0$, recall (see [11]) that $\gamma \in C^3([0,T])$ with formula (1) leads to:

$$\begin{split} \Psi_{i}[t_{i}, t_{i+1}] &= (t_{i+1} - t_{i})^{-1+\lambda} + O((t_{i+1} - t_{i})^{1+\lambda}) \\ &= (t_{i+1} - t_{i})^{-1+\lambda} + O(\delta_{m}^{1+\lambda}), \\ \Psi_{i}[t_{i+1}, t_{i+2}] &= (t_{i+2} - t_{i+1})^{-1+\lambda} + O((t_{i+2} - t_{i+1})^{1+\lambda}) \\ &= (t_{i+2} - t_{i+1})^{-1+\lambda} + O(\delta_{m}^{1+\lambda}), \\ \Psi_{i}[t_{i}, t_{i+1}, t_{i+2}] &= \frac{(t_{i+2} - t_{i+1})^{-1+\lambda} - (t_{i+1} - t_{i})^{-1+\lambda}}{t_{i+2} - t_{i}} \\ &+ O(\delta_{m}^{\lambda}). \end{split}$$
(15)

We examine now the asymptotics of the second term of $\psi_i^{(1)}(t_i)$ in (14) (denoted below as J_i) by using the definition of the second divided differences $\psi_i[t_i, t_{i+1}, t_{i+2}]$:

$$J_{i} = -(t_{i+1} - t_{i})\psi_{i}[t_{i}, t_{i+1}, t_{i+2}]$$

= $-\frac{t_{i+1} - t_{i}}{t_{i+2} - t_{i}}(\psi_{i}[t_{i+1}, t_{i+2}] - \psi_{i}[t_{i}, t_{i+1}]).$ (16)

Combining (16) with $0 < (t_{i+1} - t_i)(t_{i+2} - t_i)^{-1} < 1$ (a term of order O(1) with non vanishing asymptotic constant) and with (15) and finally coupling it with (5) (thus yielding (11)) leads to:

$$\begin{aligned} J_{i} &= O(1)[(t_{i+2} - t_{i+1})^{-1+\lambda} - (t_{i+1} - t_{i})^{-1+\lambda} + O(\delta_{m}^{1+\lambda})] \\ &= O(1)[((t_{i+1} - t_{i}) + O(\delta_{m}^{\min\{2,1+\varepsilon\}}))^{-1+\lambda} \\ &- (t_{i+1} - t_{i})^{-1+\lambda} + O(\delta_{m}^{1+\lambda})] \\ &= O(1) \\ &\cdot [(t_{i+1} - t_{i})^{-1+\lambda} (1 + (t_{i+1} - t_{i})^{-1} O(\delta_{m}^{\min\{2,1+\varepsilon\}}))^{-1+\lambda} \\ &- (t_{i+1} - t_{i})^{-1+\lambda} + O(\delta_{m}^{1+\lambda})]. \end{aligned}$$

As any ε -uniform sampling is also more-or-less uniform (see Ex. 1) the following holds $(t_{i+1} - t_i)^{-1} = O(\delta_m^{-1})$ and hence:

$$J_{i} = O(1)[(t_{i+1} - t_{i})^{-1+\lambda} (1 + O(\delta_{m}^{\min\{1,\varepsilon\}}))^{-1+\lambda} - (t_{i+1} - t_{i})^{-1+\lambda} + O(\delta_{m}^{1+\lambda})].$$
(17)

By Taylor's expansion we obtain that $(1+x)^{-1+\lambda} = 1 + (-1+\lambda)(1+\xi)^{-(2-\lambda)}x$, where $|\xi| \le |x|$. Setting $x = O(\delta_m^{\min\{1,\varepsilon\}})$ and taking into account that $2-\lambda > 0$, we have $(1+\xi)^{-2+\lambda} = O(1)$ (as ξ is asymptotically separated from -1). Consequently, $(1+O(\delta_m^{\min\{1,\varepsilon\}}))^{-1+\lambda} = 1 + O(\delta_m^{\min\{1,\varepsilon\}})$, which in turn coupled with (17) gives (with the term O(1) having non-vanishing asymptotic constant):

$$\begin{split} J_{i} &= O(1)[(t_{i+1} - t_{i})^{-1+\lambda} (1 + O(\delta_{m}^{\min\{1,\varepsilon\}})) \\ &- (t_{i+1} - t_{i})^{-1+\lambda} + O(\delta_{m}^{1+\lambda})] \\ &= O(1)[O(\delta_{m}^{\min\{\lambda, -1+\lambda+\varepsilon\}})) + O(\delta_{m}^{1+\lambda})] \\ &= O(\delta_{m}^{\min\{\lambda, -1+\lambda+\varepsilon, 1+\lambda\}}) \\ &= O(\delta_{m}^{\min\{\lambda, -1+\lambda+\varepsilon\}}) \\ &= \begin{cases} O(\delta_{m}^{-1+\lambda+\varepsilon}), & \text{for } 0 < \varepsilon \leq 1; \\ O(\delta_{m}^{\lambda}), & \text{for } \varepsilon > 1. \end{cases} \end{split}$$
(18)

Combining (18) with (14), (15), (16) and $\lambda \in [0, 1)$ results in:

$$\begin{aligned} \psi_i^{(1)}(t_i) \\ &= (t_{i+1} - t_i)^{-1+\lambda} + O(\delta_m^{1+\lambda}) + O(\delta_m^{\min\{\lambda, -1+\lambda+\varepsilon\}}) \\ &= (t_{i+1} - t_i)^{-1+\lambda} + O(\delta_m^{\min\{\lambda, -1+\lambda+\varepsilon\}}) > 0 \end{aligned}$$
(19)

asymptotically (as $-1 + \lambda < \min\{\lambda, -1 + \lambda + \varepsilon\}$, for $\varepsilon > 0$ and $1 + \lambda > \min\{\lambda, -1 + \lambda + \varepsilon\}$). By (14) as $0 < [(t_{i+2} - t_i) + (t_{i+2} - t_{i+1})](t_{i+2} - t_i)^{-1} < 2$ the above

2.2 Step 2: difference between interpolant $\hat{\gamma}_2$ and curve γ

In order to accelerate the linear convergence rates for trajectory estimation from [11] established for more-or-less uniform samplings (3), $\lambda \in [0,1)$ and any regular curve $\gamma \in C^3([0,1])$ we assume from now on that $\gamma \in C^4([0,1])$.

Let the interpolant $\hat{\gamma}_2(\hat{t}_i) = q_i$ be defined as a tracksum of quadratics $\hat{\gamma}_{2,i} : [\hat{t}_i, \hat{t}_{i+2}] \to E^n$ satisfying $\hat{\gamma}_{2,i}(\hat{t}_{i+j}) = q_{i+j}$, for j = 0, 1, 2 and i = 2k, where $k = 0, 1, \dots, m/2$. The difference between the interpolant $\hat{\gamma} = \hat{\gamma}_2$ and the unknown curve γ over each I_i (and thus over [0, 1] since mapping ψ_i is a reparameterization - see *Step 1*) reads as:

$$f_i(t) = (\hat{\gamma}_{2,i} \circ \psi_i)(t) - \gamma(t).$$
(20)

Thus as $\hat{\gamma}_{2,i}(\hat{t}_{i+j}) = (\hat{\gamma}_{2,i} \circ \psi)(t_{i+j})$ (for j = 0, 1, 2) we arrive at:

$$f_i(t_{i+j}) = \mathbf{0}.\tag{21}$$

Recall now Hadamard's Lemma (see [12]; Part 1, Lemma 2.1):

Lemma 1. Let $f : [a,b] \to E^n$ be of class C^l , where $l \ge 1$ and assume that $f(t_0) = \mathbf{0}$, for some $t_0 \in (a,b)$. Then there exists a C^{l-1} function $g : [a,b] \to E^n$ for which we have $f(t) = (t-t_0)g(t)$. In addition $g(t) = O(\frac{df}{dt})$. \Box

In order to construct the function h(t) it suffices to note that f(t) = F(1) - F(0), where $F(u) = f(tu + (1 - u)t_0)$. Thus by the Fundamental Th. of Calculus we obtain the following:

 $f(t) = \int_0^1 F'_u(u) du = (t - t_0) \int_0^1 f'(tu + (1 - u)t_0) du.$

An inspection of the proof of Lemma 1 leads to its generalization with f having multiple zeros $t_0 < t_1 < \cdots < t_k$. Indeed upon k + 1 applications of Lemma 1 we obtain:

$$f(t) = (t - t_0)(t - t_1)\dots(t - t_k)h(t),$$
(22)

where *h* is of class $C^{l-(k+1)}$ and $h = O(\frac{d^{k+1}f}{dt^{k+1}})$.

Consequently, by Hadamard's Lemma, for each $t \in I_i$ we have:

$$f_i(t) = (t - t_i)(t - t_{i+1})(t - t_{i+2})g_i(t), \qquad (23)$$

where $g_i(t) = O(f_i^{(3)}(t))$, uniformly over I_i . Furthermore

$$f_i(t) = O(\delta_m^3) \cdot O\left((\hat{\gamma}_{2,i} \circ \psi_i)^{(3)}(t) - \gamma^{(3)}(t) \right).$$
(24)

Using the chain rule for the composition of two quadratics $\hat{\gamma}_{2,i} \circ \psi_i$ combined with $\gamma \in C^4([0,1]), (24)$ gives¹:

$$f_{i}(t) = O(\delta_{m}^{3}) \\ \cdot \left(O(\hat{\gamma}_{2,i}''(\hat{t})) \cdot O(\psi_{i}^{(1)}(t)) \cdot O(\psi_{i}^{(2)}(t)) + O(1) \right), (25)$$

for $t \in I_i$ and $\hat{t} \in \hat{I}_i$, where $\hat{\gamma}_{2,i}''$ denotes the second derivative of $\hat{\gamma}_{2,i}$ with respect to $\hat{t} = \psi_i(t) \in \hat{I}_i$. In order to examine the asymptotics of (25) it suffices to analyze now the asymptotics of three involved terms, namely $O(\hat{\gamma}_{2,i}'(\hat{t}))$, $O(\psi_i^{(1)}(t))$ and $O(\psi_i^{(2)}(t))$. As to be shown, the respective asymptotic orders of the above three terms are independent from I_i .

2.3 Step 3: asymptotic orders of $\Psi^{(k)}(t)$, k = 1, 2

First we discuss the asymptotics of $O(\psi_i^{(1)}(t))$ and $O(\psi_i^{(2)}(t))$, given $\lambda \in [0,1)$ and (5). In doing so it suffices to analyze asymptotic orders of two divided differences $\psi_i[t_i, t_{i+1}]$ and $\psi_i[t_i, t_{i+1}, t_{i+2}]$, respectively.

By Taylor's Th. and $\gamma \in C^4([0,T])$, for each $t \in I_i$ we have:

$$\gamma(t) = \sum_{k=0}^{3} \frac{\gamma^{(k)}(t_i)}{k!} (t - t_i)^k + O\left((t - t_i)^4\right).$$
(26)

Furthermore by (12) the following holds:

$$\psi_i[t_i, t_{i+1}] = \frac{\psi_i(t_{i+1}) - \psi_i(t_i)}{t_{i+1} - t_i} = \frac{\left(\|\gamma(t_{i+1}) - \gamma(t_i)\|^2\right)^{\lambda/2}}{t_{i+1} - t_i}.$$

Since γ is regular (i.e. $\dot{\gamma} \neq \mathbf{0}$), it can be reparameterized to the arc-length parameterization with $\|\gamma^{(1)}(t)\| \equiv 1$ over [0,1] (see e.g. [14]). Such reparameterization does not influence the asymptotics in question. Therefore as $h(t) = \langle \gamma^{(1)}(t) | \gamma^{(1)}(t) \rangle \equiv 1$ over $t \in [0,1]$, (here $\langle \cdot | \cdot \rangle$ denotes a standard dot product in E^n) upon differentiating a constant function h(t) one arrives to:

$$0 = \langle \gamma^{(1)}(t) | \gamma^{(1)}(t) \rangle^{(1)} = 2 \langle \gamma^{(1)}(t) | \gamma^{(2)}(t) \rangle, \qquad (28)$$

which in turn results in $\gamma^{(1)}$ and $\gamma^{(2)}$ being mutually orthogonal. Taking the derivative of (28) yields:

$$\langle \gamma^{(1)}(t) | \gamma^{(3)}(t) \rangle = -\langle \gamma^{(2)}(t) | \gamma^{(2)}(t) \rangle = -\kappa^2(t),$$
 (29)

where $\kappa(t)$ is the curvature of γ at t. Combining $\|\gamma^{(1)}(t)\| = 1$, (26) (evaluated at $t = t_{i+1}$), (28), (29) we obtain $\|\gamma(t_{i+1}) - \gamma(t_i)\|^2 / (t_{i+1} - t_i)^2$

$$= \|\sum_{k=1}^{3} \frac{\gamma^{(k)}(t_i)}{k!} (t_{i+1} - t_i)^{k-1} + O((t_{i+1} - t_i)^3)\|^2$$

¹ Derivatives over \hat{t} are denoted by apostrophes, whereas calculated over *t* use superscript notation.

$$= \left\langle \sum_{k=1}^{3} \frac{\gamma^{(k)}(t_{i})}{k!} (t_{i+1} - t_{i})^{k-1} + O((t_{i+1} - t_{i})^{3}) \right|$$

$$= \frac{1}{k} \frac{\gamma^{(k)}(t_{i})}{k!} (t_{i+1} - t_{i})^{k-1} + O((t_{i+1} - t_{i})^{3}) \right\rangle$$

$$= 1 + \frac{(t_{i+1} - t_{i})^{2}}{4} \kappa^{2}(t_{i}) - \frac{(t_{i+1} - t_{i})^{2}}{3} \kappa^{2}(t_{i})$$

$$+ O((t_{i+1} - t_{i})^{3})$$

$$= 1 - \frac{(t_{i+1} - t_{i})^{2}}{12} \kappa^{2}(t_{i}) + O((t_{i+1} - t_{i})^{3}). \quad (30)$$

Consequently, coupling (27) with (30) leads to:

$$\psi_i[t_i, t_{i+1}] = (t_{i+1} - t_i)^{-1+\lambda} \\ \cdot \left(1 - \frac{(t_{i+1} - t_i)^2}{12} \kappa^2(t_i) + O\left((t_{i+1} - t_i)^3\right)\right)^{\frac{\lambda}{2}}.$$

By Taylor's expansion:

$$(1+x)^{\frac{\lambda}{2}} = 1 + \frac{\lambda x}{2} + \frac{\lambda(\lambda-2)}{4\sqrt{(1+\xi)^{4-\lambda}}}x^2,$$

for $|\xi| \leq |x|$, which satisfies $1 + \frac{\lambda x}{2} + O(x^2)$ (for $x > -1 + \rho$, where $\rho > 0$). The latter used with $x = -((t_{i+1} - t_i)^2/12)\kappa^2(t_i) + O((t_{i+1} - t_i)^3)$ (here $x > -1 + \rho$ holds asymptotically) results in $\psi_i[t_i, t_{i+1}]$

$$= (t_{i+1} - t_i)^{-1+\lambda} \cdot \left(1 - \frac{\lambda(t_{i+1} - t_i)^2}{24} \kappa^2(t_i) + O\left((t_{i+1} - t_i)^3\right)\right) = (t_{i+1} - t_i)^{-1+\lambda} \cdot \left(1 - \frac{\lambda(t_{i+1} - t_i)^2}{24} \kappa^2(t_i)\right) + O\left((t_{i+1} - t_i)^{2+\lambda}\right).$$
(31)

Note that, since $2 + \lambda > 0$ (here $\lambda \in [0, 1)$) and $0 < t_{i+1} - t_i \le \delta_m$ the last expression $O((t_{i+1} - t_i)^{2+\lambda})$ from (31) can also be substituted by $O(\delta_m^{2+\lambda})$. Similarly, for $\psi_i[t_{i+1}, t_{i+2}]$

$$= (t_{i+2} - t_{i+1})^{-1+\lambda} \left(1 - \frac{\lambda (t_{i+2} - t_{i+1})^2}{24} \kappa^2(t_{i+1}) \right) + O\left((t_{i+2} - t_{i+1})^{2+\lambda} \right).$$

The latter combined with $k^2(t_{i+1}) = k^2(t_i) + O(t_{i+1} - t_i)$ yields $\psi_i[t_{i+1}, t_{i+2}]$

$$= (t_{i+2} - t_{i+1})^{-1+\lambda}$$

$$\cdot \left[1 - \frac{\lambda (t_{i+2} - t_{i+1})^2}{24} \kappa^2(t_i) + O\left((t_{i+2} - t_{i+1})^2 (t_{i+1} - t_i) \right) \right]$$

$$+ O\left((t_{i+2} - t_{i+1})^{2+\lambda} \right)$$

$$= (t_{i+2} - t_{i+1})^{-1+\lambda} \left(1 - \frac{\lambda (t_{i+2} - t_{i+1})^2}{24} \kappa^2(t_i) \right)$$

$$+O\left((t_{i+2}-t_{i+1})^{1+\lambda}(t_{i+1}-t_{i})\right)+O\left((t_{i+2}-t_{i+1})^{2+\lambda}\right).$$
(32)

Combining (31), (32) and $|(t_{i+j+1} - t_{i+j})/(t_{i+2} - t_i)| < 1$ (for j = 0, 1) renders $\psi_i[t_i, t_{i+1}, t_{i+2}]$

$$= \frac{\psi_{i}[t_{i+1}, t_{i+2}] - \psi_{i}[t_{i}, t_{i+1}]}{t_{i+2} - t_{i}}$$

$$= \frac{(t_{i+2} - t_{i+1})^{-1+\lambda} \left(1 - \frac{\lambda(t_{i+2} - t_{i+1})^{2}}{24} \kappa^{2}(t_{i})\right)}{t_{i+2} - t_{i}}$$

$$- \frac{(t_{i+1} - t_{i})^{-1+\lambda} \left(1 - \frac{\lambda(t_{i+1} - t_{i})^{2}}{24} \kappa^{2}(t_{i})\right)}{t_{i+2} - t_{i}}$$

$$+ O\left((t_{i+2} - t_{i+1})^{1+\lambda}\right) + O\left((t_{i+2} - t_{i+1})^{1+\lambda}\right). \quad (33)$$

Again, since $\lambda + 1 \ge 0$ the last two terms are of order $O(\delta_m^{1+\lambda})$.

The argument applied so-far in *Step 3* does not exploit (5). We invoke now ε -uniformity (5). Indeed, recall that from Ex. 1, ε -uniformity implies more-or-less uniformity. By (11), (33) and $|(t_{i+1+j} - t_{i+j})(t_{i+2} - t_i))^{-1}| \le 1$ (for j = 0, 1) we have $\psi_i[t_i, t_{i+1}, t_{i+2}]$

$$= \frac{(t_{i+2} - t_{i+1})^{-1+\lambda} \left(1 - \frac{\lambda(t_{i+2} - t_{i+1})^2}{24} \kappa^2(t_i)\right)}{t_{i+2} - t_i} \\ - \frac{(t_{i+1} - t_i)^{-1+\lambda} \left(1 - \frac{\lambda(t_{i+1} - t_i)^2}{24} \kappa^2(t_i)\right)}{t_{i+2} - t_i} + O(\delta_m^{1+\lambda})$$

$$= \frac{(t_{i+2} - t_{i+1})^{-1+\lambda} - (t_{i+1} - t_i)^{-1+\lambda}}{t_{i+2} - t_i} + O(\delta_m^{1+\lambda})$$

$$= \frac{\left((t_{i+1} - t_i) + O(\delta_m^{\min\{2, 1+\varepsilon\}})\right)^{-1+\lambda} - (t_{i+1} - t_i)^{-1+\lambda}}{t_{i+2} - t_i} + O(\delta_m^{1+\lambda})$$

$$= \frac{\left((t_{i+1} - t_i) + O(\delta_m^{\min\{2, 1+\varepsilon\}})\right)^{-1+\lambda} - (t_{i+1} - t_i)^{-1+\lambda}}{t_{i+2} - t_i} + O(\delta_m^{1+\lambda}),$$

which by (3) (as any ε -uniform sampling is also more-or-less uniform and thus $t_{i+1} - t_i = O(\delta_m^{-1})$) and by Taylor's expansion of either $(1 + x)^{-1+\lambda}$ $= 1 + (-1 + \lambda)(1 + \xi)^{-2+\lambda}x = 1 + O(x)$ or of $(1+x)^{1+\lambda} = 1 + (1+\lambda)(1+\xi)^{\lambda}x$ (applied at $x_0 = 0$ and for $x = O(\delta_m^{\min\{1,\varepsilon\}})$ separated from -1 for $\varepsilon > 0$, here $|\xi| = O(x)$) yields $\psi_i[t_i, t_{i+1}, t_{i+2}]$

(34)

$$=\frac{(t_{i+1}-t_i)^{-1+\lambda}\left[\left(1+O(\delta_m^{\min\{1,\varepsilon\}})\right)^{-1+\lambda}-1\right]}{t_{i+2}-t_i}$$

$$\begin{split} &-\frac{\lambda \kappa^{2}(t_{i})}{24} \frac{(t_{i+1}-t_{i})^{1+\lambda} \left[\left(1+O(\delta_{m}^{\min\{1,\varepsilon\}})\right)^{1+\lambda}-1 \right]}{t_{i+2}-t_{i}} \\ &+O(\delta_{m}^{1+\lambda}) \\ &= \frac{(t_{i+1}-t_{i})^{-1+\lambda} (\lambda-1)O(\delta_{m}^{\min\{1,\varepsilon\}})}{t_{i+2}-t_{i}} + O(\delta_{m}^{1+\lambda}) \\ &-\frac{\lambda (1+\lambda) \kappa^{2}(t_{i})}{24} \frac{(t_{i+1}-t_{i})^{1+\lambda}O(\delta_{m}^{\min\{1,\varepsilon\}})}{t_{i+2}-t_{i}}) \\ &= (\lambda-1)O(\delta_{m}^{\min\{-1+\lambda,-2+\lambda+\varepsilon\}}) + O(\delta_{m}^{\min\{1+\lambda,\lambda+\varepsilon\}}) \\ &+O(\delta_{m}^{1+\lambda}), \end{split}$$

and thus by the latter, as $-1 + \lambda < 1 + \lambda$, we have $(\psi_i^{(2)}(t)/2) = \psi_i[t_i, t_{i+1}, t_{i+2}]$ $= (\lambda - 1)O(\delta_m^{\min\{-1+\lambda, -2+\lambda+\varepsilon\}}) + O(\delta_m^{\min\{1+\lambda,\lambda+\varepsilon\}})$ $= \begin{cases} O(\delta_m^{\min\{-1+\lambda, -2+\lambda+\varepsilon\}}), & \text{for } \lambda \in [0, 1); \\ O(\delta_m^{\min\{2, 1+\varepsilon\}}), & \text{for } \lambda = 1; \\ O(\delta_m^{1+\lambda}), & \text{for } t_i = \frac{i}{m}, \end{cases}$ (35)

as again $-1 + \lambda < 1 + \lambda$ and $-2 + \lambda + \varepsilon \le \lambda + \varepsilon$. The $O(\delta_m^{1+\lambda})$ asymptotics derived for $\{t_i\}_{i=0}^m$ uniform in (35), comes from the vanishing term $O(\delta_m^{\min\{2,1+\varepsilon\}})$ in (34) (see (11)). Indeed for $t_i = (i/m)$ we have $\delta_m = 1/m$, $\phi = id$ and $O(\delta_m^{1+\varepsilon}) \equiv 0$ in (5) and $t_{i+2} - t_{i+1} = t_{i+1} - t_i = 1/m$. Hence, by (13), we finally obtain for $t \in [t_i, t_{i+2}]$ and for $\lambda \in [0, 1]$ the formula (35).

Remark 2. A simple verification shows that formula (33) within the class of merely more-or-less uniform samplings (3) yields for $t \in [t_i, t_{i+2}]$:

$$\psi_i^{(2)}(t) = O(\delta_m^{-2+\lambda}). \tag{36}$$

The asymptotics (36) is independently shown in [11] for (3) under weaker assumption admitting $\gamma \in C^3([0,1])$ instead of $\gamma \in C^4([0,1])$. Visibly, comparison between (35) and (36) gives, for ε -uniform samplings and $\lambda \in [0,1)$, an acceleration of order min $\{1,\varepsilon\}$ in asymptotics of $O(\psi_i^{(2)}(t))$. In addition, for either $\lambda = 1$ and samplings (3) or $\{t_i\}_{i=0}^m$ uniform, formula (33) yields over I_i :

$$\psi_i^{(2)}(t) = O(\delta_m) \quad \text{or} \quad \psi_i^{(2)}(t) = O(\delta_m^\lambda), \quad (37)$$

respectively. The first result for this special case in (37) is already proved in [11] for $\gamma \in C^3([0,1])$. Similarly, upon comparing (35) with (37) (for $\lambda = 1$) we obtain an extra speed-up of order min{1, ε } in asymptotics of $O(\psi_i^{(2)}(t))$. On the other hand, once *uniform* sampling is admitted, the last formula from (35) yields faster convergence order $O(\delta_m^{1+\lambda})$ than $O(\delta_m^{\lambda})$ from (37) as shown also by [11], for $\gamma \in C^3([0,1])$. \Box

The asymptotics of $O(\psi_i^{(1)}(t))$ for ε -uniform samplings (5) by (13), (31) and (35), over I_i reads with $\psi_i^{(1)}(t)$

$$= (t_{i+2} - t_{i+1})^{-1+\lambda} \left(1 - \frac{\lambda(t_{i+2} - t_{i+1})^2}{24} \kappa^2(t_{i+1}) \right) + O((t_{i+2} - t_{i+1})^{2+\lambda}) + ((t - t_i) + (t - t_{i+1})) \cdot \begin{cases} O(\delta_m^{\min\{-1+\lambda, -2+\lambda+\varepsilon\}}), & \text{for } \lambda \in [0, 1); \\ O(\delta_m^{\min\{2, 1+\varepsilon\}}), & \text{for } \lambda = 1; \\ O(\delta_m^{1+\lambda}), & \text{for } t_i = \frac{i}{m}; \end{cases}$$

$$= \begin{cases} O(\delta_m^{-1+\lambda}), & \text{for } \lambda \in [0,1);\\ 1+O(\delta_m^2), & \text{for } \lambda = 1;\\ \delta_m^{-1+\lambda} + O(\delta_m^{1+\lambda}), & \text{for } t_i = \frac{i}{m}; \end{cases}$$

$$+ \begin{cases} O(\delta_m)O(\delta_m^{\min\{-1+\lambda,-2+\lambda+\varepsilon\}}), & \text{for } \lambda \in [0,1); \\ O(\delta_m)O(\delta_m^{\min\{2,1+\varepsilon\}}), & \text{for } \lambda = 1; \\ O(\delta_m)O(\delta_m^{1+\lambda}), & \text{for } t_i = \frac{i}{m}; \end{cases}$$

$$= \begin{cases} O(\delta_m^{-1+\lambda}) + O(\delta_m^{\min\{\lambda,-1+\lambda+\varepsilon\}}), & \text{for } \lambda \in [0,1); \\ 1 + O(\delta_m^2) + O(\delta_m^{\min\{3,2+\varepsilon\}}), & \text{for } \lambda = 1; \\ \delta_m^{-1+\lambda} + O(\delta_m^{1+\lambda}) + O(\delta_m^{2+\lambda}), & \text{for } t_i = \frac{i}{m}; \end{cases}$$

$$= \begin{cases} O(\delta_m^{-1+\lambda}), & \text{for } \lambda \in [0,1); \\ 1+O(\delta_m^2), & \text{for } \lambda = 1; \\ \delta_m^{-1+\lambda} + O(\delta_m^{1+\lambda}), & \text{for } t_i = \frac{i}{m}; \end{cases}$$

$$= \begin{cases} O(\delta_m^{-1+\lambda}), & \text{for } \lambda \in [0,1);\\ \delta_m^{-1+\lambda} + O(\delta_m^{1+\lambda}), & \text{for } t_i = \frac{i}{m} \text{ or } \lambda = 1. \end{cases}$$
(38)

The condition (19) forcing ψ_i to be a reparameterization for ε -uniform samplings is later exploited to compare both curves γ and $\hat{\gamma}_2$ defined originally over different domains [0,1] and $[0,\hat{T}]$ (with $\hat{T} = \hat{t}_m$ - see (6)), respectively.

Remark 3. Formula (38) reveals that the asymptotics of $O(\psi_i^{(1)}(t))$ for ε -uniform samplings does depend on ε (contrary to $O(\psi_i^{(2)}(t))$ - see (35)). In addition, if more-or-less uniform sampling (3) is combined with (13), (31) and (33), for $t \in [t_i, t_{i+2}]$ and $\lambda \in [0, 1]$, we obtain that $\psi_i^{(1)}(t)$

$$= (t_{i+2} - t_{i+1})^{-1+\lambda} \left(1 - \frac{\lambda (t_{i+2} - t_{i+1})^2}{24} \kappa^2 (t_{i+1}) \right) + O\left((t_{i+2} - t_{i+1})^{2+\lambda} \right) + ((t - t_i) + (t - t_{i+1}))$$

$$\cdot \left(\frac{(t_{i+2} - t_{i+1})^{-1+\lambda} \left(1 - \frac{\lambda(t_{i+2} - t_{i+1})^2}{24} \kappa^2(t_i) \right)}{t_{i+2} - t_i} - \frac{(t_{i+1} - t_i)^{-1+\lambda} \left(1 - \frac{\lambda(t_{i+1} - t_i)^2}{24} \kappa^2(t_i) \right)}{t_{i+2} - t_i} + O\left((t_{i+2} - t_{i+1})^{1+\lambda} \right) + O\left((t_{i+2} - t_{i+1})^{1+\lambda} \right) \right)$$

$$= \begin{cases} O(\delta_m^{-1+\lambda}), & \text{for } \lambda \in [0,1); \\ \delta_m^{\lambda-1} + O(\delta_m^{1+\lambda}), & \text{for } t_i = \frac{i}{m} \text{ or } \lambda = 1. \end{cases}$$
(39)

Visibly, both asymptotics established for curves $\gamma \in C^4([0,1])$ in either (38) (sampled along (5)) or in (39) (sampled according to (3)) coincide. In addition, the orders of $O(\psi_i^{(1)}(t))$ derived for $\gamma \in C^3([0,1])$ and samplings (3) in [11] are also the same to those specified in (38). Thus, as compared with [11], for estimating $O(\psi_i^{(1)}(t))$ neither raising the smoothness of γ nor restricting samplings $\{t_i\}_{i=0}^m$ to ε -uniformity improves the examined asymptotics for regular $\gamma \in C^3([0,1])$. \Box

2.4 Step 4: the asymptotic orders of $\hat{\gamma}_{2,i}^{''}(\hat{t})$

We discuss now the asymptotics of $O(\hat{\gamma}_{2,i}'(\hat{t}))$ in terms of δ_m . Similarly to (13), as for each $\hat{t} \in \hat{I}_i = [\hat{t}_i, \hat{t}_{i+2}]$:

$$\begin{split} \hat{\gamma}_{2,i}(\hat{t}) &= \gamma_{2,i}[\hat{t}_i,\hat{t}_{i+1}](\hat{t}-\hat{t}_i) + \hat{\gamma}_{2,i}[\hat{t}_i,\hat{t}_{i+1},\hat{t}_{i+2}](\hat{t}-\hat{t}_i)(\hat{t}-\hat{t}_{i+1}) \\ \text{we} \quad \text{have} \quad \hat{\gamma}_{2,i}'(\hat{t}) &= 2\hat{\gamma}_{2,i}[\hat{t}_i,\hat{t}_{i+1},\hat{t}_{i+2}] \quad \text{and} \quad \text{thus} \\ \hat{\gamma}_{2,i}''(\hat{t}) &= O(\hat{\gamma}_{2,i}[\hat{t}_i,\hat{t}_{i+1},\hat{t}_{i+2}]). \text{ Since} \ \hat{\gamma}_{2,i}(\hat{t}_{i+j}) &= \gamma(t_{i+j}) \ \text{(for} \\ j &= 0, 1, 2), \text{ by} \ (6) \text{ we obtain the following:} \end{split}$$

$$\hat{\gamma}_{2,i}[\hat{t}_i, \hat{t}_{i+1}] = \frac{\gamma(t_{i+1}) - \gamma(t_i)}{\|\gamma(t_{i+1}) - \gamma(t_i)\|^{\lambda}} = \frac{\gamma(t_{i+1}) - \gamma(t_i)}{(\|\gamma(t_{i+1}) - \gamma(t_i)\|^2)^{\frac{\lambda}{2}}}$$

The latter with (26), (30) and Taylor's expansion gives for $\hat{\gamma}_{2,i}[\hat{t}_i, \hat{t}_{i+1}] =$

$$\frac{(t_{i+1}-t_i)^{1-\lambda} \left(\sum_{k=1}^3 \frac{\gamma^{(k)}(t_i)}{k!} (t_{i+1}-t_i)^{k-1} + O((t_{i+1}-t_i)^3)\right)}{1 - \frac{\lambda(t_{i+1}-t_i)^2}{24} \kappa^2(t_i) + O((t_{i+1}-t_i)^3)}$$

Again Taylor's expansion about $x_0 = 0$ applied to the function $(1+x)^{-1}$ with $x = -\frac{\lambda(t_{i+1}-t_i)^2}{24} + O\left((t_{i+1}-t_i)^3\right)$ (separated asymptotically from -1) yields:

$$\frac{1 - \frac{\lambda(t_{i+1} - t_i)^2}{24} \kappa^2(t_i) + O((t_{i+1} - t_i)^3)}{1 - \frac{\lambda(t_{i+1} - t_i)^2}{24} \kappa^2(t_i) + O((t_{i+1} - t_i)^3).$$

Consequently, over \hat{I}_i we have that $\hat{\gamma}_{2,i}[\hat{t}_i, \hat{t}_{i+1}]$

1

$$= \left(\sum_{k=1}^{3} \frac{\gamma^{(k)}(t_i)}{k!} (t_{i+1} - t_i)^{k-1} + O\left((t_{i+1} - t_i)^3\right)\right)$$
$$\cdot \frac{\left(1 + \frac{\lambda(t_{i+1} - t_i)^2}{24} \kappa^2(t_i) + O\left((t_{i+1} - t_i)^3\right)\right)}{(t_{i+1} - t_i)^{\lambda - 1}}$$

$$= \left(\sum_{k=1}^{3} \frac{\gamma^{(k)}(t_i)}{k!} (t_{i+1} - t_i)^{k-1}\right) \left(1 + \frac{\lambda(t_{i+1} - t_i)^2}{24} \kappa^2(t_i)\right)$$

$$\cdot (t_{i+1} - t_i)^{1-\lambda} + O\left((t_{i+1} - t_i)^{4-\lambda}\right)$$

$$= (t_{i+1} - t_i)^{1-\lambda} \left(\gamma^{(1)}(t_i) + \frac{t_{i+1} - t_i}{2} \gamma^{(2)}(t_i)\right)$$

$$+ O\left((t_{i+1} - t_i)^{3-\lambda}\right) + O\left((t_{i+1} - t_i)^{4-\lambda}\right).$$

Hence, as $\gamma^{(1)}(t_{i+1}) = \gamma^{(1)}(t_i) + \gamma^{(2)}(t_i)(t_{i+1} - t_i) + O((t_{i+1} - t_i)^2)$ and $\gamma^{(2)}(t_{i+1}) = \gamma^{(2)}(t_i) + O((t_{i+1} - t_i))$ we have:

$$\begin{split} \hat{\gamma}_{2,i}[\hat{t}_{i},\hat{t}_{i+1}] \\ &= (t_{i+1}-t_{i})^{1-\lambda} \left(\gamma^{(1)}(t_{i}) + \frac{t_{i+1}-t_{i}}{2} \gamma^{(2)}(t_{i}) \right) \\ &+ O\left((t_{i+1}-t_{i})^{3-\lambda} \right), \end{split}$$

 $\hat{\gamma}_{2,i}[\hat{t}_{i+1},\hat{t}_{i+2}]$

$$= (t_{i+2} - t_{i+1})^{1-\lambda} \left(\gamma^{(1)}(t_{i+1}) + \frac{t_{i+2} - t_{i+1}}{2} \gamma^{(2)}(t_{i+1}) \right) + O\left((t_{i+2} - t_{i+1})^{3-\lambda} \right), = (t_{i+2} - t_{i+1})^{1-\lambda} \left(\gamma^{(1)}(t_i) + \frac{t_{i+2} + t_{i+1} - 2t_i}{2} \gamma^{(2)}(t_i) \right) + O(\delta_m^{3-\lambda}).$$
(40)

Taking into account that (30) and (31) we arrive at (for j = 0, 1):

$$\left(\|\gamma(t_{i+j+1}) - \gamma(t_{i+j})\|^2 \right)^{\frac{\Lambda}{2}} = \frac{\left(1 - \frac{\lambda(t_{i+j+1} - t_{i+j})^2}{24} \kappa^2(t_{i+j}) + O((t_{i+j+1} - t_{i+j})^3) \right)}{(t_{i+j+1} - t_{i+j})^{-\lambda}}.$$
(41)

So, by (6), (40) and (41) for merely more-or-less uniform samplings (3) (and hence for each ε -uniform samplings) the second divided difference, upon introducing the substitutions:

$$A = \gamma^{(1)}(t_i) + \frac{t_{i+2} + t_{i+1} - 2t_i}{2} \gamma^{(2)}(t_i),$$

$$B = \gamma^{(1)}(t_i) + \frac{t_{i+1} - t_i}{2} \gamma^{(2)}(t_i),$$

the second divided difference $\|\hat{\gamma}_{2,i}[\hat{t}_i, \hat{t}_{i+1}, \hat{t}_{i+2}]\|$ amounts to:

$$= \frac{\|\hat{\gamma}_{2,i}[\hat{i}_{i+1},\hat{i}_{i+2}] - \hat{\gamma}_{2,i}[\hat{i}_{i},\hat{i}_{i+1}]\|}{(\hat{i}_{i+2} - \hat{i}_{i+1}) + (\hat{i}_{i+1} - \hat{t}_{i})}$$

$$\leq \frac{\|(t_{i+2} - t_{i+1})^{1-\lambda} \cdot A + O(\delta_{m}^{3-\lambda})\|}{\|\gamma(t_{i+1}) - \gamma(t_{i})\|^{\lambda} + \|\gamma(t_{i+2}) - \gamma(t_{i+1})\|^{\lambda}}$$

$$+ \frac{\|(t_{i+1} - t_{i})^{1-\lambda} \cdot B + O\left((t_{i+1} - t_{i})^{3-\lambda}\right)\|}{\|\gamma(t_{i+1}) - \gamma(t_{i})\|^{\lambda} + \|\gamma(t_{i+2}) - \gamma(t_{i+1})\|^{\lambda}}$$

$$\leq \frac{\|(t_{i+2} - t_{i+1})^{1-\lambda} \cdot A + O(\delta_m^{3-\lambda})\|}{(\|\gamma(t_{i+2}) - \gamma(t_{i+1})\|^2)^{\frac{\lambda}{2}}} + \frac{\|(t_{i+1} - t_i)^{1-\lambda} \cdot B + O\left((t_{i+1} - t_i)^{3-\lambda}\right)\|}{(\|\gamma(t_{i+1}) - \gamma(t_i)\|^2)^{\frac{\lambda}{2}}} = \frac{\|(t_{i+2} - t_{i+1})^{1-2\lambda} \cdot A + O(\delta_m^{3-2\lambda})\|}{1 - \frac{\lambda(t_{i+2} - t_{i+1})^2}{24}} \kappa^2(t_{i+1}) + O(\delta_m^3) + \frac{\|(t_{i+1} - t_i)^{1-2\lambda} \cdot B + O\left((t_{i+1} - t_i)^{3-2\lambda}\right)\|}{1 - \frac{\lambda(t_{i+1} - t_i)^2}{24}} \kappa^2(t_i) + O(\delta_m^3).$$
(42)

Taylor's expansion applied to $(1+x)^{-1}$ about $x_0 = 0$ yields (for j = 0, 1):

$$\left(1 - \frac{\lambda(t_{i+j+1} - t_{i+j})^2}{24}\kappa^2(t_{i+j}) + O(\delta_m^3)\right)^{-1}$$

= $1 + \frac{\lambda(t_{i+j+1} - t_{i+j})^2}{24}\kappa^2(t_{i+j}) + O(\delta_m^3),$

and hence by (42):

$$\hat{\gamma}_{2,i}[\hat{t}_{i},\hat{t}_{i+1},t_{i+2}] = O(\delta_m^{1-2\lambda}) + O(\delta_m^{2-2\lambda}) = O(\delta_m^{1-2\lambda}).$$
(43)

In the special case when $\{t_i\}_{i=0}^m$ is *uniform*, the formulas (40) and (41) (with $t_{i+1} - t_i = t_{i+2} - t_{i+1} = \delta_m = (1/m)$) give:

$$\begin{split} \hat{\gamma}_{2,i}[\hat{t}_{i},\hat{t}_{i+1},\hat{t}_{i+2}] \\ &= \frac{\delta_{m}^{1-\lambda} \left(\frac{3\delta_{m}}{2} \gamma^{(2)}(t_{i}) - \frac{\delta_{m}}{2} \gamma^{(2)}(t_{i})\right) + O(\delta_{m}^{3-\lambda})}{\delta_{m}^{\lambda}(1 + O(\delta_{m}^{2}))} \\ &= \frac{\delta_{m}^{2-2\lambda} \gamma^{(2)}(t_{i}) + O(\delta_{m}^{3-2\lambda})}{1 + O(\delta_{m}^{2})} \\ &= O(\delta_{m}^{2-2\lambda}). \end{split}$$
(44)

Such accelerated convergence order for uniform samplings (as compared with (43)) can also be found in [11] for curves $\gamma \in C^3([0,1])$.

Finally, for another special case i.e. $\lambda = 1$ and samplings merely admissible (1), by (40), (41), $|(t_{i+j+1} - t_{i+j})/(t_{i+2} - t_i)| \leq 1$ (with j = 0, 1) and $\gamma^{(1)}(t_{i+1}) = \gamma^{(1)}(t_i) + O(t_{i+1} - t_i)$, upon substituting (for k = 0, 1):

$$C(k) = (t_{i+k+1} - t_{i+k})(1 + O((t_{i+k+1} - t_{i+k})^2))$$

the divided differences $\hat{\gamma}_{2,i}[\hat{t}_i, \hat{t}_{i+1}, \hat{t}_{i+2}]$

$$=\frac{\gamma^{(1)}(t_{i+1}) + \frac{t_{i+2} - t_{i+1}}{2}\gamma^{(2)}(t_{i+1}) - \gamma^{(1)}(t_i) - \frac{t_{i+1} - t_i}{2}\gamma^{(2)}(t_i)}{C(1) + C(0)} \\ +\frac{O\left((t_{i+2} - t_{i+1})^2\right) + O\left((t_{i+1} - t_i)^2\right)}{C(1) + C(0)} \\ = \frac{O(t_{i+1} - t_i) + O(t_{i+2} - t_{i+1})}{(t_{i+2} - t_i) + O\left((t_{i+2} - t_{i+1})^3\right) + O\left((t_{i+1} - t_i)^3\right)}$$

we arrive at
$$\|\gamma(t_{i+2}) - \gamma(t_{i+1})\|^{\lambda}$$

$$+\frac{O\left((t_{i+1}-t_i)^2\right)+O\left((t_{i+2}-t_{i+1})^2\right)}{(t_{i+2}-t_i)+O\left((t_{i+2}-t_{i+1})^3\right)+O\left((t_{i+1}-t_i)^3\right)}$$

= $\frac{O(1)+O(t_{i+1}-t_i)+O(t_{i+2}-t_{i+1})}{1+O\left((t_{i+2}-t_{i+1})^2\right)+O\left((t_{i+1}-t_i)^2\right)}$
= $O(1).$ (45)

Here we use Taylor's expansion with $x_0 = 0$ applied to $(1+x)^{-1}$ at $x = O((t_{i+1}-t_i)^2) + O((t_{i+2}-t_{i+1})^2)$. Note that (45) coincides with (44) once $\lambda = 1$. Thus a single formula (44) covers both $\lambda = 1$ or uniform samplings. This result is the same as before in [11] for curves merely $\gamma \in C^3([0,1])$. Hence collating (43), (44) and (45) for $\hat{t} \in [\hat{t}_i, \hat{t}_{i+2}]$ (with each unique $t = \psi_i^{-1}(\hat{t}) \in [t_i, t_{i+2}]$ since ψ_i is a reparameterization as shown in *Step 1*) the following holds:

$$\gamma_{2,i}^{\prime\prime}(\hat{t}) = \begin{cases} O(\delta_m^{1-2\lambda}), & \text{for } \lambda \in [0,1);\\ O(\delta_m^{2-2\lambda}), & \text{for } t_i = \frac{i}{m} \text{ or } \lambda = 1. \end{cases}$$
(46)

We exploit now (5) of $\{t_i\}_{i=0}^m$. An extra acceleration is achievable for the asymptotics of $O(\gamma_{2,i}')$ once both formulas (40) and (41) derived for $\gamma \in C^4([0,1])$ are considered with more care.

Remark 4. The analysis so-far indicates that an increase of smoothness in γ from $C^3([0,1])$ to $C^4([0,1])$ does not contribute on its own (as compared with [11]) to faster orders for $O(\gamma_{2,i}^{\prime\prime(2)})$ than for more-or-less uniform samplings. Indeed a trajectory estimation for samplings (3) and regular curves $\gamma \in C^4([0,1])$ by (25), (36), (37), (39) and (46) reads as f(t)

$$= O(\delta_m^3)$$

$$\cdot \begin{cases}
O(\delta_m^{1-2\lambda})O(\delta_m^{-1+\lambda})O(\delta_m^{-2+\lambda}), & \lambda \in [0,1); \\
O(\delta_m^{2-2\lambda})(\delta_m^{-1+\lambda} + O(\delta_m^{1+\lambda}))O(\delta_m^{\lambda}), & t_i = \frac{i}{m}; \\
O(\delta_m^{2-2\lambda})(\delta_m^{-1+\lambda} + O(\delta_m^{1+\lambda}))O(\delta_m^{\lambda}), & \lambda = 1; \\
+O(\delta_m^3) \begin{cases}
O(1), & \text{for } \lambda \in [0,1); \\
O(1), & \text{for } t_i = \frac{i}{m} \text{ or } \lambda = 1; \\
O(\delta_m^3) \begin{cases}
O(\delta_m^{-2}) + O(1), & \text{for } \lambda \in [0,1); \\
O(\delta_m) + O(1), & \text{for } t_i = \frac{i}{m} \text{ or } \lambda = 1; \\
\end{cases}
= \begin{cases}
O(\delta_m), & \text{for } \lambda \in [0,1); \\
O(\delta_m^3), & \text{for } t_i = \frac{i}{m} \text{ or } \lambda = 1. \end{cases}$$
(47)

over [0,1]. \Box

We prove now that for ε -uniform samplings the asymptotics in (46), as in (35) (and hence also in (47)) can be accelerated. In fact, to improve the estimate of $\gamma_2''(\hat{t})$ we argue as in (42). Indeed, by (41), ε -uniformity (5), (11) and by Taylor's expansion applied to $(1+x)^{\lambda}$

$$= (t_{i+2} - t_{i+1})^{\lambda} \cdot \left(1 - \frac{\lambda}{24}k^{2}(t_{i+1})(t_{i+2} - t_{i+1})^{2} + O((t_{i+2} - t_{i+1})^{3})\right) = \left((t_{i+1} - t_{i}) + O(\delta_{m}^{\min\{2,1+\varepsilon\}})\right)^{\lambda} \cdot \left(1 - \frac{\lambda}{24}k^{2}(t_{i+1})(t_{i+2} - t_{i+1})^{2} + O((t_{i+2} - t_{i+1})^{3})\right) = (t_{i+1} - t_{i})^{\lambda} \cdot \left(1 + O(\delta_{m}^{\min\{1,\varepsilon\}})\right)^{\lambda} \cdot \left(1 - \frac{\lambda}{24}k^{2}(t_{i+1})(t_{i+2} - t_{i+1})^{2}\right) + O((t_{i+2} - t_{i+1})^{3+\lambda}) = (t_{i+1} - t_{i})^{\lambda} \cdot \left(1 + O(\delta_{m}^{\min\{1,\varepsilon\}})\right) \cdot \left(1 - \frac{\lambda}{24}k^{2}(t_{i+1})(t_{i+2} - t_{i+1})^{2}\right) + O((t_{i+2} - t_{i+1})^{3+\lambda}).$$
(48)

Similarly $\|\gamma(t_{i+1}) - \gamma(t_i)\|^{\lambda}$

 $=(t_{i+1}-t_i)^{\lambda}$

$$\cdot \left(1 - \frac{\lambda}{24}k^2(t_i)(t_{i+1} - t_i)^2\right) + O((t_{i+1} - t_i)^{3+\lambda}).$$
(49)

Coupling formula (48) with (49) leads to $(\|\gamma(t_{i+2}) - \gamma(t_{i+1})\|^{\lambda} + \|\gamma(t_{i+1}) - \gamma(t_i)\|^{\lambda})^{-1}$

$$= \frac{1}{(t_{i+1} - t_i)^{\lambda} (2 + O(\delta_m^{\min\{1, \varepsilon\}}))} = (t_{i+1} - t_i)^{-\lambda} (2 + O(\delta_m^{\min\{1, \varepsilon\}})),$$
(50)

where Taylor's expansion is applied to $(2+x)^{-1}$ at $x = O(\delta_m^{\min\{1,\varepsilon\}})$. Furthermore by (11), (40), (41), (50) combined with (3), $\gamma^{(1)}(t_{i+1}) = \gamma^{(1)}(t_i) + O(\delta_m)$ and Taylor's expansion $(1+x)^{1-\lambda}$ we obtain for the divided difference $\hat{\gamma}_2[\hat{t}_i, \hat{t}_{i+1}, \hat{t}_{i+2}]$

$$= \frac{(t_{i+2} - t_{i+1})^{1-\lambda} \left(\gamma^{(1)}(t_{i+1}) + O(\delta_m)\right)}{\|\gamma(t_{i+1}) - \gamma(t_i)\|^{\lambda} + \|\gamma(t_{i+2}) - \gamma(t_{i+1})\|^{\lambda}} \\ - \frac{(t_{i+1} - t_i)^{1-\lambda} \left(\gamma^{(1)}(t_i) + O(\delta_m)\right)}{\|\gamma(t_{i+1}) - \gamma(t_i)\|^{\lambda} + \|\gamma(t_{i+2}) - \gamma(t_{i+1})\|^{\lambda}} + O(\delta_m^{3-2\lambda}) \\ = \frac{(t_{i+2} - t_{i+1})^{1-\lambda} \left(\gamma^{(1)}(t_i) + O(\delta_m)\right)}{\|\gamma(t_{i+1}) - \gamma(t_i)\|^{\lambda} + \|\gamma(t_{i+2}) - \gamma(t_{i+1})\|^{\lambda}} \\ - \frac{(t_{i+1} - t_i)^{1-\lambda} \left(\gamma^{(1)}(t_i) + O(\delta_m)\right)}{\|\gamma(t_{i+1}) - \gamma(t_i)\|^{\lambda} + \|\gamma(t_{i+2}) - \gamma(t_{i+1})\|^{\lambda}} + O(\delta_m^{3-2\lambda}) \\ = \frac{\left((t_{i+1} - t_i) + O(\delta_m^{\min\{2,1+\varepsilon\}})\right)^{1-\lambda} \gamma^{(1)}(t_i)}{\|\gamma(t_{i+1}) - \gamma(t_i)\|^{\lambda} + \|\gamma(t_{i+2}) - \gamma(t_{i+1})\|^{\lambda}}$$

$$-\frac{\left(t_{i+1}-t_{i}\right)^{1-\lambda}\gamma^{(1)}(t_{i})}{\|\gamma(t_{i+1})-\gamma(t_{i})\|^{\lambda}+\|\gamma(t_{i+2})-\gamma(t_{i+1})\|^{\lambda}}+O(\delta_{m}^{2-2\lambda})$$

$$=\frac{\left(t_{i+1}-t_{i}\right)^{1-\lambda}\left(1+O(\delta^{\min\{1,\varepsilon\}})\right)^{1-\lambda}\gamma^{(1)}(t_{i})}{\|\gamma(t_{i+1})-\gamma(t_{i})\|^{\lambda}+\|\gamma(t_{i+2})-\gamma(t_{i+1})\|^{\lambda}}$$

$$-\frac{\left(t_{i+1}-t_{i}\right)^{1-\lambda}\gamma^{(1)}(t_{i})}{\|\gamma(t_{i+1})-\gamma(t_{i})\|^{\lambda}+\|\gamma(t_{i+2})-\gamma(t_{i+1})\|^{\lambda}}+O(\delta_{m}^{2-2\lambda})$$

$$=\frac{\left(t_{i+1}-t_{i}\right)^{1-\lambda}\left(1+\left(1-\lambda\right)O(\delta_{m}^{\min\{1,\varepsilon\}})\right)\gamma^{(1)}(t_{i})}{\|\gamma(t_{i+1})-\gamma(t_{i})\|^{\lambda}+\|\gamma(t_{i+2})-\gamma(t_{i+1})\|^{\lambda}}+O(\delta_{m}^{2-2\lambda})$$

$$=\frac{\left(1-\lambda\right)O(\delta_{m}^{\min\{2-\lambda,1+\varepsilon-\lambda\}}\right)}{\|\gamma(t_{i+1})-\gamma(t_{i})\|^{\lambda}+\|\gamma(t_{i+2})-\gamma(t_{i+1})\|^{\lambda}}+O(\delta_{m}^{2-2\lambda})$$

$$=\left(1-\lambda\right)O(\delta_{m}^{\min\{2-2\lambda,1+\varepsilon-2\lambda\}})+O(\delta_{m}^{2-2\lambda})$$

$$=O(\delta_{m}^{\min\{2-2\lambda,1+\varepsilon-2\lambda\}}).$$
(51)

Note that if $\lambda = 1$ then (51) yields $\gamma_{2,i}''(\hat{t}) = O(1)$ which coincides with (46). Similarly, if in (51), uniform sampling is used (i.e when term $O(\delta_m^{\min\{2,1+\varepsilon\}})$ in (5) and (11) vanishes), evidently we have $\gamma_{2,i}'(\hat{t}) = O(\delta_m^{2-2\lambda})$ which again is already claimed by (46). In summary, over \hat{I}_i , for $\lambda \in [0,1]$ and ε -uniform samplings the following holds:

$$\hat{\gamma}_{2}^{\prime\prime}(\hat{t}) = \begin{cases} O(\delta_{m}^{\min\{2-2\lambda,1+\varepsilon-2\lambda\}}), & \text{for } \lambda \in [0,1);\\ O(\delta_{m}^{2-2\lambda}), & \text{for } t_{i} = \frac{i}{m} \text{ or } \lambda = 1. \end{cases}$$
(52)

Formula (52) as compared with (46) yields, for all $\lambda \in [0,1)$ an acceleration by either ε for $0 < \varepsilon \le 1$ or by 1 for $\varepsilon \ge 1$. (In addition, the case $\lambda = 1$ relaxes the assumption concerning $\{t_i\}_{i=0}^m$ to form merely admissible samplings (1).)

2.5 *Step 5: asymptotics for trajectory estimation*

We pass now to the final stage of the asymptotic estimate for γ approximation by interpolant $\hat{\gamma}_2$. It is essential to observe that both curves γ and $\hat{\gamma}_2$ are originally defined over different domains i.e. over [0,1] and $[0,\hat{T}]$, respectively. The piecewise-quadratic $\psi : [0,1] \rightarrow [0,\hat{T}]$ (a track-sum of $\psi_i : [t_i, t_{i+2}] \rightarrow [\hat{t}_i, \hat{t}_{i+2}]$) applied here to compare γ and $\hat{\gamma}_2 \circ \psi$, as demonstrated in *Step 1* forms a genuine reparameterization of [0,1] into $[0,\hat{T}]$ for arbitrary ε -uniform samplings (5). The latter may not be the case for the general class of more-or-less uniform samplings (3) (see [11]). Using (25), (35), (38) and (52) with ε -uniformity yields for $\lambda \in [0, 1]$ the following approximation orders in trajectory estimation error over each I_i reading as $f_i(t)$

- 2

$$= O(\delta_m^3)O(1) + \begin{cases} O(\delta_m^3)O(\delta_m^{\min\{2-2\lambda,1+\varepsilon-2\lambda\}}), & \text{for } \lambda \in [0,1); \\ O(\delta_m^3)O(1), & \text{for } \lambda = 1; \\ O(\delta_m^3)O(\delta_m^{2-2\lambda}), & \text{for } t_i = \frac{i}{m}; \end{cases}$$

$$\cdot \begin{cases} O(\delta_m^{-1+\lambda})O(\delta_m^{\min\{-1+\lambda,-2+\lambda+\varepsilon\}}), & \text{for } \lambda \in [0,1); \\ (1+O(\delta_m^2))O(\delta_m^{\min\{2,1+\varepsilon\}}), & \text{for } \lambda = 1; \\ (\delta_m^{-1+\lambda}+O(\delta_m^{1+\lambda}))O(\delta_m^{1+\lambda}), & \text{for } t_i = \frac{i}{m}; \end{cases}$$

$$= O(\delta_m^3) + \begin{cases} O(\delta_m^{\min\{5-2\lambda,4+\varepsilon-2\lambda\}+\min\{-2+2\lambda,-3+2\lambda+\varepsilon\}}), \lambda \in [0,1); \\ O(\delta_m^{\min\{5,4+\varepsilon\}}), & \lambda = 1; \\ O(\delta_m^5), & t_i = \frac{i}{m}. \end{cases}$$

$$(53)$$

We re-emphasized here that for $\lambda = 1$ the constraint on samplings $\{t_i\}_{i=0}^m$ in (53) are the loosest, i.e. only condition (1) is imposed. Upon noting that both inequalities $5 - 2\lambda \le 4 + \varepsilon - 2\lambda$ and $2\lambda - 2 \le 2\lambda + \varepsilon - 3$ hold if and only if $\varepsilon \ge 1$ formula (53) reduces to:

$$f(t) = O(\delta_m^3),$$

$$+ \begin{cases} O(\delta_m^{1+2\varepsilon}), & \text{for } 0 < \varepsilon \le 1 \& \lambda \in [0,1); \\ O(\delta_m^3), & \text{for } \varepsilon > 1 \& \lambda \in [0,1); \\ O(\delta_m^{\min\{5,4+\varepsilon\}}), & \text{for } \lambda = 1; \\ O(\delta_m^5), & \text{for } t_i = \frac{i}{m}; \end{cases}$$

$$= \begin{cases} O(\delta_m^{\min\{3,1+2\varepsilon\}}), & \text{for } \lambda \in [0,1); \\ O(\delta_m^3), & \text{for } t_i = \frac{i}{m} \text{ or } \lambda = 1. \end{cases}$$
(54)

The above asymptotics applies over each sub-interval I_i . As the bounds involved are independent from I_i , the formula (8) holds over [0, 1]. Consequently, the proof of Th. 4 is complete. \Box

Remark 5. For (8) it suffices to take $\{\hat{t}_i\}_{i=0}^m$ instead of the re-normalized $\{\tilde{t}_i\}_{i=0}^m$ (see (6)). The linear mapping $\theta_i : [\hat{t}_i, \hat{t}_{i+2}] \rightarrow [\tilde{t}_i, \tilde{t}_{i+2}]$, where $\tilde{t} = \theta_i(\hat{t}) = \hat{t}/\hat{T}$ satisfies $\theta_i(\hat{t}_{i+j}) = \tilde{t}_{i+j}$, for j = 0, 1, 2. A quadratic $\tilde{\gamma}_{2,i} : [\tilde{t}_i, \tilde{t}_{i+2}] \rightarrow E^n$ which fulfills $\tilde{\gamma}_{2,i}(\tilde{t}_{i+j}) = q_{i+j}$ corresponds to the quadratic $\hat{\gamma}_{2,i} : [\hat{t}_i, \hat{t}_{i+2}] \rightarrow E^n$ satisfying $\hat{\gamma}_{2,i}(\hat{t}_{i+j}) = q_{i+j}$, where $\tilde{\gamma}_{2,i} = \hat{\gamma}_{2,i} \circ \theta_i^{-1}$. Let $\tilde{\psi}_i : [t_i, t_{i+2}] \rightarrow [\tilde{t}_i, \tilde{t}_{i+2}]$ is a quadratic satisfying $\tilde{\psi}_i(t_{i+j}) = \tilde{t}_{i+j}$, for j = 0, 1, 2. By linearity of θ_i and uniqueness of Lagrange interpolant we also have $\tilde{\psi}_i = \theta_i \circ \psi_i$. Hence $f(t) = (\hat{\gamma}_{2,i} \circ \psi_i)(t) - \gamma(t) = (\hat{\gamma}_{2,i} \circ \theta_i^{-1} \circ \theta_i \circ \psi_i)(t) - \gamma(t) = (\hat{\gamma}_{2,i} \circ \tilde{\psi}_i)(t) - \gamma(t)$. Also $\tilde{\psi}_i$ is asymptotically a reparameterization since $\psi_i > 0$, for sufficiently large *m* (see Step 1 in Th. 4). Thus the asymptotics derived in (54) prevails equally for $(\tilde{\gamma}_{2,i} \circ \tilde{\psi}_i)(t) - \gamma(t)$. The shift in $\hat{t} \in [0, \hat{t}_{i+2} - \hat{t}_i]$ used in

Step 1 does not change the asymptotics in (54) as the curve $\hat{\gamma}_{2,i,s}(\hat{t}) = \hat{\gamma}_{2,i}(\hat{t} - \hat{t}_i)$ satisfies $\hat{\gamma}''_{2,i,s}(\hat{t}) = \hat{\gamma}''_{2,i}(\hat{t})$. \Box

Note that for ε -uniform samplings Th. 4 extends Th. 2 (claimed for $\lambda = 0$) to $\lambda \in [0, 1)$. The estimates established in Th. 4 are *sharp* (as shown in Ex. 2). Consequently by Th. 4 any increment within the interval $\lambda \in [0, 1)$ does not bring a further extra convergence acceleration (for ε -uniform samplings) different than 2ε established earlier for $\lambda = 0$ in Th. 2. Moreover, the bigger ε in (5) is, the closer, modulo a diffeomorphism ϕ , the sampling $\{t_i\}_{i=0}^m$ approaches a uniform sampling. Indeed, this is manifested in (54), where cubic convergence order $O(\delta_m^3)$ established for $t_i = i/m$ is attained with $\varepsilon \geq 1$. The case when $\lambda = 1$ (see Th. 3) is also covered by Th. 4.

The next example confirms analytically the sharpness of Th. 4. Recall that sharpness for samplings (3) with $\lambda \in [0,1]$ or for $\lambda = 1$ and samplings (1) is already demonstrated in [11]. We pass now to the case when $\lambda \in [0,1)$ and ε -uniform samplings are admitted.

Example 2. Consider the ε -uniform sampling such that for some knots $\{t_i, t_{i+1}, t_{i+2}\}$ (with $t_0 = 0$):

$$t_{i+1} - t_i = \hat{\delta}_m (1 + \hat{\delta}_m^{\varepsilon}), \qquad t_{i+2} - t_{i+1} = \hat{\delta}_m (1 - \hat{\delta}_m^{\varepsilon}),$$
(55)

where $\hat{\delta}_m = 1/m$. Note that here $\delta_m = \hat{\delta}_m (1 + \hat{\delta}_m^{\varepsilon})$ and $\phi = id$ (see (5)). The curve under consideration (*a straight line*) is defined as $\gamma_l(t) = t\mathbf{v}$, where $\|v\| = 1$ and $t \in [0, 1]$.

a) For sharpness of (8) (with $\varepsilon \in (0,1]$) it suffices to show that, over I_i we have:

$$f_l(t) = (\hat{\gamma}_2 \circ \psi_i)(t) - \gamma_l(t) = \sigma \delta_m^{1+2\varepsilon} + O(\delta_m^{1+2\varepsilon+\kappa}),$$
(56)

for some $\kappa > 0$ and vector $\boldsymbol{\sigma} = (\sigma_1, \sigma_2) \neq \mathbf{0} \in E^2$. Note that the second expression in (56) is a vector in E^2 . Since $\hat{\delta}_m^{\rho} = \delta_m^{\rho}(1 + \hat{\delta}_m^{\varepsilon})^{-\rho}$ by the Binomial Th. $\hat{\delta}_m^{\rho} = \delta_m^{\rho}(1 + O(\hat{\delta}_m^{\varepsilon}))$ and as $\hat{\delta}_m < \delta_m$ we have $\hat{\delta}_m^{\rho} = \delta_m^{\rho}(1 + O(\delta_m^{\varepsilon}))$. Thus to justify (56) it is sufficient to substitute δ_m with $\hat{\delta}_m$. It is also enough to prove (56) for some $\bar{t} \in [t_i, t_{i+2}]$. We set here $\bar{t} = (t_i + t_{i+2})/2$. The proof of Lemma 1 yields:

$$f_{l}(\bar{t}) = (\bar{t} - t_{i})(\bar{t} - t_{i+1})(\bar{t} - t_{i+2})$$

$$\cdot \int_{[0,1]^{3}} f_{l}'''(\eta(\bar{t}))u^{2}u_{1}dudu_{1}du_{2},$$
(57)

for the function $\eta(\bar{t})$ equal to $\eta(\bar{t}) = ((\bar{t}u_2 + (1-u_2)t_{i+2})u_1 + (1-u_1)t_{i+1})u + (1-u)t_i$ and where the third derivative of f_l is taken over $\eta(t)$. Furthermore by the Chain Rule, (13) and $\gamma_l''(t) \equiv \mathbf{0}$ we obtain that:

$$\begin{aligned} &f_{l}'''(\eta(\bar{t})) \\ &= 3\hat{\gamma}_{2,i}''(\psi_{i}(\eta(\bar{t})))\psi_{i}^{(1)}(\eta(\bar{t}))\psi_{i}^{(2)}(\eta(\bar{t})) \\ &= 12\hat{\gamma}_{2,i}[\hat{t}_{i},\hat{t}_{i+1},\hat{t}_{i+2}]\psi_{i}[t_{i},t_{i+1},t_{i+2}] \end{aligned}$$

$$\cdot \left(\psi_i[t_i, t_{i+1}] + (2\eta(\bar{t}) - t_i - t_{i+1})\psi_i[t_i, t_{i+1}, t_{i+2}] \right)$$
(58)

and that by (55) the following holds:

$$(\bar{t} - t_i)(\bar{t} - t_{i+1})(\bar{t} - t_{i+2})$$

$$= (1/8)(t_{i+1} - t_i)^2 ((t_{i+2} - t_i) + (t_{i+1} - t_i))$$

$$= (1/8)\hat{\delta}_m^3 (1 + \hat{\delta}_m^{\varepsilon})^2 (3 - \hat{\delta}_m^{\varepsilon}).$$
(59)

Since $\int_{[0,1]^3} u^2 u_1 du du_1 du_2 = 1/6$ formula (57) combined with (58) and (59) yields $f_l(\bar{t}) =$

$$(3/2)\hat{\delta}_{m}^{2}(1+\hat{\delta}_{m}^{\varepsilon})^{2}(3\hat{\delta}_{m}-\hat{\delta}_{m}^{1+\varepsilon})$$

$$\cdot\hat{\gamma}_{2,i}[\hat{t}_{i},\hat{t}_{i+1},\hat{t}_{i+2}]\psi_{i}[t_{i},t_{i+1},t_{i+2}]$$

$$\cdot((1/6)\psi_{i}[t_{i},t_{i+1}]$$

$$+\int_{[0,1]^{3}}(2\eta(\bar{t})-t_{i}-t_{i+1})\psi_{i}[t_{i},t_{i+1},t_{i+2}]u^{2}u_{1}dudu_{1}du_{2}).$$
(60)

b) We determine now the asymptotics of the first component $f_{l1}(\bar{t})$ of (60) (assume here the decomposition $f_l(\bar{t}) = f_{l1}(\bar{t}) + f_{l2}(\bar{t})$). Combining (6) and (55) with the Binomial Th.:

$$\psi_i[t_i,t_{i+1}]$$

 $\psi_i[t_{i+1},t_{i+2}]$

$$= \hat{\delta}_m^{-1+\lambda} (1 - \hat{\delta}_m^{\varepsilon})^{-1+\lambda}$$

$$= \hat{\delta}_m^{-\lambda+1} \cdot \left(1 - (\lambda - 1)\hat{\delta}_m^{\varepsilon} + \frac{(\lambda - 1)(\lambda - 2)}{2}\hat{\delta}_m^{2\varepsilon} + (\lambda - 1)O(\hat{\delta}_m^{3\varepsilon}) \right)$$

$$= \hat{\delta}_m^{-1+\lambda} - (\lambda - 1)\hat{\delta}_m^{-1+\varepsilon+\lambda} + (\lambda - 1)O(\hat{\delta}_m^{-1+2\varepsilon+\lambda}).$$
(61)

Therefore, by (55) and (61) we have:

$$\begin{split} \psi_i[t_i, t_{i+1}, t_{i+2}] \\ &= \frac{\hat{\delta}_m^{-1+\lambda} (1 - \hat{\delta}_m^{\varepsilon})^{-1+\lambda} - \hat{\delta}_m^{-1+\lambda} (1 + \hat{\delta}_m^{\varepsilon})^{-1+\lambda}}{2\hat{\delta}_m} \\ &= (1 - \lambda)\hat{\delta}_m^{-2+\varepsilon+\lambda} + (1 - \lambda)O(\hat{\delta}_m^{-2+3\varepsilon+\lambda}) \end{split}$$

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$$= \hat{\delta}_m^{-2+\varepsilon+\lambda} \left((1-\lambda) + (1-\lambda)O(\hat{\delta}_m^{2\varepsilon}) \right).$$
 (62)

The divided differences for $\hat{\gamma}_{2,i}$ upon using again the Binomial Th. read as:

$$\begin{aligned}
& \gamma_{2,i}[t_{i},t_{i+1},t_{i+2}] \\
&= \frac{\frac{(t_{i+2}-t_{i+1})\mathbf{v}}{(t_{i+2}-t_{i+1})^{\lambda}} - \frac{(t_{i+1}-t_{i})\mathbf{v}}{(t_{i+1}-t_{i})^{\lambda}}}{\left(\hat{\delta}_{m}(1-\hat{\delta}_{m}^{\varepsilon})\right)^{\lambda} \|\mathbf{v}\|^{\lambda} + \left(\hat{\delta}_{m}(1+\hat{\delta}_{m}^{\varepsilon})\right)^{\lambda} \|\mathbf{v}\|^{\lambda}} \\
&= \frac{(\hat{\delta}_{m}(1-\hat{\delta}_{m}^{\varepsilon}))^{1-\lambda}\mathbf{v} - (\hat{\delta}_{m}(1+\hat{\delta}_{m}^{\varepsilon}))^{1-\lambda}\mathbf{v}}{(\hat{\delta}_{m}(1-\hat{\delta}_{m}^{\varepsilon}))^{\lambda} + (\hat{\delta}_{m}(1+\hat{\delta}_{m}^{\varepsilon}))^{\lambda}} \\
&= \frac{\hat{\delta}_{m}^{1-2\lambda}\left(2(\lambda-1)\hat{\delta}_{m}^{\varepsilon} + (\lambda-1)O(\hat{\delta}_{m}^{3\varepsilon})\right)}{2+\lambda(\lambda-1)O(\hat{\delta}_{m}^{2\varepsilon})}\mathbf{v} \\
&= \hat{\delta}_{m}^{1-2\lambda+\varepsilon}\left((\lambda-1) + (\lambda-1)O(\hat{\delta}_{m}^{2\varepsilon})\right)\mathbf{v} \end{aligned} \tag{63}$$

as $\left(1 + \lambda(\lambda - 1)O(\hat{\delta}_m^{2\varepsilon})\right)^{-1} = 1 + O(\hat{\delta}_m^{2\varepsilon})$. Therefore by (61), (62), (63), the first expression $f_{l1}(\bar{t})$ in (60) satisfies:

$$f_{l1}(\bar{t}) = (1/4)\hat{\delta}_m^3 (1+2\hat{\delta}_m^{\varepsilon} + \hat{\delta}_m^{2\varepsilon})(3-\hat{\delta}_m^{\varepsilon})\hat{\delta}_m^{-1+\lambda} \cdot \left(1+(\lambda-1)\hat{\delta}_m^{\varepsilon} + (\lambda-1)O(\hat{\delta}_m^{2\varepsilon})\right)\hat{\delta}_m^{-2+\varepsilon+\lambda} \cdot \left((1-\lambda) + (1-\lambda)O(\hat{\delta}_m^{2\varepsilon})\right)\hat{\delta}_m^{1-2\lambda+\varepsilon} \cdot \left((\lambda-1) + (\lambda-1)O(\hat{\delta}_m^{2\varepsilon})\right)\mathbf{v} = \frac{-(1-\lambda)^2}{4}\hat{\delta}_m^{1+2\varepsilon} \left(1+O(\hat{\delta}_m^{\varepsilon})\right)\mathbf{v},$$
(64)

which as $\lambda \neq 1$ gives a sharp estimate in (8) for $\varepsilon \in (0,1]$ (up to the asymptotics of the second component $f_{l2}(\bar{t})$ in (60) - see next step).

c) We demonstrate now that the second expression $f_{l2}(\bar{t})$ in (60) has higher convergence order than $\hat{\delta}_m^{1+2\varepsilon}$. For the latter, it suffices to show that the expression $(1/6)\psi_i[t_i,t_{i+1}] = \hat{\delta}_m^{-1+\lambda} + O(\hat{\delta}_m^{-1+\lambda+\varepsilon})$ (see (61)) has slower asymptotics than the expression D

$$= \psi_i[t_i, t_{i+1}, t_{i+2}] \int_{[0,1]^3} (2\eta(\bar{t}) - t_i - t_{i+1}) u^2 u_1 du du_1 du_2.$$
(65)

Indeed for
$$\overline{t} = (t_i + t_{i+1})/2$$
 we have $2\eta(\overline{t}) - t_i - t_{i+1}$

$$= 2\{[(\overline{t}u_2 + (1 - u_2)t_{i+2})u_1 + (1 - u_1)t_{i+1}]u + (1 - u)t_i\}$$

$$-t_i - t_{i+1}$$

$$= 2\{[(\overline{t}u_2 + (1 - u_2)t_{i+2})u_1 + (1 - u_1)t_{i+1}]u\} + (t_i - t_{i+1})$$

$$-2ut_i$$

$$= 2 [(\bar{t}u_2 + (1 - u_2)t_{i+2})uu_1] + 2u(t_{i+1} - t_i) - 2uu_1t_{i+1} + (t_i - t_{i+1})$$

$$= 2\overline{t}uu_{1}u_{2} - 2uu_{1}u_{2}t_{i+2} + 2uu_{1}(t_{i+2} - t_{i+1}) + 2u(t_{i+1} - t_{i})$$

$$+ (t_{i} - t_{i+1})$$

$$= 2uu_{1}u_{2}(\overline{t} - t_{i+2}) + 2uu_{1}(t_{i+2} - t_{i+1}) + 2u(t_{i+1} - t_{i})$$

$$+ (t_{i} - t_{i+1})$$

$$= uu_{1}u_{2}((t_{i} - t_{i+2}) + (t_{i+1} - t_{i+2})) + 2uu_{1}(t_{i+2} - t_{i+1})$$

$$+ 2u(t_{i+1} - t_{i}) + (t_{i} - t_{i+1}).$$

Coupling the latter with (55) yields the integral from (65) equal to:

Combining the above with (62) and (65) leads to:

$$D = \left((1-\lambda)\hat{\delta}_m^{-2+\varepsilon+\lambda} + (1-\lambda)O(\hat{\delta}_m^{-2+3\varepsilon+\lambda}) \right)$$
$$\cdot \hat{\delta}_m \left((1/8) + O(\hat{\delta}_m^{\varepsilon}) \right)$$
$$= \frac{1-\lambda}{8} \hat{\delta}_m^{-1+\lambda+\varepsilon} + (1-\lambda)O(\hat{\delta}_m^{-1+2\varepsilon+\lambda}), \tag{66}$$

which yields faster convergence rate by ε than the term $\psi_i[t_i, t_{i+1}]$ (we assumed here that $\lambda \neq 1$). Thus (64) and (66) prove sharpness of (8) for $\varepsilon \in (0, 1]$.

Note that for $\lambda = 1$ (by (62)) here $f(t) \equiv \mathbf{0}$ since $\psi_i^{(2)}(t) = 0$ (as the quadratic ψ_i is an affine function) and $\gamma_l^{(3)}(t) = \mathbf{0}$). The sharpness of Th. 4 for $\lambda = 1$ is demonstrated in [10] or [11].

A close inspection of the proof of Th. 4 shows that in fact for γ_l and for sampling (55) the cubic component in $\min\{3, 1 + \varepsilon\}$ for $\varepsilon \ge 1$ does not occur and the asymptototic order $1 + 2\varepsilon$ prevails for all $\varepsilon > 0$ (as indeed proved above). Such acceleration is also numerically confirmed in Ex. 3.

In order to prove the sharpness of cubic orders in (8) for $\varepsilon > 1$ (and $\lambda \neq 1$) we consider a cubic curve (71) (see Ex. 3 b)) sampled according to (55). Note that as $\gamma_c^{\prime\prime\prime}(t) =$

 $(0,6) \neq \mathbf{0}$ and as (59) is always a non-vanishing term of order $\hat{\delta}_m^3$ we have e.g. over $I_0 = [t_0, t_2]$ that $f_c(\eta(\bar{t}))$ $= O(\hat{\delta}_m^3) O(\hat{\gamma}_2(\psi_0(\eta(\bar{t})))) O(\psi_0^{(1)}(\eta(\bar{t})) O(\psi_0^{(2)}(\eta(\bar{t})))$

$$-O(\hat{\delta}_m^3) \tag{67}$$

with $\bar{t} = (t_0 + t_2)/2$. It is sufficient to show that the first component in (67) has order $O(\hat{\delta}_m^{1+2\varepsilon})$. Repeating the calculation from above carried out for γ_l (upon recalling $a^3 - b^3 = (a - b)(a^2 + ab + b^2)$ and the Binomial Th.) yields:

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$$\begin{split} \psi_{0}[t_{0},t_{1}] &= \delta_{m}^{-1+\lambda} (1+\delta_{m}^{\varepsilon})^{-1+\lambda} (1+O(\delta_{m}^{4})), \\ \psi_{0}[t_{1},t_{2}] &= \hat{\delta}_{m}^{-1+\lambda} (1-\hat{\delta}_{m}^{\varepsilon})^{-1+\lambda} (1+O(\hat{\delta}_{m}^{4})), \\ \psi_{0}[t_{0},t_{1},t_{2}] &= \hat{\delta}_{m}^{-2+\lambda+\varepsilon} ((\lambda-1)+(\lambda-1)O(\hat{\delta}_{m}^{2\varepsilon})) \\ &\cdot (1+O(\hat{\delta}_{m}^{4})), \\ \hat{\gamma}_{2,0}[\hat{t}_{0},\hat{t}_{1}] &= \hat{\delta}_{m}^{1-\lambda} (1+\hat{\delta}_{m}^{\varepsilon})^{1-\lambda} \mathbf{v}_{1}, \\ \hat{\gamma}_{2,0}[\hat{t}_{1},\hat{t}_{2}] &= \hat{\delta}_{m}^{1-\lambda} (1-\hat{\delta}_{m}^{\varepsilon})^{1-\lambda} \mathbf{v}_{2} \end{split}$$
(68) and

and

 $\hat{\gamma}_{0}$ [\hat{t}_{0} \hat{t}_{1} \hat{t}_{2}]

$$= \frac{\hat{\delta}_{m}^{1-2\lambda+\varepsilon}(2(\lambda-1)+O(\hat{\delta}_{m}^{2\varepsilon}))}{(1+\hat{\delta}_{m}^{\varepsilon})^{\lambda}(1+O(\hat{\delta}_{m}^{4}))+(1-\hat{\delta}_{m}^{\varepsilon})^{\lambda}(1+O(\hat{\delta}_{m}^{4}))}\mathbf{v}$$

$$= \frac{\hat{\delta}_{m}^{1-2\lambda+\varepsilon}((\lambda-1)+(\lambda-1)O(\hat{\delta}_{m}^{2\varepsilon}))}{1+O(\hat{\delta}_{m}^{\min\{4,2\varepsilon\}})}\mathbf{v}$$

$$= \hat{\delta}_{m}^{1-2\lambda+\varepsilon}\left((\lambda-1)+(\lambda-1)O(\hat{\delta}_{m}^{2\varepsilon})\right)$$

$$\cdot \left(1+O(\hat{\delta}_{m}^{\min\{4,2\varepsilon\}})\right)\mathbf{v}, \tag{69}$$

where vectors $\mathbf{v_i} = (1, O(1))$ (for i = 1, 2) and $\mathbf{v} = (1, O(1))$. An analogous analysis as for curve γ_l applied to (68) and (69) renders for the first component in (67) the asymptotics of order $O(\hat{\delta}_m^{1+2\varepsilon})$ (and thus also of order $O(\delta_m^{1+2\varepsilon})$). \Box

3 Experiments

The tests are conducted in *Mathematica* 9.0 (see e.g. [13]) on a 2.4 GHz Intel Core 2 Duo computer with 8 GB RAM. Since $1 = \sum_{i=1}^{m} (t_{i+1} - t_i) \le m\delta_m$ the following holds $m^{-\alpha} = O(\delta_m^{\alpha})$, for $\alpha > 0$. Hence, the verification of the asymptotics expressed in terms of $O(\delta_m^{\alpha})$ can be performed by examining the claim of Th. 4 in terms of $O(1/m^{\alpha})$ asymptotics.

For a parametric regular curve $\gamma : [0,1] \rightarrow E^n$ $\lambda \in [0,1]$ and *m* varying between $m_{min} \leq m \leq m_{max}$ the *i*-th component of the error for γ estimation is defined here according to:

$$E_m^i = \sup_{t \in [t_i, t_{i+2}]} \left\| (\hat{\gamma}_{2,i} \circ \psi_i)(t) - \gamma(t) \right\|$$

$$= \max_{t \in [t_i, t_{i+2}]} \| (\hat{\gamma}_{2,i} \circ \psi_i)(t) - \gamma(t) \|,$$

as $\tilde{E}_m^i(t) = \|(\check{\gamma}_{2,i} \circ \psi_i)(t) - \gamma(t)\| \ge 0$ is continuous over each sub-interval $[t_i, t_{i+2}] \subset [0, 1]$. The maximal value E_m of $\tilde{E}_m(t)$ (the track-sum of $\tilde{E}_m^i(t)$), for each m = 2k (here $k = 1, 2, 3, \dots, m/2$ is found by using Mathematica optimization built-in functions: Maximize or *FindMinimum* (the latter applied to $-\tilde{E}_m(t)$). From the set of *absolute errors* $\{E_m\}_{m=m_{min}}^{m_{max}}$ the numerical estimate $\bar{\alpha}(\lambda)$ of genuine order $\alpha(\lambda)$ is subsequently computed by using a linear regression to the pair of points $(\log(m), -\log(E_m))$ (see also [3]). Since piecewisely $deg(\hat{\gamma}_2) = 2$ the number of interpolation points $\{q_i\}_{i=0}^m$ is odd i.e. m = 2k as indexing runs over $0 \le i \le m$. The Mathematica built-in functions LinearModelFit renders the coefficient $\bar{\alpha}(\lambda)$ from the computed regression line $y(x) = \bar{\alpha}(\lambda)x + b$ based on pairs of points $\{(\log(m), -\log(E_m))\}_{m=m_{min}}^{m_{max}}$. Note that as indicated in [11] the tested regular curves need not be parameterized exclusively by arc-length. Namely, given our interpolation scheme both regular curve γ and its reparameterized version by arc-length $\gamma \circ \theta$ (see also [14]) yields the same asymptotics for trajectory estimation (which in particular applies to Th. 4). Finally, recall that as justified in Th. 4 any ε -uniform sampling renders asymptotically ψ_i as reparameterization of $[t_i, t_{i+2}]$ into $[\hat{t}_i, \hat{t}_{i+2}]$ - recall that by Remark 5 the tests can equally use normalized or unnormalized exponential parameterizations (6).

In the next steps we test experimentally the asymptotics established in Th. 4 together with the sharpness established by Ex. 2. First we verify the latter.

Example 3. a) Consider *a regular straight line* (parameterized by arc-length):

$$\gamma_l(t) = \left(\frac{t}{\sqrt{5}}, \frac{2t}{\sqrt{5}}\right) \subset E^2 \tag{70}$$

for $t \in [0, 1]$, sampled according to (55), where $t_0 = 0$ and $t_m = 1$ - see Fig. 1 for the distribution of $\{\gamma_l(t_i)\}_{i=0}^m$ with $\varepsilon = 0.5$ and m = 12.

Recall that case $\lambda = 1$ is excluded in Ex. 2. The quadratic ψ_i is a genuine reparameterization (see Step 1). The linear regression is applied to $m_{min} = 101 \leq m \leq m_{max} = 121$ and the results for computed $\bar{\alpha}_{\varepsilon}(\lambda) \approx \alpha_{\varepsilon}(\lambda) = \min\{3, 1+2\varepsilon\}$ are presented in Tab. 1. Note that sharpness or nearly sharpness of Th. 4 is confirmed herein for $\varepsilon \in (0,1]$ as proved in Ex. 2. In fact as indicated also in Ex. 2 the sharp result for γ_l and samplings (55) should coincide with $1 + 2\varepsilon$ for all $\varepsilon > 0$. Indeed the latter is supported by the numerical estimates $\bar{\alpha}_{\varepsilon}(\lambda)$ listed in Tab. 2.

b) Consider a cubic curve $\gamma_c : [0,1] \to E^2$ defined as:

$$\gamma_c(t) = (t, t^3) \tag{71}$$

sampled according to (55). Visibly γ_c is a regular curve. The numerical cubic estimates for $\varepsilon \ge 1$ conducted for



Fig. 1: The plot of the straight line γ_l from (70) sampled according to (55), for m = 12 and $\varepsilon = 0.5$.

Table 1: Computed $\bar{\alpha}_{\varepsilon}(\lambda) \approx \alpha_{\varepsilon}(\lambda) = \min\{3, 1+2\varepsilon\}$ for γ_l from (70) sampled along (55) and interpolated by $\hat{\gamma}_2$ with some discrete values $\lambda \in [0, 1)$ and $\varepsilon \in (0, 1]$.

λ	$\varepsilon = 0.1$	$\varepsilon = 0.33$	$\varepsilon = 0.5$	$\varepsilon = 0.7$	$\varepsilon = 0.9$	$\varepsilon = 1.0$
0.00	1.47	1.80	2.10	2.46	2.85	3.04
0.10	1.45	1.80	2.10	2.46	2.85	3.04
0.33	1.42	1.80	2.10	2.46	2.85	3.04
0.50	1.39	1.80	2.10	2.46	2.85	3.04
0.70	1.37	1.79	2.10	2.47	2.85	3.04
0.90	1.36	1.79	2.10	2.47	2.85	3.04
$\alpha_{\varepsilon}(\lambda)$	1.20	1.66	2.00	2.40	2.80	3.00

Table 2: Computed $\bar{\alpha}_{\varepsilon}(\lambda) \approx \alpha_{\varepsilon}(\lambda) = 1 + 2\varepsilon$ for γ_1 from (70) sampled along (55) and interpolated by $\hat{\gamma}_2$ with some discrete values $\lambda \in [0, 1)$ and $\varepsilon \ge 1$.

λ	$\varepsilon = 1.0$	$\varepsilon = 1.5$	$\varepsilon = 1.7$	$\varepsilon = 2.0$	$\varepsilon = 2.5$	$\varepsilon = 2.7$
0.33	3.04	4.04	4.44	5.05	6.04	6.37
0.50	3.04	4.04	4.44	5.05	6.03	6.30
$\alpha_{\varepsilon}(\lambda)$	3.00	4.00	4.40	5.00	6.00	6.40

Table 3: Computed $\bar{\alpha}_{\varepsilon}(\lambda) \approx \alpha_{\varepsilon}(\lambda) = 3$ for γ_c from (71) sampled along (55) and interpolated by $\hat{\gamma}_2$ with some discrete values $\lambda \in [0, 1)$ and $\varepsilon \geq 1$.

λ	$\varepsilon = 1.0$	$\varepsilon = 1.5$	$\varepsilon = 2.0$	$\varepsilon = 3.0$	$\varepsilon = 4.0$	$\varepsilon = 5.0$
0.33	3.04	3.03	3.02	3.03	3.03	3.04
0.50	3.02	3.04	3.03	3.03	3.03	3.04
$\alpha_{\varepsilon}(\lambda)$	3.00	3.00	3.00	3.00	3.00	3.00



Fig. 2: The plot of the helix γ_h from (72) sampled according to (73), for m = 22 and $\varepsilon = 0.5$.

 $100 \le m \le 121$ shown in Tab. 3 confirm the sharpness of Th. 4. \Box

The next example refers to the regular spatial curve in E^3 .

Example 4. We verify now the sharpness of Th. 4 for a quadratic elliptical helix $\gamma_h : [0,1] \to E^3$:

$$\gamma_h(t) = (2\cos(2\pi t), \sin(2\pi t), 4\pi^2 t^2),$$
 (72)

sampled ε -uniformly (5) (with $\phi = id$) according to:

$$t_{i} = \begin{cases} \frac{i}{m}, & \text{if } i \text{ even;} \\\\ \frac{i}{m} + \frac{1}{2m^{1+\varepsilon}}, & \text{if } i = 4k+1; \\\\ \frac{i}{m} - \frac{1}{2m^{1+\varepsilon}}, & \text{if } i = 4k+3. \end{cases}$$
(73)

Fig. 2 illustrates the curve γ_h sampled along (73) for $\varepsilon = 0.5$ and m = 22. Recall again that, by Th. 4 the function ψ_i is a reparameterization. All tests conducted in this example resort to the linear regression applied for $m_{min} = 101 \le m \le m_{max} = 121$. The corresponding computed estimates $\bar{\alpha}_{\varepsilon}(\lambda) \approx \alpha_{\varepsilon}(\lambda) = \min\{3, 1+2\varepsilon\}$ are presented in Tab. 4.

Again all obtained results are consistent with the asymptotics established in Th. 4. The sharpness of (8) is also generically confirmed. \Box

Some combinations of curves $\gamma \in C^4([0,1])$ and ε -uniform samplings (5) may provide an extra acceleration in asymptotics in comparison with those from Th. 4. Such potential situation is shown in the next example.

Example 5. Consider a planar regular convex spiral γ_{sp} : $[0,1] \rightarrow E^2$ defined as:

$$\gamma_{sp}(t) = ((6\pi - 5\pi t)\cos(5\pi t), (6\pi - 5\pi t)\sin(5\pi t))$$
(74)

Table 4: Estimated $\bar{\alpha}_{\varepsilon}(\lambda) \approx \alpha_{\varepsilon}(\lambda) = \min\{3, 1+2\varepsilon\}$ (with $\lambda \in [0,1)$) and $\bar{\alpha}_{\varepsilon}(1) \approx \alpha_{\varepsilon}(1) = 3$ for γ_h from (72) sampled along (73) and interpolated by $\hat{\gamma}_2$ for some discrete values $\lambda \in [0,1]$ and $\varepsilon \in (0,1]$.

1	0 0 1	0.22	0.5	0.7	0.0	a 1.0
λ	$\varepsilon = 0.1$	$\varepsilon = 0.33$	$\varepsilon = 0.5$	$\varepsilon = 0.7$	$\varepsilon = 0.9$	$\varepsilon = 1.0$
0.00	1.26	1.74	2.10	2.54	2.96	3.01
0.10	1.26	1.74	2.09	2.54	2.97	3.01
0.33	1.24	1.72	2.07	2.93	2.93	2.95
0.50	1.23	1.70	2.06	3.01	3.01	3.04
0.70	1.20	1.64	2.94	2.94	2.94	3.19
0.90	1.15	2.89	2.89	2.89	2.89	3.22
$\alpha_{\varepsilon}(\lambda)$	1.20	1.66	2.00	2.40	2.80	3.00
1.00	2.89	2.91	2.92	2.93	2.88	3.21
$\alpha_{\varepsilon}(1)$	3.00	3.00	3.00	3.00	3.00	3.00

Table 5: Estimated $\bar{\alpha}_{\varepsilon}(\lambda) \approx \alpha_{\varepsilon}(\lambda) = \min\{3, 1+2\varepsilon\}$ (with $\lambda \in [0,1)$) and $\bar{\alpha}_{\varepsilon}(1) \approx \alpha_{\varepsilon}(1) = 3$ for γ_{sp} from (74) sampled along (73) and interpolated by $\hat{\gamma}_2$ for some discrete values $\lambda \in [0,1]$ and $\varepsilon \in (0,1]$.

λ	$\varepsilon = 0.1$	$\epsilon = 0.33$	$\varepsilon = 0.5$	$\varepsilon = 0.7$	$\epsilon = 0.9$	$\varepsilon = 1.0$
0.00	1.25	2.07	2.80	2.96	2.97	2.97
0.10	1.26	2.16	2.84	2.96	2.97	2.97
0.33	1.33	2.44	2.91	2.97	2.97	2.98
0.50	1.45	2.67	2.95	3.97	2.97	2.98
0.70	1.87	2.89	2.97	2.97	2.97	2.98
0.90	2.82	2.99	2.99	2.98	2.97	2.98
$\alpha_{\varepsilon}(\lambda)$	1.20	1.66	2.00	2.40	2.80	3.00
1.00	2.99	3.01	2.99	2.98	2.96	2.97
$\alpha_{\epsilon}(1)$	3.00	3.00	3.00	3.00	3.00	3.00



Fig. 3: The plot of the spiral γ_{sp} from (74) sampled according to (73), for m = 22 and $\varepsilon = 0.33$.

sampled in accordance to (73). Fig. 3 illustrates γ_{sp} coupled with (73) for $\varepsilon = 0.33$ and m = 22. The verification for sampling (73) enforcing ψ_i to be a reparameterization (proved earlier to be automatically fulfilled) can be accomplished as in the previous example (see also (19)). For the numerical assessment of $\alpha_{\varepsilon}(\lambda)$, as previously a linear regression is applied to $101 \le m \le 121$. The relevant numerical results are listed in Tab. 5.

Evidently most of the experiments from Tab. 5 indicate faster convergence rates as opposed to those established in Th. 4. \Box

4 Conclusion

In this paper we extend the existing results for trajectory estimation via *piecewise-quadratic interpolation based* on reduced data sampled ε -uniformly. Our analysis

focuses on *the exponential parameterization* (6) which depends on a parameter $\lambda \in [0,1]$. Exponential parameterization is commonly used in computer graphics for curve modeling - see e.g. [4]. The case when $\lambda = 0$ is discussed in [9]. The opposite one with $\lambda = 1$, refers to the cumulative chords and general admissible samplings (1) which is already analyzed e.g. in [3] or [10]. A recent result [11] (established for samplings (3) and curves $\gamma \in C^3([0,T])$) addresses the remaining cases of $\lambda \in (0,1)$ by proving that there is no acceleration in trajectory estimation, and that the respective convergence orders $\alpha(\lambda) = 1$, for all $\lambda \in [0,1)$ have a discontinuity at $\lambda = 1$ with a jump to $\alpha(1) = 3$.

However, a further acceleration can be achieved for ε -uniform samplings (5) and $\lambda = 0$ (see [9]), with sharp orders $\alpha_{\varepsilon}(0) = \min\{3, 1+2\varepsilon\}$ claimed for trajectory estimation (with $\varepsilon > 0$). *The main result* of this paper (i.e. Th. 4 and Ex. 2) extends the latter to all $\lambda \in [0,1)$ combined with ε -uniform samplings. As demonstrated the accelerated convergence orders $\alpha_{\varepsilon}(\lambda) = \min\{3, 1+2\varepsilon\}$ are not dependent on $\lambda \in [0, 1)$ but merely on ε . Again for $\lambda \in [0,1)$ with $0 < \varepsilon < 1$ at $\lambda = 1$ we have a discontinuous jump in convergence order from $\alpha_{\varepsilon}(\lambda) = 1 + 2\varepsilon$ to $\alpha_{\varepsilon}(1) = 3$. Such discontinuity is removed once $\varepsilon \ge 1$ as then cubic orders hold for both $\lambda = 1$ and $\lambda \in [0, 1)$. This paper proves also that a natural candidate for reparameterization of $[t_i, t_{i+2}]$ into $[\hat{t}_i, \hat{t}_{i+2}]$ i.e. a Lagrange quadratic ψ_i satisfying $\psi_i(t_{i+j}) = \hat{t}_{i+j}$ with j = 0, 1 (see (6)) forms a genuine reparameterization for all ε -uniform samplings. On the other hand, the latter does not always hold for arbitrary more-or-less uniform samplings (3) as shown in [11]. It should be mentioned that Th. 4 extends also to the case when $\varepsilon = 0$ (with (8) still sharp), upon imposing extra constraints on samplings (we omit the analysis). The ε -uniformly sampled reduced data Q_m in the context of the asymptotics of length estimation for an arbitrary regular curve in E^n has been recently discussed in [15].

A possible extension of this work is to invoke smooth interpolation schemes (see [6]) combined with reduced data exponential parameterization (see [4]). Certain clues may be given in [16], where complete C^2 splines are dealt with for $\lambda = 1$, to obtain the fourth orders of convergence in length estimation. The analysis of C^1 interpolation for reduced data with cumulative chords (i.e. again with $\lambda = 1$) can additionally be found in [3] or [17].

There are also other parameterizations applied predominantly on sparse data (applicable also on dense Q_m) - see e.g. the so-called *blending parameterization* [18] or *monotonicity or convexity preserving ones* [4]. The alternative approach is discussed in [19].

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48